

VERITAS Volume Manager™ 4.0 Intelligent Storage Provisioning

Administrator's Guide

Solaris

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Preface

The *VERITAS Volume Manager™ Intelligent Storage Provisioning Administrator's Guide* provides information on how to use the VERITAS Intelligent Storage Provisioning (ISP) feature of VERITAS Volume Manager (VxVM).

Audience

This guide is intended for system administrators responsible for installing, configuring, and maintaining systems under the control of VxVM.

This guide assumes that the user has a:

- ◆ working knowledge of the Solaris operating system
- ◆ basic understanding of Solaris system administration
- ◆ basic understanding of storage management using VxVM

Scope

The purpose of this guide is to introduce the concepts of ISP, and to describe how ISP enhances the usability of VxVM by making the best use of the available storage, and by preserving the reliability and performance capabilities of application volumes throughout their lifetime. This guide also includes descriptions of the standard sets of storage pool, template and capability definitions that are provided for use with ISP.



Organization

This guide is organized as follows:

- ◆ [Understanding ISP](#)
- ◆ [Creating and Administering Storage Pools](#)
- ◆ [Creating Application Volumes](#)
- ◆ [Administering Application Volumes](#)
- ◆ [Administering Instant Snapshots](#)
- ◆ [Administering Volume Templates and Other Configuration Elements](#)
- ◆ [Creating and Modifying User Templates](#)
- ◆ [Using Capabilities, Templates and Rules](#)
- ◆ [ISP Language Definition](#)
- ◆ [ISP Configuration Elements](#)
- ◆ [Volume Group Definition Syntax](#)
- ◆ [Command Summary](#)
- ◆ [Command Examples](#)
- ◆ [Configuring ISP to Work with SAL](#)

Using This Guide

This guide contains instructions for performing ISP administration tasks from the command line. Details on how to use the VERITAS Enterprise Administrator to administer ISP can be found in the *VERITAS Volume Manager User's Guide — VEA*. Detailed descriptions of other VxVM commands and utilities, their options, and details on their use are located in the *VERITAS Volume Manager Administrator's Guide* and in the VxVM manual pages.

Note Most VxVM commands require superuser or other appropriate privileges.

Related Documents

The following documents provide information related to VxVM:

- ◆ *Cross-platform Data Sharing for VERITAS Volume Manager Administrator's Guide*
- ◆ *VERITAS FlashSnap Point-In-Time Copy Solutions Administrator's Guide*
- ◆ *VERITAS Volume Manager Administrator's Guide*
- ◆ *VERITAS Volume Manager Hardware Notes*
- ◆ *VERITAS Volume Manager Installation Guide*
- ◆ *VERITAS Volume Manager Release Notes*
- ◆ *VERITAS Volume Manager Troubleshooting Guide*
- ◆ *VERITAS Volume Manager User's Guide — VEA*
- ◆ VERITAS Volume Manager manual pages



Conventions

The following table describes the typographic conventions used in this guide.

Typeface	Usage	Examples
monospace	Computer output, file contents, files, directories, software elements such as command options, function names, and parameters	Read tunables from the <code>/etc/vx/tunefstab</code> file. See the <code>ls(1)</code> manual page for more information.
<i>italic</i>	New terms, book titles, emphasis, variables to be replaced by a name or value	See the <i>User's Guide</i> for details. The variable <i>ncsize</i> determines the value of...
monospace (bold)	User input; the “#” symbol indicates a command prompt	# mount -F vxfs /h/filesys
<i>monospace (bold and italic)</i>	Variables to be replaced by a name or value in user input	# mount -F fstype mount_point

Symbol	Usage	Examples
%	C shell prompt	
\$	Bourne/Korn/Bash shell prompt	
#	Superuser prompt (all shells)	
\	Continued input on the following line	# mount -F vxfs \ /h/filesys
[]	In a command synopsis, brackets indicates an optional argument	<code>ls [-a]</code>
	In a command synopsis, a vertical bar separates mutually exclusive arguments	<code>mount [suid nosuid]</code>



Getting Help

If you have any comments or problems with VERITAS products, contact VERITAS Technical Support:

- ◆ U.S. and Canadian Customers: 1-800-342-0652
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- ◆ Email: support@veritas.com

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- ◆ Email: license@veritas.com
- ◆ Fax: 1-650-527-0952

For software updates:

- ◆ Email: swupdate@veritas.com

For information on purchasing VERITAS products:

- ◆ Phone: 1-800-327-2232
- ◆ Email: sales.mail@veritas.com

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For additional information about VERITAS and VERITAS products, visit the Web site at:

- ◆ <http://www.veritas.com>

Unique Message Number

If you encounter a product error message, record the unique message number preceding the text of the message. When contacting VERITAS Technical Support, either by telephone or by visiting the VERITAS Technical Support website, be sure to provide the relevant message number. VERITAS Technical Support will use this message number to quickly determine if there are TechNotes or other information available for you.

A unique message number is an alpha-numeric string beginning with the letter “V”. For example, in the message number:

V-5-732-8018 At least one disk must be specified

the “V” indicates that this is a VERITAS product error message. The text of the error message follows the unique message number.



Using VRTSexplorer

The VRTSexplorer program can help VERITAS Technical Support engineers diagnose the cause of technical problems associated with VERITAS products. You can download this program from the VERITAS FTP site or install it from the VERITAS Installation CD. For more information, consult the *VERITAS Volume Manager Release Notes* and the README file in the support directory on the VERITAS Installation CD.



Understanding ISP

1

VERITAS Intelligent Storage Provisioning (ISP) allows you to organize and manage your physical storage by creating virtual storage devices, *application volumes*. You can use application volumes in the same way as traditional volumes in VERITAS Volume Manager (VxVM).

ISP creates volumes from available storage with the required capabilities that you specify. To achieve this, it selects storage by consulting the externally defined rule base for creating volumes, and compares this with the properties of the storage that is available.

ISP provides the following main functionality:

- ◆ Creation and removal of application volumes.
- ◆ Organizing storage by grouping into storage pools.
- ◆ Resizing a volume while it is online.
- ◆ Moving or evacuating subdisks of a volume.
- ◆ Adding mirrors and columns to a volume while it is online.
- ◆ Removing mirrors and columns from a volume while it is online.
- ◆ Relocating a subdisk of a volume while it is online.
- ◆ Changing the capabilities of a volume while it is online.
- ◆ Creating volume snapshots using software or hardware.
- ◆ Reallocation of storage to preserve the capabilities of a volume.

ISP is capable of understanding Storage Area Network (SAN) topology and of efficiently using the available intelligent storage. ISP interacts with other VERITAS components, where these are available, such as the VERITAS Array Integration Layer (VAIL) and the SAN Access Layer (SAL), to take appropriate actions when configuring intelligent storage in a SAN environment.

See “[Configuring ISP to Work with SAL](#)” on page 179 for details of how to set up ISP so that it can use information that is provided by SAL.

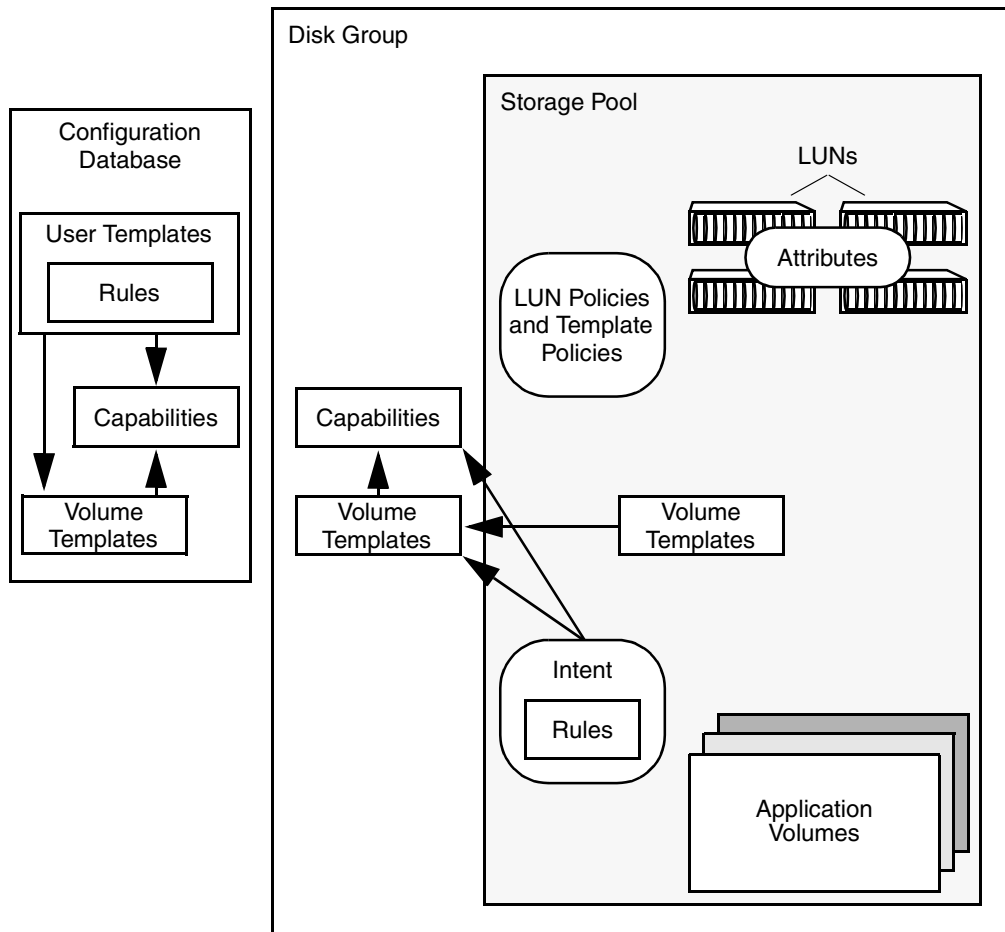


This book describes the command-line interface to ISP, and the language that is used for writing new rules, capabilities and templates. For a description of the graphical interface to ISP that is provided by the VERITAS Enterprise Administrator (VEA), see the *VERITAS Volume Manager User's Guide — VEA*.

ISP Concepts

The figure, “[Relationship Between Concepts in ISP](#),” illustrates the dependencies between the various ISP components.

Relationship Between Concepts in ISP



These concepts are defined in the following sections.

Disk Group

A disk group is a named collection of disks that share a common configuration. Volumes and other VxVM objects must be created within a disk group, and are restricted to using disks from within that disk group.

LUN

A LUN, or *logical unit*, can either correspond to a single physical disk, or to a collection of disks that are exported as a single logical entity, or virtual disk, by a device driver or by an intelligent disk array's hardware. VxVM and other VERITAS software modules may be capable of automatically discovering the special characteristics of LUNs, or you can use the Annotation Service to define new storage attributes.

Attribute

A storage attribute allows the properties of a LUN to be defined in an arbitrary conceptual space. For example, attributes can describe properties such as:

- ◆ Disk access name
- ◆ Disk media name
- ◆ Manufacturer
- ◆ Model type
- ◆ Physical location, such as rack number, frame number, floor, building, or site
- ◆ Hardware RAID configuration
- ◆ Failover properties
- ◆ Performance properties

Note You can use the *annotation service*, provided in the VEA graphical user interface, to create and delete storage attributes.

Attributes may be used to capture information about special features that storage possesses, such as:

- ◆ Hardware-supported cloning, such as EMC Business Continuity Volumes (BCV)
- ◆ Hardware-supported replication, such as the EMC Symmetrix Remote Data Facility (SRDF)
- ◆ Hardware redundancy, such as mirrored parity, and caching



It should only be necessary to enter such information manually if VxVM cannot discover it automatically. An example of a user-defined attribute is physical location.

Note Attribute names and their string values are case sensitive. You can use the `vxvoladm listattrs` command to discover the correct spelling of LUN attribute names.

Storage Pool

A storage pool is defined within a disk group in VxVM for use by ISP. A storage pool is a policy-based container for LUNs and volumes. This means that the templates, capabilities and policies that are associated with a storage pool define how storage is organized within the pool.

For convenience, storage pool definitions are provided that include a number of associated templates that can be used for different purposes. See “[Storage Pools](#)” on page 158 for details of the storage pool definitions that are provided.

Two types of storage pool are defined: *data pools* and *clone pools*. These are described in the following sections.

Data Pool

The first storage pool that is created within a disk group. All other storage pools that are subsequently created within a disk group are clone pools.

Note Only one data pool can be created within a disk group.

It should not usually be necessary to move a data pool to another disk group. However, if this is required, only an entire data pool can be moved. An individual application volume within a data pool cannot be moved. If you want to move a data pool into a different disk group, you must ensure that the data pool contains only those objects that you require.

Clone Pool

A storage pool that contains one or more full-sized instant volume snapshot replicas of volumes within a data pool. (A volume snapshot is an image of a volume’s contents at the moment in time that the snapshot was taken. See the *VERITAS Volume Manager Administrator’s Guide* for more information about volume snapshots.)

Note Only full-sized and space-optimized instant snapshots are supported for use with ISP. Third-mirror break-off volume snapshots are not supported.

A clone pool can be moved into another disk group, but an individual snapshot within it cannot. If you want to move a clone pool into a different disk group, you must ensure that the clone pool contains only those snapshots that you require.

Storage Pool Set

A storage pool set is a bundled definition of the capabilities of a data pool and its clone pools. For convenience, you can use a storage pool set definition to define both pools in a single operation. See “[Storage Pool Sets](#)” on page 162 for details of the storage pool sets that are provided.

Policy

A storage pool’s policies define how it behaves when more storage is required, and when you try to create volumes whose capabilities are not permitted by the current templates. The two policies that are associated with a storage pool are:

AutoGrow	Defines how a storage pool uses LUNs. This policy can take the following <i>level</i> values:						
	<table> <tbody> <tr> <td>pool</td> <td>Use storage that has been manually assigned to the storage pool.</td> </tr> <tr> <td>diskgroup</td> <td>Use storage that has been assigned to the disk group.</td> </tr> </tbody> </table>	pool	Use storage that has been manually assigned to the storage pool.	diskgroup	Use storage that has been assigned to the disk group.		
pool	Use storage that has been manually assigned to the storage pool.						
diskgroup	Use storage that has been assigned to the disk group.						
SelfSufficient	Defines how a storage pool uses templates. This policy can take the following <i>level</i> values:						
	<table> <tbody> <tr> <td>pool</td> <td>Use templates that have been manually assigned to the storage pool.</td> </tr> <tr> <td>diskgroup</td> <td>Use templates that have been manually assigned to the disk group.</td> </tr> <tr> <td>host</td> <td>Use templates that have been installed in the ISP repository on this host.</td> </tr> </tbody> </table>	pool	Use templates that have been manually assigned to the storage pool.	diskgroup	Use templates that have been manually assigned to the disk group.	host	Use templates that have been installed in the ISP repository on this host.
pool	Use templates that have been manually assigned to the storage pool.						
diskgroup	Use templates that have been manually assigned to the disk group.						
host	Use templates that have been installed in the ISP repository on this host.						

The values of these two policies can be combined to suit how the storage pool is to be used.

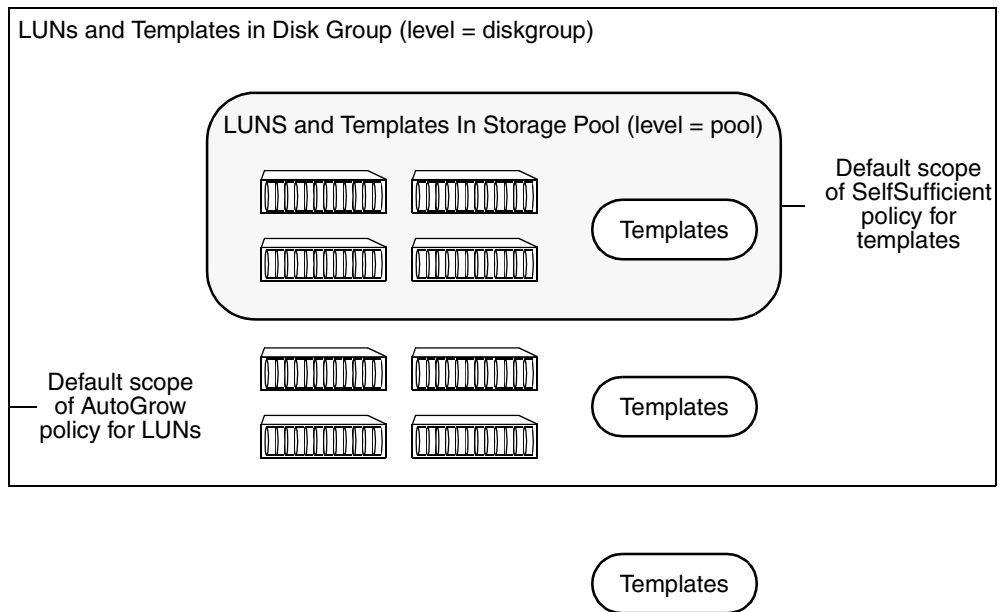


The policy levels that are associated with a storage pool control how it manages its templates and LUNs:

- ◆ The default level of the `AutoGrow` policy is `diskgroup`. This allows LUNs that are associated with the storage pool and its disk group to be used for allocating storage to volumes.
- ◆ The default level of the `SelfSufficient` policy is `pool`. This allows only templates that are associated with the storage pool to be used for allocating storage to volumes. The storage pool can contain only volumes with the reliability and performance capabilities that are supported by these templates.

The scope of the levels that can be configured as policy values for a storage pool is illustrated in “[Scope Levels for Storage Pool Policies](#).”

Scope Levels for Storage Pool Policies



All Available Templates (level = host)

Note LUNs in other storage pools or disk groups or outside any disk group are not immediately available for aggregating into another storage pool or disk group.

Capability

A capability is a feature that is provided by a volume. For example, a volume may exhibit capabilities such as performance and reliability to various degrees. Each type of capability is defined as a set of rules.

The following table shows some simple examples of capabilities that might be supported by a storage pool:

Capability	Adjustable Parameters	Description
DataMirroring	<code>nmirs</code> — number of mirrors (plexes)	Provides reliability by using mirrored plexes.
Raid5Capability	<code>ncols</code> — minimum number of columns <code>nmaxcols</code> — maximum number of columns	Provides reliability by using RAID-5 parity.
Raid5LogMirroring	<code>nlogs</code> — number of log copies	Provides reliability for RAID-5 logs by mirroring.
Striping	<code>ncols</code> — minimum number of columns <code>nmaxcols</code> — maximum number of columns	Provides performance by striping across columns.

Capabilities have variable parameters that you can specify, such as the number of mirrors or columns. You can adjust the values of these parameters to tune the characteristics of a volume. If you do not specify parameter values, default values are used.

See “[Capabilities](#)” on page 152 for details of the capabilities that are provided.

How capabilities can provide performance and reliability is described in the following sections.

Performance

Performance specifies the capabilities of a volume based on factors such as number of columns in striped volumes, stripe unit size, preferred characteristics of storage such as using prefabricated disks that are configured in hardware.



Reliability

Reliability specifies the level of redundancy that is required from a volume as a capability. Very reliable volumes have a high degree of redundancy. For example, a very reliable volume could be configured as a software mirrored volume built upon underlying prefabricated RAID-5 capable LUNs that are configured in the enclosure hardware. A medium-level redundant volume could be a simple 2-way mirror or RAID-5 volume configured either in software or on a suitable LUN within a single enclosure.

Rule

A rule is a statement written in the VERITAS ISP language that specifies how a volume is to be created. A rule can define selection of storage or layout of storage. Rules are usually gathered together as templates for creating volumes, rather than being specified individually.

Examples of storage selection and storage layout rules are described in the following sections.

Storage Selection Rules

Storage selection rules specify what storage can be used to create volumes. The following are examples of storage selection rules:

Rule	Description
<code>affinity</code>	Attempts to select storage with shared attributes.
<code>confineto</code>	Restricts selection of storage by specifying attributes.
<code>exclude</code>	Prevents storage with certain attributes from being selected.
<code>select</code>	Specifies the storage to be used.
<code>separateby</code>	Defines fault domains for objects such as plexes.
<code>strong separateby</code>	Does not allow objects in different fault domains to share attributes.

For example, the following rule specifies that any LUNs may be selected from the named enclosures:

```
select "Enclosure"="ENC01", "Enclosure"="ENC02"
```

The next rule specifies that LUNs may be selected from the set of Hitachi disks that are located in Room1:

```
confineto "VendorName"="HITACHI", "Room"="Room1"
```

This example of a separation rule specifies that enclosures are to be treated as individual fault domains:

```
separateby "Enclosure"
```

Storage Layout Rules

Storage layout rules specify how storage is used to create volumes. The following are examples of storage layout rules:

Rule	Description
log	Specifies the type of log and its degree of redundancy.
mirror	Specifies how many mirrors a volume should have.
parity	Specifies whether redundancy is provided by using parity.
stripe	Specifies how many columns a volume should have.
striped	Specifies whether a volume is striped.

For example, the following rule specifies that a volume can be created using parity to provide data redundancy:

```
parity true
```

Volume Template

A volume template (or template for short) is a meaningful collection of rules that provide a capability. A template can specify one or more capabilities that a volume created using the template may have, and consists of a collection of storage selection and layout rules. For example, a template may allow you to create a volume that is able to tolerate the failure of a certain number of controllers, or that has a certain number of copies of the volume data.

When creating a volume, it is easier to specify its desired capabilities than to specify the precise layout of the volume on the available storage. ISP selects the appropriate templates and uses them to create a volume with the desired capabilities.



If you specify parameter values for a volume's capabilities, the rules that are defined within the chosen template use these values when selecting and laying out storage. If not specified, the default parameter values for a volume's capabilities are assumed by the template.

The following table shows some simple examples of templates and the capabilities that they might provide:

Template	Provides Capabilities	Adjustable Parameters for the Capability
DataMirroring	DataMirroring	<code>nmirs</code> — number of mirrors (plexes)
Raid5Volume	Raid5Capability, Raid5LogMirroring	<code>ncols</code> — minimum number of columns <code>nlogs</code> — number of log copies <code>nmaxcols</code> — maximum number of columns
Striping	Striping	<code>ncols</code> — minimum number of columns <code>nmaxcols</code> — maximum number of columns

See [“Volume Templates”](#) on page 148 for details of the templates that are provided.

Template Sets

A template set consists of related capabilities and templates that have been collected together for convenience. Associating a template set with a storage pool is equivalent to associating each of its member templates separately with the storage pool. See [“Template Sets”](#) on page 144 for details of the template sets that are provided.

User Template

A user template (or user-defined template) defines an arbitrary collection of capabilities, templates and rules to which you want volumes of a certain type to conform. For example, you might want all volumes that you create to store database tables to share the same reliability and performance capabilities, and also that they only be allocated from a restricted set of storage.

It is useful to create user templates if you regularly create volumes with similar capabilities.

The following table shows some examples of user templates that might be created:

User Template	Description
OracleTable	Provides a reliable high-performance volume that is suitable for use by a database table.
OracleIndex	Provides an extremely high-performance volume that is suitable for a database index.

As for templates, each user template can have a number of adjustable parameters that you can use for tuning the characteristics of the created volumes.

Note A user template is not directly associated with a storage pool. Its association is implied by its reference to capabilities and templates.

Application Volume

An application volume is created by ISP, and then exported for use by an application such as a database or file system. It is identical to a traditional volume that you would create using `vxassist` and other VxVM commands, except that you can only administer it by using the `vxvoladm` command, or via the interface to ISP that is provided by the VEA. Similarly, traditional volumes cannot be administered by using the `vxvoladm` command, or via the VEA interface to ISP.

Note In this book, the term *volume* always means *application volume* unless it is specified that a traditional VxVM volume is meant.

Intent

The intent of a volume is a conceptualization of its purpose as defined by its characteristics and implemented by a template. ISP attempts to preserve the intent of a volume whenever the volume is reconfigured, resized, or relocated. Intent preservation automatically conserves capabilities such as reliability and performance, and observes additional rules such as allocating storage based on confinement and exclusion specifications.



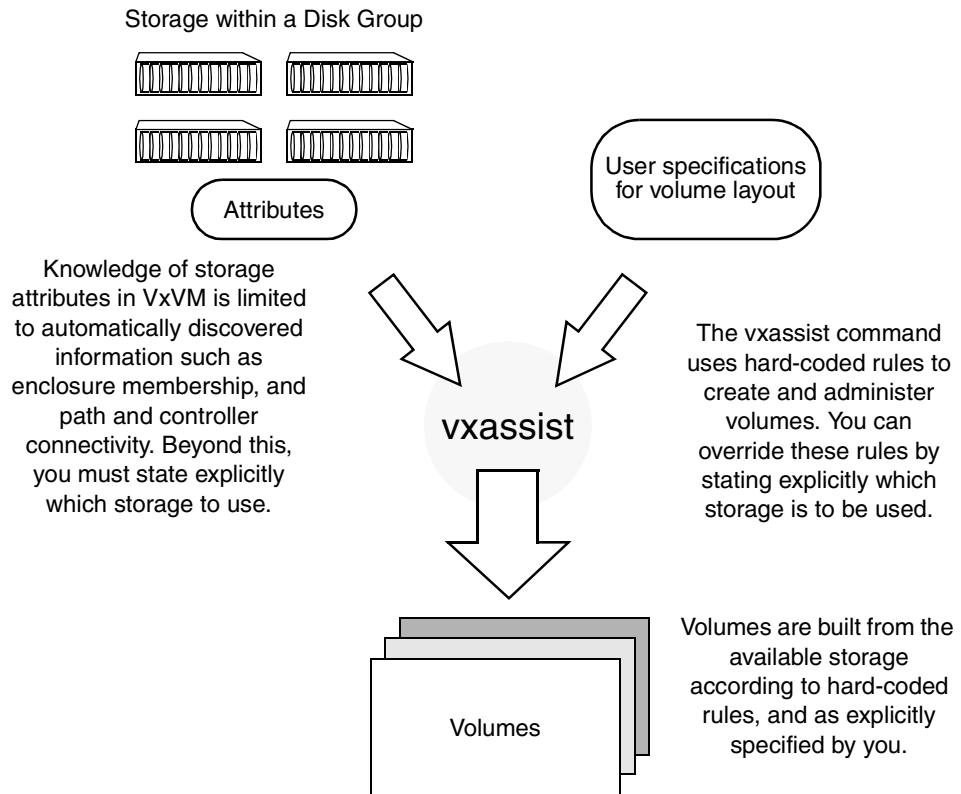
The Benefits of ISP

When creating a volume in VERITAS Volume Manager in previous releases, you could specify the disk storage on which to lay out its various parts, subdisks, plexes, and so on. In specifying the storage to be used, you had to take into account the tolerance of a volume to failure of any component of the storage infrastructure, and how the specified layout affected I/O performance and reliability of service. For small installations with a few tens of disks in relatively low-specification arrays, you could either specify the storage layout manually to commands such as `vxassist`, or rely on `vxassist` to choose appropriate storage based on general layout specification, such as “mirror across controllers” and “mirror across enclosures,” and using the set of heuristic rules that are hard-coded within `vxassist`.

The traditional model for allocating storage to volumes is shown in [“Traditional Model for Creating and Administering Volumes in VERITAS Volume Manager”](#) on page 13. This illustrates that, although some storage attributes are known to VxVM, you must do most of the work in deciding how to lay out the storage if you are to create a volume with the desired performance, reliability and fault tolerance.



Traditional Model for Creating and Administering Volumes in VERITAS Volume Manager



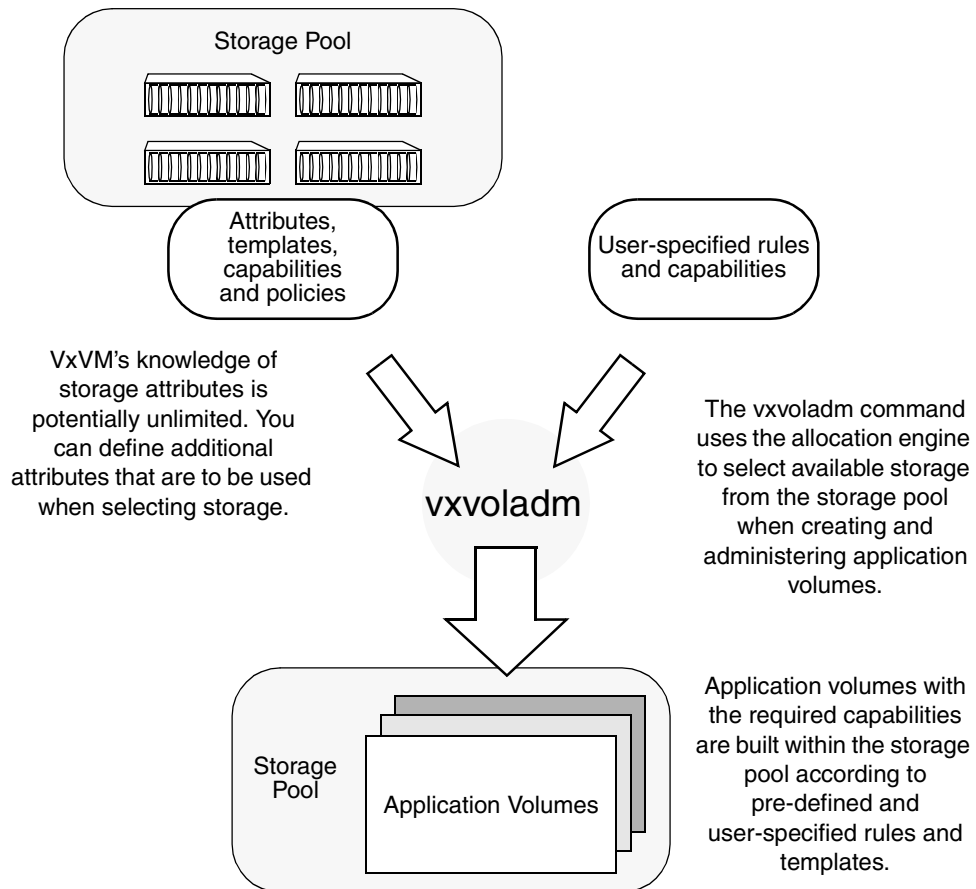
When intelligent disk arrays are used, many sophisticated features, such as RAID capabilities, snapshots facilities, and remote replication, are provided by logical unit storage devices, LUNs, that are exported by the disk array. Such devices may or may not have ways of making their attributes known to VxVM. In any case, you may be presented with hundreds or thousands of LUNs connected over a SAN.

Allocating storage to volumes when faced with a potentially large number of devices with widely varying and possibly hidden properties is a daunting task to perform manually. ISP aids you in managing large sets of storage by providing an allocation engine that chooses which storage to use based on the capabilities that you specify for the volumes to be created.

“[How ISP Enhances Volume Management](#)” on page 14 illustrates how ISP improves on the traditional model for creating volumes. The main differences are that the set of information about the available storage is potentially unlimited, and the set of rules that the allocation engine uses to choose storage is defined externally to commands such as `vxvoladm`.



How ISP Enhances Volume Management



Summary of the Benefits of Using ISP

The following list summarizes the main benefits that VERITAS ISP provides over the existing storage allocation features in `vxassist`:

- ◆ Storage is automatically allocated based on abstract requirements such as the desired capabilities of a volume.
- ◆ Prefabricated capabilities that are provided by vendor-specific features of intelligent storage arrays can be encoded as storage attributes, and used to allocate storage.
- ◆ Volumes can be created or grown in batch mode safe in the knowledge that ISP will balance the requirements of all volumes.

- ◆ All ISP operations preserve the original intent of the volumes. There is no possibility that operations such as grow, evacuate, add mirror, or add column can accidentally degrade the reliability or performance capabilities of a volume.
- ◆ ISP is SAN-aware and understands SAN attributes. It is also capable of using VAIL to learn the capabilities of LUNs.
- ◆ The annotation service allows you to define attributes for LUNs that lie outside their discovered hardware characteristics, and to assign values to these attributes.

Limitations of ISP

The following features of `vxassist` are not currently supported in ISP:

- ◆ The `vxassist` utility includes a number of hard-coded rules that it uses when selecting storage. For example, `vxassist` may configure objects on separate controllers without being instructed to do so. ISP requires that the selection of storage is made explicit through rules, capabilities and templates.
- ◆ ISP supports space-optimized instant snapshots and full-sized instant snapshots that are created on pre-prepared volumes. It does not support third-mirror break-off snapshots.
- ◆ Disk group split and join is supported at the level of storage pools. A snapshot of an application volume should be created within a clone pool if it is to be moved between disk groups.
- ◆ Templates are not provided in the base product to support the special features of EMC Symmetrix arrays.



Administration Roles in ISP

The administration of ISP can seem overwhelming when compared with the traditional administration model in VERITAS Volume Manager. To simplify matters, it is useful to think in terms of three levels of administration based on level of knowledge of ISP, and frequency of application of this knowledge:

- ◆ [Basic Administration Tasks](#)
- ◆ [Advanced Administration Tasks](#)
- ◆ [Expert Administration Tasks](#)

Basic administration tasks are performed most often and require the least knowledge of ISP to perform. Expert storage administration tasks are performed least often and require the most knowledge of ISP to perform.

Basic Administration Tasks

Basic administration tasks include creating storage pools, and creating and administering volumes. This includes performing tasks such as adding or removing mirrors or columns from volumes, resizing volumes, and creating and using volume snapshots.

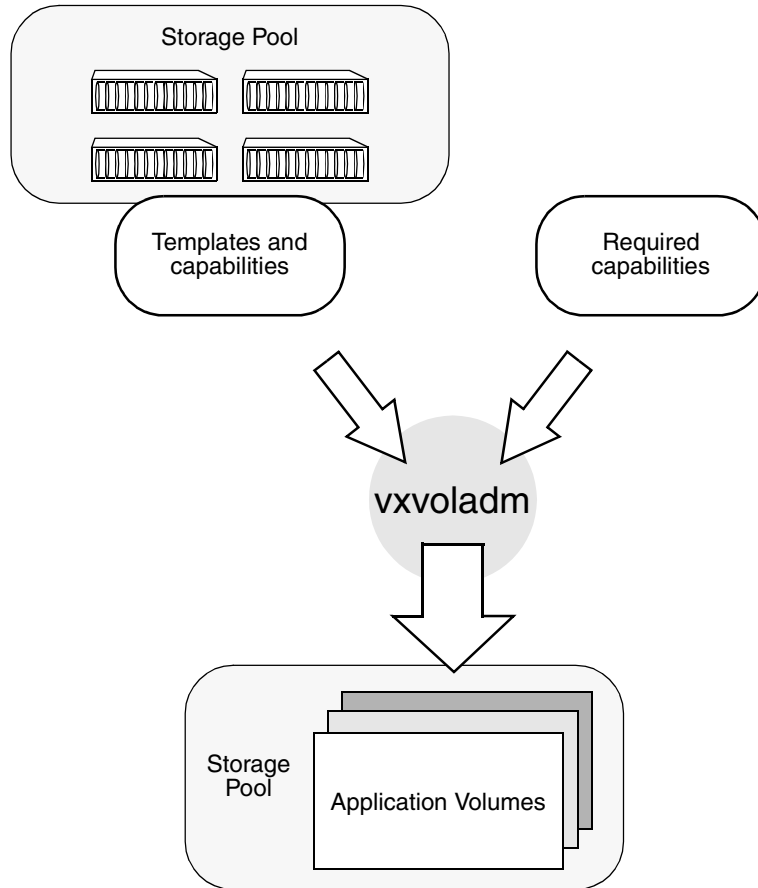
The system administrator's role requires the following knowledge of ISP:

- ◆ Familiarity with the meaning of the terms disk group, storage pool, template, user template, application volume, and capabilities such as reliability, performance and fault tolerance.
- ◆ What templates and user templates are available for use in creating volumes with the required capabilities.
- ◆ What templates and user templates are associated with the disk groups in which you will create volumes.
- ◆ How to use the VEA or the `vxvoladm` and `vxtemplate` commands to perform your tasks.

As a system administrator, you can use either the VEA or the `vxvoladm` and `vxtemplate` utilities to perform your tasks. The VEA graphical interface is most suitable for day-to-day administration. The `vxvoladm` utility is primarily intended for use in administration scripts. The `vxtemplate` utility allows you to find out which templates are associated with disk groups and with storage pools.

The use of `vxvoladm` to create application volumes is illustrated in “[Creation of Application Volumes](#).”

Creation of Application Volumes



System administration tasks are described in the following chapters:

- ◆ [Creating Application Volumes](#)
- ◆ [Administering Application Volumes](#)
- ◆ [Administering Instant Snapshots](#)



Advanced Administration Tasks

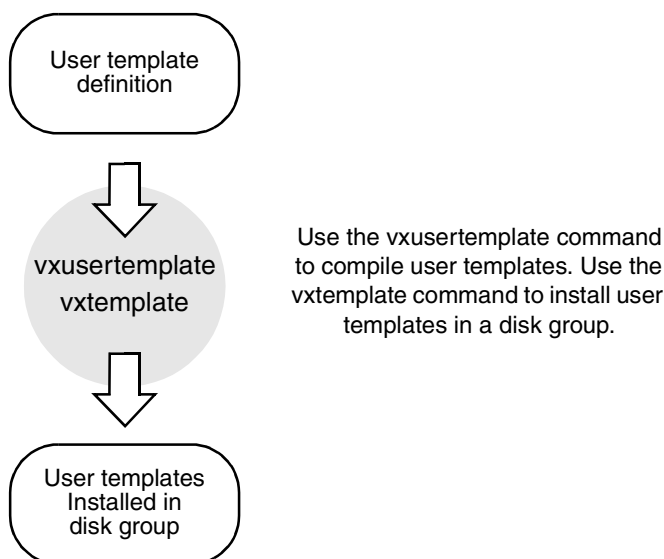
Advanced administration tasks include administering storage pools and user templates, creating clone pools, and creating volumes with additionally specified rules.

The system administrator's role requires the following knowledge of ISP:

- ◆ Knowledge of basic administration tasks, see "[Basic Administration Tasks](#)" on page 16.
- ◆ Familiarity with the meaning of the terms LUN, attribute, policy, intent, and rules such as those for confining or excluding how storage is allocated to new volumes.
- ◆ How to create or modify user templates, and then associate these with disk groups and storage pools.
- ◆ How to use the VEA or the command-line utilities to perform your tasks.

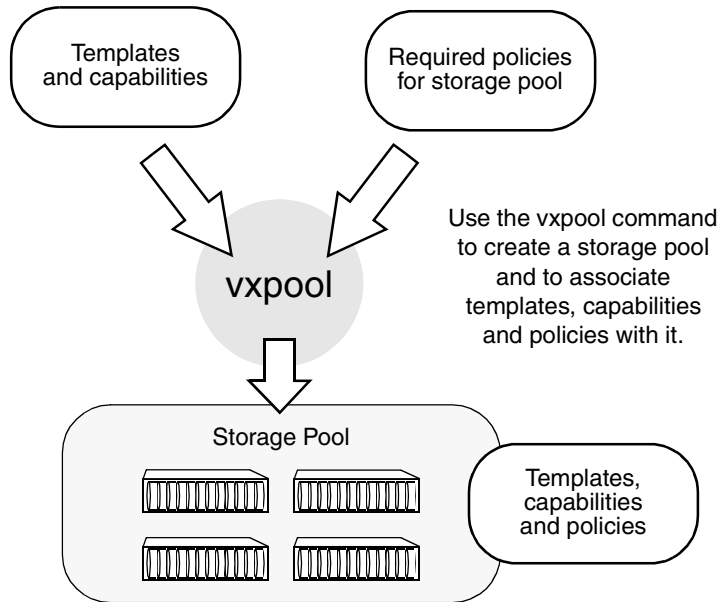
As a storage administrator, you can use either the VEA or command-line utilities to perform your tasks. The VEA interface is most suitable for day-to-day administration. The command-line utilities are primarily intended for use in administration scripts, but can also be used to compile and install user templates as illustrated in "[Creation of User Templates](#)."

Creation of User Templates



“[Creation of Storage Pools](#)” illustrates that the `vxpool` command is used to create storage pools with associated policies, templates and capabilities.

Creation of Storage Pools



System administration tasks are described in the following chapters:

- ◆ [Creating and Administering Storage Pools](#)
- ◆ [Creating and Modifying User Templates](#)



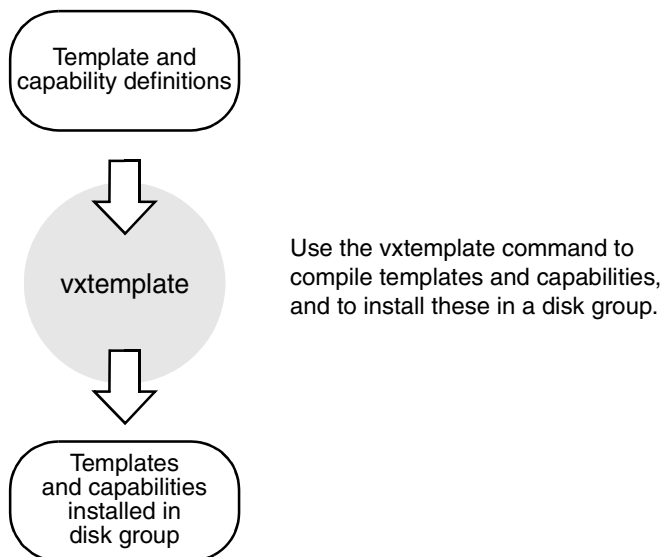
Expert Administration Tasks

Expert administration tasks include creating new attributes to describe storage features, and designing and creating new templates and capabilities.

The storage administrator's role requires the following knowledge of ISP:

- ◆ Knowledge of basic and advanced administration tasks, see “[Basic Administration Tasks](#)” on page 16 and “[Advanced Administration Tasks](#)” on page 18.
- ◆ Familiarity with the ISP rule specification language, and how to use it to write rules, capabilities and templates.
- ◆ How to use the VEA or the command-line utilities to perform your tasks. You can use any suitable text editor to create template definition files. The command-line utilities are primarily intended for use in administration scripts, but can also be used to compile and install templates and capabilities as illustrated in “[Creating Templates and Capabilities](#).”

Creating Templates and Capabilities



Advanced storage administration tasks are described in the following chapters:

- ◆ [Administering Volume Templates and Other Configuration Elements](#)
- ◆ [Using Capabilities, Templates and Rules](#)
- ◆ [ISP Language Definition](#)

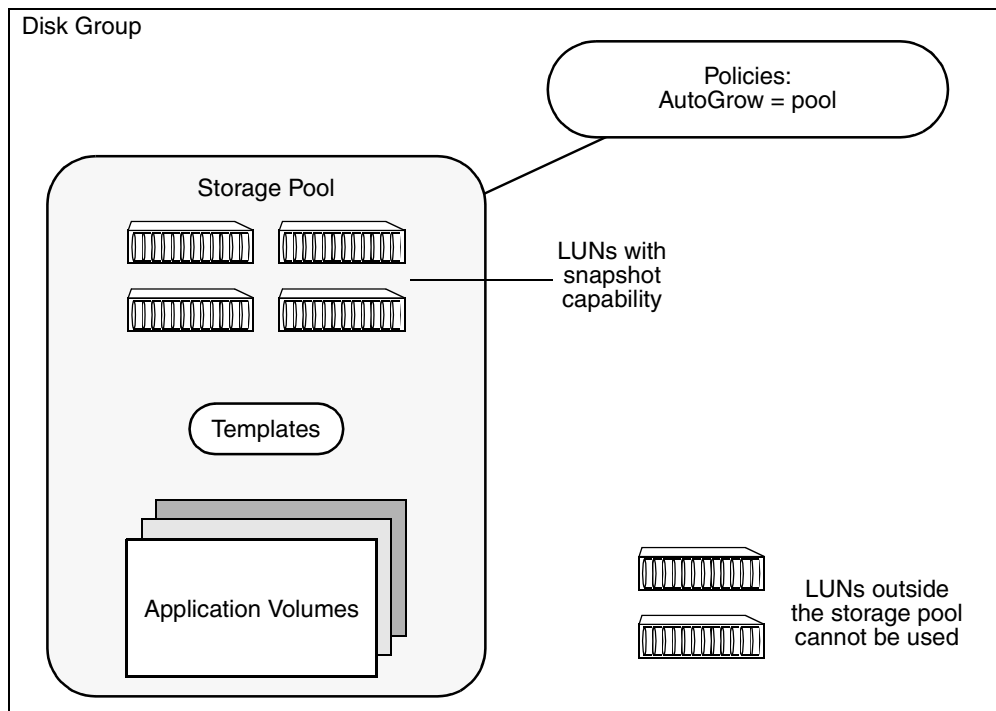
Sample ISP Deployments

This section contains high-level examples of how you can configure volume creation using ISP.

Using Storage Pool Policies

As described in [“Policy”](#) on page 5, a storage pool’s policies affect how it allocates LUNs to create new volumes, and how it uses templates. By selecting which templates and LUNs are associated with a storage pool, and setting appropriate policies on the storage pool, you can control how storage is allocated to volumes. For example, a storage pool might be composed entirely of LUNs that have a hardware snapshot capability (for example, EMC Business Continuity Volumes). Setting the `AutoGrow` policy to `pool` ensures that the entire storage pool remains snapshot-capable as illustrated in [“Effect of Setting the Value of the AutoGrow Policy to pool.”](#)

Effect of Setting the Value of the AutoGrow Policy to pool

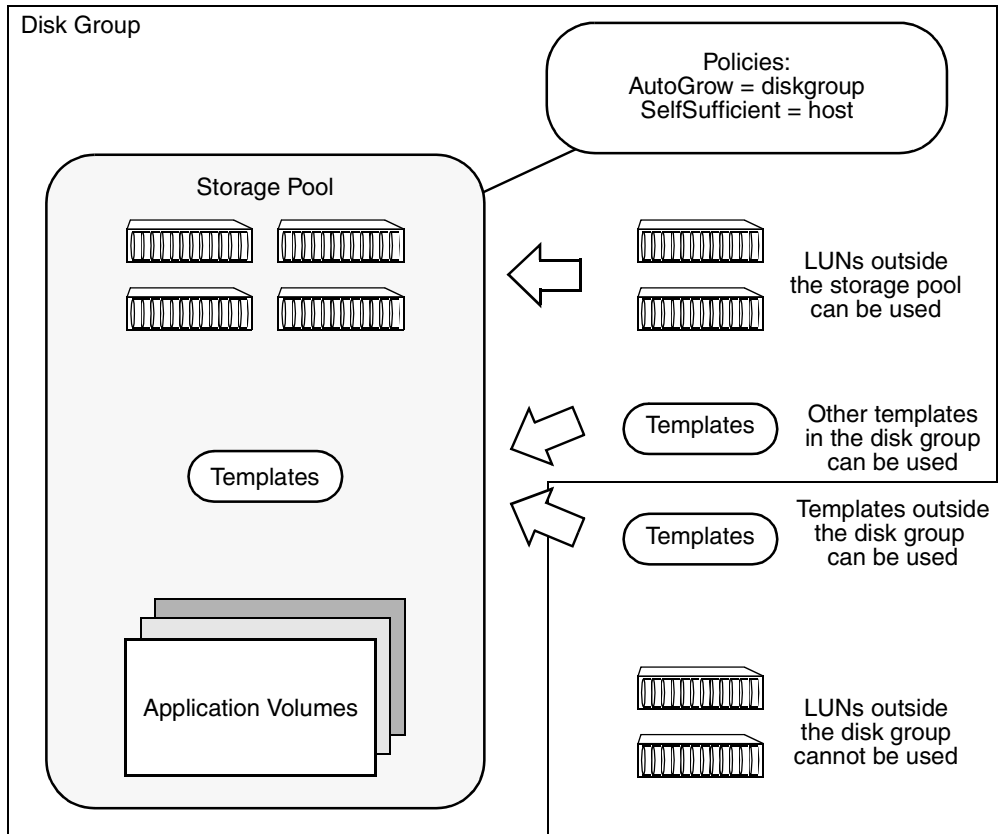


If the `AutoGrow` policy level were to remain set to the default value of `diskgroup`, this would allow the ISP to aggregate LUNs from the disk group.



“Effect of Setting Non-Default Storage Pool Policies” illustrates how setting the `AutoGrow` policy to `diskgroup` allows LUNs from the same disk group that are outside the storage pool to be used, and setting the `SelfSufficient` policy to `host` allows templates that provide the required capabilities to be imported from outside the storage pool or disk group.

Effect of Setting Non-Default Storage Pool Policies

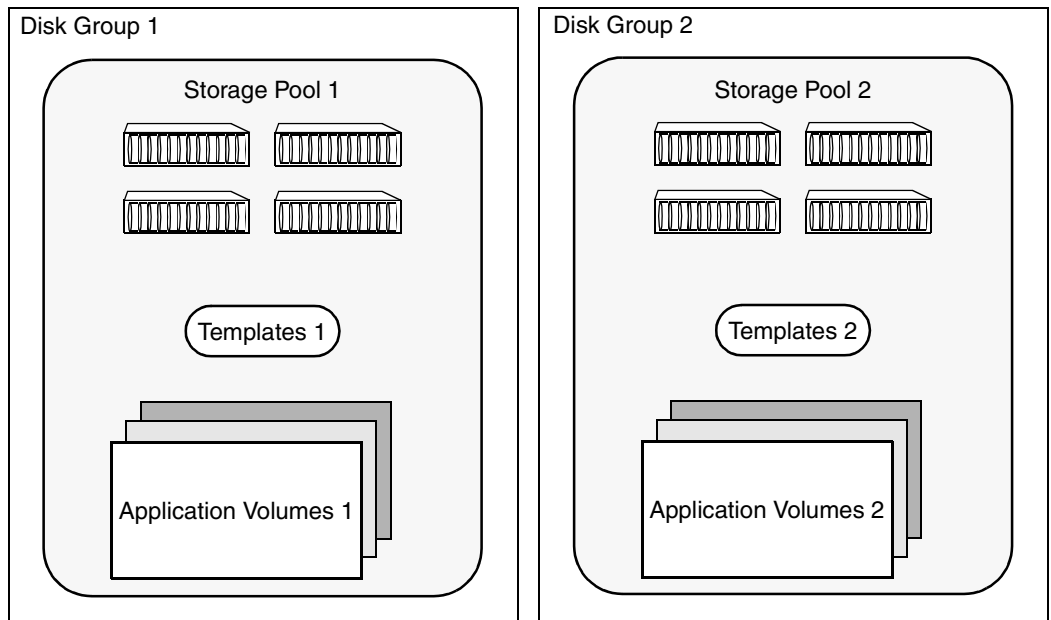


Note Setting the storage pool policies away from their default values may not be desirable if you want to maintain close control over how a storage pool is used.

Arranging Storage by Volume Usage

The simplest way to arrange storage so that its use is restricted to certain applications is to divide it between storage pools as shown in “[Arranging Storage by Volume Usage](#).” This requires that each storage pool is configured in a separate disk group. Each storage pool can have its own set of policies and templates that are tailored to the requirements of the volumes that are created from its LUNs.

Arranging Storage by Volume Usage



Although this is the simplest way of arranging storage and is expected to be the most common, it may not provide sufficient flexibility for some installations. See “[Arranging Storage by Attributes](#)” on page 24 for an example of using storage attributes for controlling how storage is allocated.

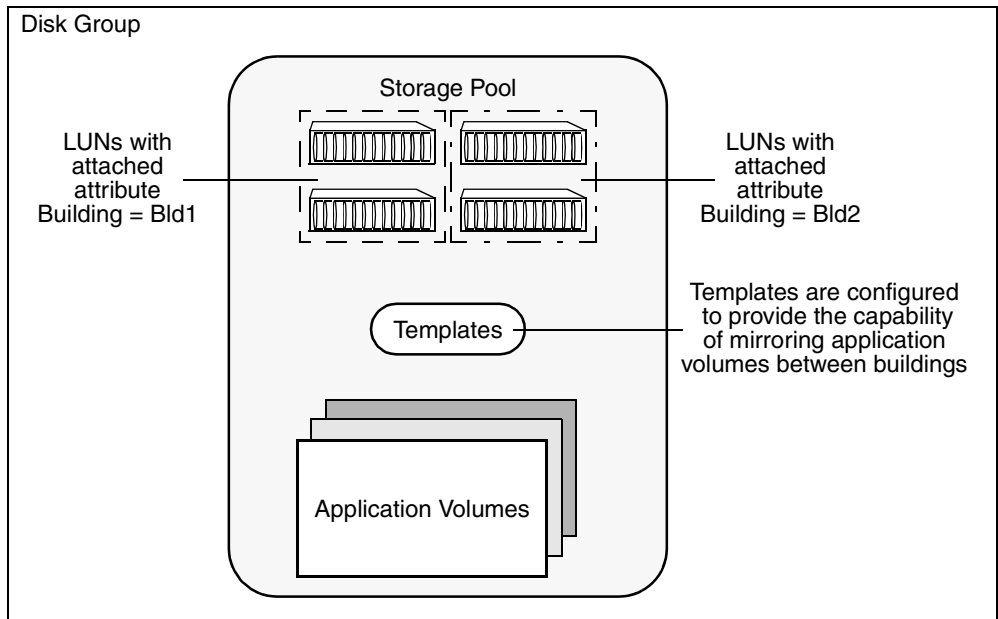


Arranging Storage by Attributes

You can use storage attributes to control how ISP assigns storage to application volumes. For example, you can use confinement rules to restrict some volumes to a subset of LUNs which share common attributes, such as caching to enhance I/O performance, or hardware RAID to provide redundancy and/or enhance performance.

As described in “[Policy](#)” on page 5, not all attributes of LUNs are capable of being discovered automatically. You can use the annotation service to manually attach such attributes to storage. An example of using attached attributes is shown in “[Example Usage of Attached Attributes](#),” where the templates can use the value of the `Building` attribute to provide the availability capability of mirroring volumes between different locations at a site.

Example Usage of Attached Attributes



Alternatively, you could specify appropriate separation rules to instruct ISP to mirror volumes between buildings.

Another example of using attached attributes would be to tag certain LUNs within a storage pool as having the best performance. You could then use confinement rules to ensure that certain volumes are only configured from this storage, while the remaining storage is used for other volumes with less critical performance requirements.

Frequently Asked Questions About ISP

- ◆ *What is the relationship between a storage pool and a volume template?*

Storage pools contain disks, VxVM objects such as volumes, and a set of volume templates. A storage pool is defined by the volume templates that it contains. The ISP Configuration Database contains a number of storage pool definitions that you can use to create a storage pool object in VxVM. Each definition contains a list of volume templates and the default policy settings for the pool. definition. When you create a storage pool object in a disk group from a storage pool definition, these volume templates and policies also get installed.

- ◆ *When do I need to specify a template set?*

A storage pool contains volume templates that define its characteristics. A template set is simply a collection of related volume templates that you can associate with a storage pool.

- ◆ *When do I need to specify a storage pool set?*

A disk group that you want to use with ISP must be configured to contain one data storage pool, and optionally one or more clone storage pools. You can use a storage pool set definition to organize a disk group so that it contains data and clone storage pools with well-defined characteristics.

- ◆ *If I create a storage pool using a storage pool definition, can I later create a volume in that pool using a volume template other than those that are associated with the pool?*

The answer can be illustrated by an example. Suppose you create a storage pool using the `mirrored_volumes` pool definition. This installs volume templates that allow you to create mirrored volumes and volumes with similar characteristics in the pool. If you attempted to create a striped volume in the pool, the resulting volume is mirrored as well as striped. However, you are not constrained from creating volumes with other characteristics. You can use rules to bypass restrictions that are imposed by higher-level abstractions like volume templates and capabilities.

Bear in mind that creating a storage pool from a storage pool definition does not uniquely determine the capabilities of volumes that you create in the pool. Only when you create a volume can you specify its capabilities and ensure consistency between the volumes in a pool.

- ◆ *What does “prefabricated” mean as used in volume templates?*

The term *prefabricated* implies that the characteristics of a volume are implemented using hardware rather than software. For example, `PrefabricatedRaid5` implies the use of RAID-5 LUNs that have been set up in an array’s hardware, rather than being implemented as a VxVM RAID-5 volume.



- ◆ *Can I use both hardware and software RAID volumes in a storage pool?*

A storage pool is usually configured either for prefabricated RAID devices or for VxVM volumes that are created in software. This provides consistency in performance and failure tolerance within the pool. If you add both hardware and software RAID templates to a pool, ISP allocates templates that are appropriate to the capabilities of the volumes that you specify.

- ◆ *How does ISP discover LUN hardware characteristics?*

ISP relies on the VERITAS Array Integration Layer (VAIL) to provide detailed information on LUN characteristics via array-specific modules.

- ◆ *How do I restrict allocation to storage from certain vendors, for example EMC BCV or Hitachi?*

By default, ISP use LUNs with similar characteristics for allocating storage. If insufficient storage is available, it relaxes this constraint. You can make the constraint mandatory by specifying the capability `ArrayProductId` when creating a volume. This forces ISP to allocate storage on LUNS that share with the same product identifier. Alternatively, you can use the capability `ConfineToSimilarStorage`. This makes ISP use LUNs from the same vendor, but allows the product identifiers of these LUNs to differ.

- ◆ *When I create a volume, ISP uses space on the same disks unless I choose other disks from the storage pool manually. Why doesn't ISP automatically spread the volumes across the other disks in the storage pool to enhance I/O performance?*

ISP is tuned to use as few disks as possible. In any case, I/O performance depends on many factors: the way storage is connected to the system, the inherent capabilities of the storage, how volumes are configured and how they share storage, the type of I/O requests made by applications, and the amount of I/O from/to each volume. For example, allocating two volumes to a single disk array that has a large cache would probably provide better overall I/O performance than placing one volume on the disk array and the other on a JBOD. If necessary, you can configure smaller storage pools in separate disk groups to restrict the allocation of storage. Alternatively, you can explicitly specify the storage that can or cannot be allocated to a volume.

Examples of Using ISP from the Command Line

This section provides examples of using ISP from the command line and provides pointers to where more information can be found. You can also find summaries of the usage of commonly used commands in “[Command Summary](#)” on page 169. Further examples may be found in “[Command Examples](#)” on page 173 and in the manual page for each command.

Creating a Data Storage Pool

Assuming that you have created a disk group, `mydg`, that contains several disks that you have initialized for use with VxVM, the following command creates a data storage pool, `mypool`, containing several disks, and which supports the creation of striped-mirror volumes:

```
# vxpool -g mydg create mypool \
  dm=mydg01,mydg02,mydg03,mydg04,mydg06 \
  pooldefinition=stripe_mirror_volumes
```

For more information, see “[Creating a Storage Pool](#)” on page 34.

Adding Disks to a Storage Pool

You can use the `vxpool adddisk` command to add initialized disks to a storage pool. For example, this command adds two disks to the storage pool, `mypool`:

```
# vxpool -g mydg adddisk mypool dm=mydg07,mydg08
```

For more information, see “[Adding Disks to a Storage Pool](#)” on page 37.

Creating an Application Volume

The following command creates a striped-mirror volume with three columns and two mirrors in the data storage pool, `mypool`, by specifying the capability `DataStripeMirror` together with the appropriate parameters:

```
# vxvoladm -g mydg -p mypool make stmrvol 2g \
  capability='DataStripeMirror(ncols=3,nmirs=2)' init=active
```

The `init=active` attribute makes the volume immediately available for use without performing any synchronization.



Having created the application volume, `stmrvol`, you can use the following command to prepare it for use with volume snapshots:

```
# vxvoladm -g mydg -p mypool add log stmrvol nlog=2 logtype=dco
```

This command associates a data change object (DCO) and DCO volume with the volume. The attribute `nlog` is used to specify that the DCO volume has the same redundancy as the original volume. Alternatively, you can use the `vxsnap prepare` command to set up the volume for snapshots:

```
# vxsnap -g mydg prepare stmrvol ndcomirs=2
```

For more information, see [“Creating Application Volumes”](#) on page 41 and [“Creating Instant Snapshots”](#) on page 75.

Resizing an Application Volume

If the application volume, `stmrvol`, that you have just created is not large enough for your needs, you can increase its size using this command:

```
# vxvoladm -g mydg -p mypool growto stmrvol 4g
```

Any file system or other application storage layout that you have created on the volume can be resized after you have grown the volume.

For more information, see [“Resizing Volumes Online”](#) on page 53.

Creating a Clone Storage Pool

Assuming that you also want to create full-sized snapshots of application volumes in `mypool` that can be moved into different disk groups (potentially for offhost processing), the following command creates a clone storage pool, `myclpool`, in the same disk group as `mypool`:

```
# vxpool -g mydg create myclpool dm=mydg09,mydg10,mydg11,mydg12 \  
autogrow=pool pooldefinition=mirrored_volumes
```

This pool supports the creation of mirrored volumes. It also has a non-default `autogrow` policy that prevents it aggregating disks from the disk group outside the pool.

For more information, see [“Preparing Storage Pools for Full-Sized Instant Snapshots”](#) on page 69.

Preparing a Full-Sized Snapshot Volume

Before you can take a full-sized snapshot of an application volume, you must prepare the empty volume that is to become the snapshot volume as shown here:

```
# vxvoladm -g mydg -p myclpool make mysnpvol 2g type=snapshot\  
init=active
```

This command automatically associates a data change object (DCO) and DCO volume with the volume. For more information, see [“Creating a Volume for Use as a Full-Sized Instant Snapshot”](#) on page 70.

Taking a Full-Sized Snapshot of an Application Volume

Having prepared an empty volume, you can take a snapshot of the application volume:

```
# vxsnap -g mydg make source=stmrvol/snapvol=mysnpvol/syncing=on
```

The following command starts a full synchronization of the snapshot volume, and blocks until this is complete:

```
# vxsnap -g mydg syncwait mysnpvol
```

For more information, see [“Creating Instant Snapshots”](#) on page 75.

Creating a Cache Volume for Space-Optimized Snapshots

If you want to use space-optimized snapshots, you must prepare a storage cache where the snapshots can be created. This command sets up a 1GB cache volume, `mycache`, in the clone pool, `myclpool`:

```
# vxvoladm -g mydg -p myclpool make mycache 1g type=cachevolume
```

For more information, see [“Creating a Shared Cache Volume and Preparing Space-Optimized Snapshots”](#) on page 71.



Preparing a Space-Optimized Snapshot

Having created a cache volume, you now need to prepare the space-optimized snapshots that you require. This command sets up a space-optimized snapshot, `mysovol`, using the cache volume, `mycache`:

```
# vxvoladm -g mydg -p myclpool make mysovol 2g type=snapshot \  
cachevolume=mycache init=active
```

Note The argument `2g` is the same as the length of the original source volume for which the snapshot is being prepared. This value defines the logical size of the snapshot. The actual amount of storage that the snapshot requires is less than this, and is limited by the size of the cache volume.

For more information, see [“Creating a Shared Cache Volume and Preparing Space-Optimized Snapshots”](#) on page 71.

Taking a Space-Optimized Snapshot of an Application Volume

Having prepared a cache volume and one or more empty space-optimized snapshots, you are ready to take a snapshot of the application volume:

```
# vxsnap -g mydg make source=stmrvol/snapvol=mysovol
```

For more information, see [“Creating Instant Snapshots”](#) on page 75.



Creating and Administering Storage Pools

2

VERITAS Intelligent Storage Provisioning (ISP) allows you to group storage with similar characteristics for creating volumes. A storage pool is a named collection of volumes and the LUNs with which they are associated.

The storage policies and rules that are associated with a storage pool determine its characteristics. Each storage pool represents a collection of volumes that are created according to these policies and rules. For example, a pool may be configured to allow allocation of LUNs from outside the pool, and to use only templates that are associated with the pool by specifying the appropriate `autogrow` and `selfsufficient` policies.

For more information on the rules that are supported for storage pools, refer to “[Rules](#)” on page 115.

This chapter describes how to use the `vxpool` utility to create and administer storage pools. For full information about this command, see the `vxpool(1M)` manual page.

Reserving and Unreserving Disks for Use with ISP

When you initialize a disk for use with VxVM, for example, by running the `vxdiskadm` command, both ISP and non-ISP utilities have access to the space on the disk. You can reserve a disk for use with either set of utilities by setting the values of the `allocator_reserved` and `allocator_nouse` flags for the disk.

To reserve disks for exclusive use with ISP, and prevent non-ISP utilities such as `vxassist` from using these disks, select the menu item 23 `Mark a disk as ISP-reserved for a disk group` from the main menu of the `vxdiskadm` command. Alternatively, you can use the following command to reserve a disk specified by its disk media name for use with ISP:

```
# vxedit [-g diskgroup] set "allocator_reserved=on" diskname
```

Note A disk that is to be reserved for ISP must not contain any existing VxVM subdisks.



To remove the reservation flag from disks, select menu item 24 Turn off the allocator-reserved flag on a disk from the main menu of the `vxdiskadm` command. Alternatively, you can use the following command to remove ISP reservation from a disk specified by its disk media name:

```
# vxedit [-g diskgroup] set "allocator_reserved=off" diskname
```

To prevent a disk from being used by ISP, enter the following command:

```
# vxedit [-g diskgroup] set "allocator_nouse=on" diskname
```

The following command removes the restriction on ISP using a disk:

```
# vxedit [-g diskgroup] set "allocator_nouse=off" diskname
```

Note The flags `allocator_reserved` and `allocator_nouse` are mutually exclusive. Their values cannot both be set to on for a disk.

You can use the `vxdisk list` and `vxprint` commands to tell whether a disk has been reserved for ISP, as shown in the following examples:

```
# vxdisk list
DEVICE      TYPE          DISK          GROUP        STATUS
c0t8d0s2    auto:cdsdisk mydg1        mydg         online allocrsvd

# vxprint -g mydg mydg1
TY NAME     ASSOC      KSTATE LENGTH  PLOFFS  STATE      TUTILO  PUTILO
dm mydg1    c0t8d0s2  -         35365968-  ALLOC_RES -        -
```

The `allocrsvd` status flag and the `ALLOC_RES` state indicate that a disk is reserved for use with ISP.

Organizing Storage Pools in a Disk Group

Before you can use ISP to create volumes in a disk group, you must first create any storage pools that you require in that disk group. A storage pool has associated disks, templates and policies. These policies control how the disks and templates are used when allocating storage from the pool to volumes.

The `vxpool organize` command simplifies the initial creation of one or more pools in a disk group by using a storage pool set definition. You can use this command to create a set of pools with policies and templates that are designed for a variety of different applications. A storage pool set consists of one data pool definition and one or more clone pool definitions. Each of these pool definition typically consists of the pool type, the templates that the pool contains, and the pool policies. See “[Listing Storage Pool Sets](#)” and “[Displaying Storage Pool Set Definitions](#)” on page 33 for details of how to find out what

storage pool sets are available for use. See [“Using Disk Group Split and Join with Storage Pools”](#) on page 36 for details of how data and clone pools are typically used with the disk group split and join feature of VxVM.

For example, if you want your data volumes to be mirrored for redundancy, and your snapshot volumes to be striped for performance, you can choose a storage pool set definition where the data pool has associated templates that relate to mirroring, and the clone pool has associated templates that relate to striping. A suitable choice would be the `mirrored_data_striped_clones` storage pool set described on page 162. To create these storage pools within a disk group, you would use the following command:

```
# vxpool -g diskgroup organize mirrored_data_striped_clones
```

The section, [“Creating a Storage Pool”](#) on page 34, describes the alternate way of creating storage pools in a disk group.

Listing Storage Pool Sets

A storage pool set defines the storage pool types for a data storage pool and for the clone storage pools that are used to hold snapshots of the data storage pool’s volumes.

To list all the available storage pool sets, use the following command:

```
# vxpool listpoolsets
```

For a list of supported storage pool sets, see [“Storage Pool Sets”](#) on page 162.

Displaying Storage Pool Set Definitions

To display the definition of a storage pool set, use the following command;

```
# vxpool printpoolsets storage_pool_set [storage_pool_set ...]
```

For example, the following command displays the definition of the storage pool set, `mirrored_data_stripe_clones`:

```
# vxpool printpoolsets mirrored_data_stripe_clones
storage_pool_set mirrored_data_striped_clones {
  description "The data volumes have multiple copies of data.
  Snapshot volumes have I/Os spread across multiple columns."
  display_name "Mirrored Data and Striped Snapshots"
  data mirrored_volumes
  clone striped_volumes
};
```

See [“Displaying Storage Pool Definitions”](#) on page 35 for information on how to display definitions for storage pool types such as `mirrored_volumes` and `striped_volumes`.



Creating a Storage Pool

As an alternative to the `vxpool organize` command described in “[Organizing Storage Pools in a Disk Group](#)” on page 32, you can use the `vxpool create` command to define and create a storage pool, as shown here:

```
# vxpool [-g diskgroup] create storage_pool [dm=dm1[,dm2...]] \  
[description="description"] [autogrow={1|pool}|{2|diskgroup}] \  
[selfsufficient={1|pool}|{2|diskgroup}|{3|host}] \  
[rules=rule [ rule ...]] [pooldefinition=storage_pool_definition]
```

For example, the following command creates the storage pool, `mypool`, that contains disks `mydg02` and `mydg03`, and associates it with the disk group, `mydg`.

```
# vxpool -g testdg create testpool dm=mydg02,mydg03 \  
autogrow=diskgroup selfsufficient=pool
```

The `autogrow` policy level is set to `diskgroup` so the pool can use any storage within the disk group. The `selfsufficient` policy level of `pool` only allows the use of templates that have been manually assigned to the storage pool.

To simplify pool creation, you can also create a storage pool from a storage pool definition that is known to the system, as shown here:

```
# vxpool -g mydg create mypool pooldefinition=mirrored_volumes
```

Such definitions standardize storage pool policies and the templates that are to be associated with storage pools. See “[Listing Available Storage Pool Definitions](#)” on page 35 for details of how to find out the storage pool definitions that are known to the system, and “[Displaying Storage Pool Definitions](#)” on page 35 for information on how to display a storage pool definition.

See “[Storage Pools](#)” on page 158 for a list of pre-defined storage pool types. These definitions include default policy values, and a set of volume templates that are installed. You can add disks to such a storage pool as described in “[Adding Disks to a Storage Pool](#).”

Note The disks that you assign to a storage pool must have already been initialized for use, and must belong to the disk group in which you are creating the storage pool.

The first storage pool that you create in a disk group is a data storage pool that contains application volumes. Any storage pools that you subsequently create in the disk group are clone storage pools that can be used to hold full-sized instant snapshots of the volumes in the data storage pool. You need only place such snapshots in a separate clone storage pool if they need to be created using different templates from their parent volumes, or if they are to be moved into a different disk group.

See “[Administering Instant Snapshots](#)” on page 67 for more information about creating and using full-sized instant snapshots with clone storage pools.

Listing Available Storage Pool Definitions

To list all the available storage pool definitions, use the following command:

```
# vxpool listpooldefinitions
```

For a list of supported storage pool definitions, see “[Storage Pools](#)” on page 158.

To display the details of a storage pool definition, see “[Displaying Storage Pool Definitions](#)” on page 35.

Displaying Storage Pool Definitions

To display the details of one or more storage pool definitions, use the following command:

```
# vxpool printpooldefinitions [storage_pool_definition] ...
```

If no storage pool definitions are named, the definitions for all storage pools are displayed.

For example, the following command displays the definition of the storage pool, `mirrored_volumes`:

```
# vxpool printpooldefinitions mirrored_volumes
storage_pool mirrored_volumes {
    description "Volume has multiple copies of data."
    display_name "Data Mirroring"
    volume_templates ArrayProductId, ConfineLogsToSimilarStorage,
    ConfineMirrorsToSimilarStorage, ConfineToSimilarStorage,
    ConfineToSpecificStorage, DCOLogMirroring, DataMirroring,
    InstantSnapshottable, LogsOnSeparateComponents,
    MirrorsOnSeparateComponents, MultipathingThroughMultiplePaths
    autogrow 2
    selfsufficient 1
};
```



Using Disk Group Split and Join with Storage Pools

Storage pools form the smallest unit that can participate in disk group split and join operations (see the section “Reorganizing the Contents of Disk Groups” in the “Creating and Administering Disk Groups” chapter of the *VERITAS Volume Manager Administrator’s Guide* for details).

Note Only clone storage pools can be moved between disk groups; data pools must remain in the disk group in which they were created.

The following command is used to split one or more clone pools from a source disk group to a newly created target disk group:

```
# vxpdg split sourcedg targetdg clonepool ...
```

All volumes (including instant snapshots) within the specified clone pools are moved to clone pools within the target disk group.

Note Any disk group that contains a clone pool must also contain a data pool. If a clone pool is split from a disk group, an empty data pool is also created in the newly created target disk group.

The following command is used to join two disk groups by merging the contents of the source disk group with the target disk group and then removing the source disk group:

```
# vxpdg join sourcedg targetdg
```

All volumes (including full-sized instant snapshots) within the clone pool in the source disk group are moved to a clone pool of the same name within the target disk group.

Note When two disk groups containing storage pools are joined, only one of the data pools may contain any disks, and the set of templates that are associated with one data pool must be a subset (including the null set) of the templates that are associated with the other data pool. The join operation fails if both data pools contain disks, if the sets of templates are overlapping or disjoint. At the end of the join operation, the data pool that contains the most templates is retained and the other data pool is deleted.

You can use the following command to move a clone pool between disk groups:

```
# vxpdg move sourcedg targetdg clonepool ...
```

As for the split operation, a data pool is created in the target disk group if no data pool currently exists there.

Adding Disks to a Storage Pool

To add one or more initialized disks to the storage pool, use the following command:

```
# vxpool [-g diskgroup] adddisk storage_pool dm=dm1[,dm2,...]
```

The following example shows two disks, `mydg04` and `mydg05`, being added to the storage pool, `mypool`:

```
# vxpool -g mydg adddisk mypool dm=mydg04,mydg05
```

Note Any disks that you add to a storage pool must have already been initialized for use, and must belong to the same disk group as the storage pool.

If a storage pool's autogrow policy is set to `diskgroup`, ISP automatically brings additional disks from the disk group into the storage pool as required.

Removing Disks from a Storage Pool

To remove one or more disks from the storage pool, use the following command:

```
# vxpool [-g diskgroup] rmdisk storage_pool dm=dm1[,dm2...]
```

In the following example, the disks, `mydg01` and `mydg04`, are removed from the storage pool, `ReliablePool`, for use elsewhere:

```
# vxpool -g mydg rmdisk ReliablePool dm=mydg01,mydg04
```

Note You cannot remove a disk from a storage pool if any volumes are configured on that disk. To remove such a disk, first use the `vxvoladm evacuate` command to move the volumes away from the disk. When you have done this, you can then remove the disk from the storage pool.

Associating Templates with a Storage Pool

To associate one or more volume templates with a storage pool, use the `vxpool assoctemplate` command as shown here:

```
# vxpool [-g diskgroup] assoctemplate storage_pool \  
  template=t1[,t2,...]
```

For example, the following command associates the templates `Mirroring` and `Striping` with the storage pool, `ReliablePool`:

```
# vxpool -g mydg assoctemplate ReliablePool \  
  template=Mirroring,Striping
```



Note If the value of the `selfsufficient` policy is `diskgroup` or `host`, ISP first looks for storage that complies with the templates that are associated with the storage pool, and if no suitable templates are found, it then examines templates outside the pool.

For a list of supported templates, see “[Volume Templates](#)” on page 148.

Associating Template Sets with a Storage Pool

To associate one or more template sets, including all the templates that they contain, with a storage pool, use the `vxpool assoctemplateset` command as shown here:

```
# vxpool [-g diskgroup] assoctemplateset storage_pool \  
  template_set=ts1[,ts2,...]
```

For example, the following command associates the template set, `DataMirroring`, with the storage pool, `ReliablePool`:

```
# vxpool -g mydg assoctemplateset ReliablePool \  
  template_set=DataMirroring
```

Note If the value of the `selfsufficient` policy is `diskgroup` or `host`, ISP first looks for storage that complies with the templates that are associated with the storage pool, and if no suitable templates are found, it then examines templates outside the pool.

For a list of supported template sets, see “[Template Sets](#)” on page 144.

Dissociating Templates from a Storage Pool

To dissociate a template from the storage pool, use the following command:

```
# vxpool [-g diskgroup] distemplate storage_pool \  
  template=t1[,t2,...]
```

In the following example, the `PrefabricatedRaid5` template is dissociated from the storage pool, `ReliablePool`:

```
# vxpool -g mydg distemplate ReliablePool \  
  template=PrefabricatedRaid5
```

After a template has been dissociated, Storage Allocator does not refer to the rules and capabilities in that template unless this is permitted by the `selfsufficient` policy that is set on a storage pool.

Displaying Information About Storage Pools

To display information about one or more storage pools, use the following command:

```
# vxpool [-g diskgroup] print storage_pool [storage_pool ...]
```

For example, the following command displays information about the storage pool, ReliablePool:

```
# vxpool -g mydg print ReliablePool
TY   NAME           AUTOGROW  SELFSUFFICIENT  DESCRIPTION
st   ReliablePool    2         2                -
dm   disk04          -         -                -
dm   disk02          -         -                -
dm   disk01          -         -                -
```

The command displays the policies and description for each specified storage pool, together with a list of the disks that are associated with the storage pool.

Displaying Storage Pool Policies

To display the policies that are set on a storage pool, use the `vxpool getpolicy` command as shown here:

```
# vxpool [-g diskgroup] getpolicy storage_pool
```

In the following example, this command is used to display the policies for the storage pool, ReliablePool:

```
# vxpool -g mydg getpolicy ReliablePool
Autogrow           Selfsufficient
2                  1
```

Changing the Policies on a Storage Pool

By default, Storage Allocator sets the values of the `autogrow` policy to `diskgroup`, and the `selfsufficient` policy to `pool`. To change the policies that are set on a storage pool, use the `vxpool setpolicy` command:

```
# vxpool [-g diskgroup] setpolicy storage_pool \
[autogrow={1|pool}|{2|diskgroup}] \
[selfsufficient={1|pool}|{2|diskgroup}|{3|host}]
```

The existing pool policies are overwritten by the new levels that you set.



In the following example, the policies on the storage pool, `mypool`, are changed to disallow the use of storage resources from outside the storage pool, and to allow all available templates to be considered for use when creating volumes:

```
# vxpool -g mydg setpolicy mypool autogrow=pool \  
selfsufficient=host
```

Listing Storage Pools Within a Disk Group

To display a list of all storage pools within a disk group, use the `vxpool list` command as shown here:

```
# vxpool [-g diskgroup] list
```

For example, the following command lists all the storage pools within the disk group, `mydg`:

```
# vxpool -g mydg list
```

Renaming a Storage Pool

To rename a storage pool, use the following command:

```
# vxpool [-g diskgroup] rename storage_pool new_name
```

For example, to rename the storage pool, `mypool`, as `ReliablePool`, you would use the following command:

```
# vxpool -g mydg rename mypool ReliablePool
```

Deleting a Storage Pool

To delete a storage pool, use the following command:

```
# vxpool [-g diskgroup] [-r] delete storage_pool
```

The `-r` option must be specified to dissociate all disks from the storage pool and then deletes the storage pool as shown in this example:

```
# vxpool -g mydg -r delete ReliablePool
```

Note If any volumes are present in the storage pool, you must delete these before the storage pool can be deleted.

Creating Application Volumes

3

Volumes created by VERITAS Intelligent Storage Provisioning (ISP) are similar to traditional volumes created by `vxassist`, but have the advantage that their intent is preserved and cannot accidentally be degraded. Volumes that are created by ISP can be managed by using commands such as `vxvoladm`, or by using the VEA client graphical user interface. For information on using VEA to create volumes, refer to the *VERITAS Volume Manager User's Guide — VEA*. This chapter describes how to use the `vxvoladm` command to create volumes.

Note To create application volumes successfully, the appropriate licenses must be present on your system. For example, you need a full VERITAS Volume Manager™ license and a VERITAS FlashSnap™ license to use the instant snapshot feature. Vendors of disk arrays may also provide capabilities that require special licenses for certain features of their hardware.

Overview of the `vxvoladm` Command

You can use the `vxvoladm` command to create and manage volumes. ISP optimally assigns storage resources as defined and constrained by any parameter values, rules, capabilities and templates that you specify as arguments to the command. Capabilities provide the highest, most abstract way of specifying volumes. Rules provide the lowest, most direct means of specification. This gives you great freedom to create volumes that meet your requirements.

The `vxvoladm` command takes the general form:

```
# vxvoladm [options] keyword volume [additional_arguments] \  
[storage_specification] [attribute=value ...]
```

The *keyword* denotes the action that `vxvoladm` is to perform on the named volume. The storage specification defines the storage that can or cannot be used with an operation. This consists of a comma-separated list of disk media names and other storage attributes, such as `Controller:controller_name` to indicate all disks on a controller. Excluded storage is indicated by a `!` prefix. Finally, attributes and their values can be used to specify further constraints on the operation.



Each invocation of `vxvoladm` is applied to only a single storage pool that has been configured within a disk group. The default disk group is that aliased by the setting of `defaulttdg`. You can specify an alternate disk group by using the `-g diskgroup` option.

Note Refer to the `vxvoladm(1M)` manual page for full details on using the `vxvoladm` command.

Setting Default Values for vxvoladm

You can define default values for `vxvoladm` in the file `/etc/default/allocator`, or in an alternate defaults file that you specify using the `-d` option. The defaults listed in this file are used unless they are overridden by a value specified on the command line. If a value is not defined in a defaults file or on the command line, `vxvoladm` uses a built-in default value.

By default, the attribute settings in the installed `/etc/default/allocator` file are commented out. If required, you can uncomment the entries, and edit their values. If you do this, you should first make a backup copy of the original unedited file to keep for reference.

The following entry for `default_rules` in the `/etc/default/allocator` file is commented out by default:

```
# default_rules=desired confineto "ProductId"
```

If enabled, this rule changes the default behavior of ISP so that it attempts to confine volumes to disks with the same product ID. The rule may also prevent hot-relocation or volume transformation taking place if disks with the same product ID are not available.

Determining the Maximum Volume Size

Before creating a volume, you may wish to check whether there is sufficient storage available. You can use the following command to determine the maximum size of a volume with a given capability that you can create in the data storage pool of a disk group:

```
# vxvoladm [-g diskgroup] [-p storage_pool] [-b maxsize \  
[storage_specification] [attribute=value ...]
```

Specify the `-b` option if you want to run this command in the background. Otherwise, it will block until it has completed its calculation of the maximum volume size.

Note The storage that is available for allocation is based on the setting of the `AutoGrow` policy on a storage pool. If the value of this policy is set to `diskgroup` and not to `pool`, all suitable disks in the disk group are used in the calculation. You can use the `-p` option to specify that only storage from the specified pool is to be considered.

For example, the following command returns the maximum possible size of a mirrored volume with 3 mirrors that can be created in the disk group, `mydg`, from all the available free storage using the `DataMirroring` capability:

```
# vxvoladm -g mydg maxsize capability='DataMirroring(nmirs=3)'
```

The next example checks for the maximum volume size that can be created using prefabricated mirrors of a specified vendor type:

```
# vxvoladm -g peakdg maxsize \
  volume_template=PrefabricatedDataMirroring \
  rules='confineto "VendorName"="ACME"'
```

Creating Volumes

To create a volume with a specified length, specify the `make` keyword to `vxvoladm` as shown here:

```
# vxvoladm [options] make volume length [storage_specification] \
  [attribute=value ...]
```

It is possible to specify a combination of capabilities, templates and rules to this command. Recall that:

- ◆ A rule specifies a criterion for choosing and allocating storage.
- ◆ A template is a meaningful collection of rules that define a capability.
- ◆ A capability is a high-level description of what a volume can do.

The properties of the volume that is created are further determined by any parameters and other attributes that you specify. Rules, capabilities and templates may be combined as follows:

- ◆ If you specify rules along with capabilities, ISP creates volumes that comply to the rules that are defined in the capabilities, and also to those rules that you specify as arguments to `vxvoladm`.
- ◆ If you specify rules along with templates, ISP creates volumes that comply to the rules in the templates, and also to those rules that are specified as arguments to `vxvoladm`.
- ◆ If you specify capabilities along with templates, ISP selects the appropriate templates from those specified that conform to the desired capabilities.



- ◆ If you specify rules, capabilities and templates, ISP selects the appropriate templates from those specified that conform to the desired capabilities, and that adhere to the specified rules in addition to the rules in those templates.

Note Refer to [“Using Capabilities, Templates and Rules”](#) on page 107 for more information.

Finally, you can create volumes by specifying user templates that you have set up with the required redundancy, fault tolerance, or performance capabilities for the applications that you run at your site. See [“Creating and Modifying User Templates”](#) on page 101 for more information.

Creating Volumes by Specifying Capabilities

A capability is a high-level description of a volume, for example, `DataMirroring`, `Striping` or `PrefabricatedRaid5`. ISP automatically selects a suitable template from those that provide the desired capability. As such, this is the most abstract way of creating volumes using `vxvoladm` as it requires the least specification by you. You can customize a capability by specifying values for any variable parameters that it defines.

For a list of predefined capabilities that are supported, see [“Capabilities”](#) on page 152. The following sections provide some examples of creating volumes with these capabilities.

Creating a Mirrored Volume

The following command creates a 1-gigabyte volume with the default number of 2 mirrors:

```
# vxvoladm -g mydg make mir2vol 1g capability='DataMirroring' \
  init=active
```

The `init=active` attribute makes the volume immediately available for use without attempting to synchronize its empty plexes.

The following command creates a 1-gigabyte volume with 3 mirrors:

```
# vxvoladm -g mydg make mir3vol 1g \
  capability='DataMirroring(nmirs=3)' init=active
```

Creating a Mirrored Volume with Mirrors on Separate Enclosures

The following command creates a 2-gigabyte mirrored volume with 2 mirrors, and with the mirrors located on separate enclosures:

```
# vxvoladm -g mydg make strpvol 2g capability='DataMirroring,\
  MirrorsOnSeparateComponents'
```

Such a volume tolerates the failure of one enclosure and provides greater reliability. Such a capability can be combined with multipathing to provide resilience against the failure of one of the paths to an enclosure:

```
# vxvoladm -g mydg make strpvol 2g capability='DataMirroring,\
MirrorsOnSeparateComponents,MultipathingThroughMultiplePaths'
```

Creating a Striped Volume

The following command creates a 2-gigabyte striped volume with 10 columns:

```
# vxvoladm -g mydg make strpvol 2g capability='Striping(ncols=10)'
```

Creating a Mirrored-Stripe Volume with Mirrors on Separate Controllers

The following command creates a 2-gigabyte mirrored-stripe volume with 8 columns, and with the mirrors located on separate controllers:

```
# vxvoladm -g mydg make strpvol 2g \
capability='DataMirrorStripe(ncols=8),\
MirrorsOnSeparateComponents(component="Controller")'
```

Creating a Striped-Mirror Volume from Prefabricated Mirrors

The following command creates a 10-gigabyte striped-mirror volume with 8 columns, and which uses prefabricated mirrors that are exported by an array to form each column:

```
# vxvoladm -g mydg make strpvol 2g capability='Striping(ncols=8),\
PrefabricatedDataMirroring'
```

Creating a RAID-5 Volume with a RAID-5 Log

The following command creates a 1-gigabyte RAID-5 volume with 8 columns and a RAID-5 log that has 2 redundant copies:

```
# vxvoladm -g mydg make r5vol 2g \
capability='Raid5Capability(ncols=8),Raid5LogMirroring(nlogs=2)'
```



Creating Volumes by Specifying Capabilities and Rules

You can specify storage selection and layout rules in addition to capabilities when creating volumes. This allows you to select explicitly which storage can and cannot be used for certain volumes. For example, you might do this to ensure that volumes are created on storage with certain performance or reliability that is implemented in an array's hardware.

Refer to “[Rules](#)” on page 115 for details of the different types of rule and their usage.

Creating a RAID-5 Volume on Prefabricated Storage

The following command creates a 10-gigabyte volume on a prefabricated RAID-5 disk that is exported from an array made by a specified vendor:

```
# vxvoladm -g mydg make perfr5vol 10g \  
  capability='PrefabricatedRaid5' \  
  rules='confineto "VendorName"="ACME"'
```

Creating a Mirrored Volume on Enclosures in Separate Locations

The following command creates a mirrored volume that tolerates the failure of a single enclosure, where each enclosure is in a different room. This avoids single point of failure and ensures greater reliability.

```
# vxvoladm -g mydg make mirvol 10g capability='DataMirroring' \  
  rules='separateby "Room","Enclosure"'
```

Note In this example, it is assumed that values for the user-defined attribute `Room` have been assigned to each enclosure.

Creating a Striped Volume Excluding Certain Disks

The following command creates a striped volume on storage other than that in `Room1` and certain disks in enclosure, `Enc1`:

```
# vxvoladm -g mydg make strvol 1g capability='Striping(ncols=4)' \  
  rules='exclude allof("Room"="Room1","DeviceName"="Enc1_1",\  
  "DeviceName"="Enc1_2")'
```


Creating Volumes by Specifying Templates

Volumes can be created by specifying templates instead of capabilities. The following example demonstrates how to create a mirrored volume using a template:

```
# vxvoladm -g mydg make mirvol 1g volume_template=DataMirroring
```

Note If you specify templates when creating a volume, you must ensure that these templates are self-sufficient, and that they do not depend on templates that are not specified on the command line. This applies to all cases where templates are named by themselves, or in combination with a mixture of capabilities and rules.

A template can refer to other templates in following ways:

- ◆ It can be an extension of another template.
- ◆ It can apply another template.
- ◆ It can require or inherit a capability that is provided by another template.

If one or more of these conditions apply, ISP may not be able to use the given templates and volume creation may fail. To view the details of a template, use the following command:

```
# vxtemplate [-g diskgroup] print template=template_name
```

Examine the definitions of the `extends`, `inherits`, `requires` and `apply` fields to see the other templates on which the specified template depends. See “[Volume Templates](#)” on page 110 for more information about these fields.

For example, the following command fails because of a template dependency:

```
# vxvoladm -g mydg make myvol 1g volume_template=PrefabricatedRaid5
VxVM vxvoladm ERROR V-61-49872-28 Template PrefabricatedRaid5 is
not valid for the operation. Either the template itself is invalid
or one or more of the related templates/capabilities are not in the
scope.
```

The `vxtemplate` command is then run to examine the definition of the `PrefabricatedRaid5` volume template:

```
# vxtemplate -g mydg print template=PrefabricatedRaid5
volume_template PrefabricatedRaid5 {
    provides PrefabricatedRaid5
    rules {
        apply ArrayProductId
        confineto "Parity" ="1"
    }
};
```



The `apply` rule in the listing shows that the `PrefabricatedRaid5` template depends on the `ArrayProductId` template. If the `ArrayProductId` template does not depend on any other templates, the `vxvoladm make` command should be modified to list `ArrayProductId` in addition to `PrefabricatedRaid5`:

```
# vxvoladm -g mydg make myvol 1g \  
  volume_template=PrefabricatedRaid5,ArrayProductId
```

Creating Volumes by Specifying Templates and Rules

The following command creates a striped volume using a template, and specifies a rule to ensure that storage is allocated only from a single enclosure in a specified location:

```
# vxvoladm -g mydg make strvol 1g \  
  volume_template='Striping' \  
  rules='confineto eachof("Enclosure","Room"="Room2")'
```

Note If you use a volume template to create a volume, and do not specify any capabilities, the values of all the variables that are used in the volume template are taken from the default values defined in the capability. An error is returned if such a variable does not have a default value.

Creating Volumes by Specifying Templates and Capabilities

If you specify templates in addition to capabilities when creating a volume, this restricts ISP to choosing from the specified templates.

The following example shows how to specify both capabilities and templates:

```
# vxvoladm [-g diskgroup] make volume length \  
  capability='capability[,capability...]' \  
  volume_template=template[,template...]
```

If you specify rules in addition to capabilities and templates, these rules are applied after ISP has selected the templates that satisfy the required capabilities.

Creating Volumes by Specifying User Templates

Once you have set them up, user templates provide the simplest way of creating volumes for use with the applications that you run. For example, you can configure user templates that ensure that volumes that you create to store database tables all share the same reliability and performance capabilities, and that they are allocated from a restricted set of storage. The following example shows how you might use a user template to create a volume for a database table:

```
# vxvoladm -g dbdg make Customers 15g user_template=DBTable
```

Creating Multiple Volumes as a Volume Group

If you choose to create volumes individually, allocation may eventually fail when the available storage is exhausted. The `-M` option to the `vxvoladm` command allows you to create several volumes at the same time while making the most efficient use of the available storage resources. ISP automatically chooses the best way to allocate storage to the volumes. A set of multiple volumes that are created by this method is referred to as a *volume group*.

For convenience, it is easiest to define one or more volume groups in a definition file, and have `vxvoladm` read this file to create the volumes as shown here:

```
# vxvoladm -M make < filename
```

For a description of the syntax of a volume group definition, see [“Volume Group Definition Syntax”](#) on page 165.

A sample definition might contain the following `volumegroup` entry:

```
volumegroup {
  diskgroup "mydg"
  rules {
    separateby "Enclosure"
    exclude "Enclosure"="ENC1"
  }
  volume "mirvol1" 10g {
    capability 'DataMirroring(nmirs=2)'
  }
  volume "mirvol2" 10g {
    capability 'DataMirroring(nmirs=2)'
  }
  volume "mirvol3" 10g {
    capability 'DataMirroring(nmirs=2)'
  }
};
```

This specifies three 10-gigabyte mirrored volumes in the disk group, `mydg`, with the data mirrors placed on separate enclosures, but excluding enclosure, `ENC1`.

The next sample definition specifies a prefabricated striped volume on storage that is restricted to the location `Room1`, and a volume that is mirrored across controllers in the disk group `testdg`. In addition, the rules for the volume group specify that the volumes are to be created on separate enclosures, and that storage may only be allocated on disks from a given vendor.

```
volumegroup {
  diskgroup "testdg"
  rules {
    separateby "Enclosure"
```



```

        confineto "VendorName"="ACME"
    }
    volume "strpvol" 10g {
        rules {
            confineto "Room=Room1"
        }
        capability 'PrefabricatedStriping'
    }
    volume "mirdvol" 1g {
        rules {
            separateby "Controller"
        }
        capability 'DataMirroring(nmirs=2)'
    }
};

```

Creating a Volume for Use with Snapshots and DRL

If the dirty region logging (DRL) or instant snapshot features are going to be used with an application volume, a version 20 data change object (DCO) and DCO volume must be associated with the volume.

If you want to create a volume of which you can take instant snapshots, the `InstantSnapShottable` capability or template must be specified (unless this capability is already implied by another capability or template):

```

# vxvoladm -g mydg make mir3vol 1g \
  capability='DataMirroring(nmirs=3),InstantSnapshottable' \
  init=active

```

By default, a data change object (DCO) and DCO volume with a single plex are associated with a volume to enable the instant snapshot capability. To increase the redundancy of the DCO volume, specify the `DCOLogMirroring` capability as shown here:

```

# vxvoladm -g mydg make mir3vol 1g \
  capability='DataMirroring(nmirs=3),InstantSnapshottable,\
  DCOLogMirroring(nlogs=3)' init=active

```

In this example, the same degree of redundancy is created for the DCO volume as for the data volume.

The DCO and DCO volume that are added by the `InstantSnapShottable` capability also provide the dirty region logging (DRL) capability that speeds recovery of mirrored volumes after a system crash. To enable DRL, specify either the attribute `drl=on` for full DRL, or `drl=sequential` for sequential DRL (used with volumes containing database replay logs). By default, DRL is disabled (`drl=off`). For example, the following command enables DRL for the volume, `mir3vol`, that is being created:

```
# vxvoladm -g mydg make mir3vol 1g \  
  capability='DataMirroring(nmirs=3),InstantSnapshottable' \  
  drl=on init=active
```





Administering Application Volumes

4

This chapter describes how to perform maintenance tasks on volumes that you have created using VERITAS Intelligent Storage Provisioning (ISP). This includes resizing and changing the capabilities of volumes without taking them offline.

The operations in this chapter use the `vxvoladm` command. For full details, see the `vxvoladm(1M)` manual page.

For details of how to display information about volumes, monitor and control tasks, and using the `vxresize` command to resize a volume and an underlying file system, see the “Administering Volumes” chapter of the *VERITAS Volume Manager Administrator’s Guide*.

Resizing Volumes Online

Increasing or decreasing the size of a volume is an operation that can be performed while a volume is online. The following `vxvoladm` operations are available for resizing a volume:

- ◆ `growto` — Increase volume size to a specified length.
- ◆ `growby` — Increase volume size by a specified length.
- ◆ `shrinkto` — Reduce volume size to a specified length.
- ◆ `shrinkby` — Reduce volume size by a specified length.

You can specify the length argument in sectors, kilobytes, megabytes, gigabytes or as a percentage by adding the unit of measure as a suffix (`s`, `m`, `k`, `g`, `%`) to the length value. If no unit is specified, sectors are assumed.

Caution If you use `vxvoladm` to resize a volume, do not shrink it below the size of the file system that is located on it. If you do not shrink the file system first, you risk unrecoverable data loss. If you have a VxFS file system, shrink the file system first, and then shrink the volume. Other file systems may require you to back up



your data so that you can later recreate the file system and restore its data. Alternatively, you can use the `vxresize` command to resize both the volume and its file system where this is supported.

Note If you use the `vxvoladm` command to resize application volumes of type `fsgen` or `raid5`, you must specify the `-f` (force) option to the command. You must also specify the `-f` option if growing a volume would violate any rules.

Determining the Maximum Size of a Volume

You can use the following command to determine by how much you can grow a volume using the available storage:

```
# vxvoladm [-g diskgroup] maxgrow volume [attributes...]
```

You can use storage specification attributes with this command to restrict the storage that is taken into consideration by the calculation. For example, the following command specifies that any JBOD storage may be used to resize volume, `vol02`:

```
# vxvoladm -g mydg maxgrow vol02 \  
use_storage='allof("Enclosure"="Disk")'
```

Increasing the Size of a Volume to a Specified Length

The following command grows a volume to a specified length:

```
# vxvoladm [-g diskgroup] [-f] growto volume length [attributes...]
```

You can use storage specification attributes with this command to restrict the storage that is used to grow a volume. For example, the following command expands the volume `vol1` to 10 gigabytes, but excludes storage on controller `c1` from being allocated:

```
# vxvoladm -g mydg growto vol1 10g \  
use_storage='noneof("Controller"="c1")'
```

This operation fails if the new length specified is smaller than the current size of the volume.

Increasing the Size of a Volume by a Specified Amount

The following command grows a volume by a specified amount:

```
# vxvoladm [-g diskgroup] [-f] growby volume length [attributes...]
```

For example, the following command grows the volume `vol1` by 1 gigabyte by allocating contiguous storage:

```
# vxvoladm -g mydg growby vol1 1g layout=contig
```

The setting `layout=contig` allows only contiguous regions of disk to be used for plexes or columns. By default, the length of a volume is increased by first extending existing subdisks in the volume if possible, and then by adding and associating new subdisks. This default behavior corresponds to the attribute setting `layout=noconfig`.

Reducing the Size of a Volume to a Specified Length

The following command reduces the length of a volume:

```
# vxvoladm [-g diskgroup] [-f] shrinkto volume length \  
[attributes...]
```

For example, the following command shrinks the volume `vol1` to 5 gigabytes:

```
# vxvoladm -g mydg shrinkto vol1 5g
```

This operation fails if the new length specified is larger than the current size of the volume.

Reducing the Size of a Volume by a Specified Amount

The following command reduces the length of a volume by a specified amount:

```
# vxvoladm [-g diskgroup] [-f] shrinkby volume length \  
[attributes...]
```

For example, the following command shrinks the volume `vol101` by 500 megabytes:

```
# vxvoladm -g mydg shrinkby vol1 500m
```



Growing and Shrinking Multiple Volumes

If the `-M` option is specified to the `vxvoladm` command, multiple volumes can be resized in the same operation. For convenience, it is easiest to define the volumes that are to be resized in a file, and then have `vxvoladm` read this file to resize the volumes as shown in this example:

```
# vxvoladm -M growby < filename
```

Each line of input defines the disk group, volume and length parameters for the resize and has the following format:

```
diskgroup dgroupname volume volume_name length
```

When used in scripts, the input may conveniently be taken from a “here document” as shown in this example:

```
vxvoladm -M shrinkto <<!!
diskgroup mydg volume vol01 10g
diskgroup mydg volume vol02 12g
!!
```

Preparing a Volume for DRL and Snapshot Operations

To prepare an application volume for dirty region logging (DRL) and instant snapshot operations, a data change object (DCO) and DCO volume must be associated with the volume.

Note The procedure in this section describes how to add a version 20 DCO and DCO volume to an application volume that you previously created in a disk group with a version number of 110 or greater. If you are creating a new volume in a disk group with a version number of 110 or greater, you can specify the co-creation of a DCO and DCO volume and enable DRL as described in [“Creating a Volume for Use with Snapshots and DRL”](#) on page 50.

You may need an additional license to use the DRL and FastResync features.

Use the following command to add a version 20 DCO and DCO volume to an existing volume:

```
# vxvoladm [-g diskgroup] [-p storage_pool] add log volume \
[nlog=number] logtype=dco [regionsize=size] \
[drl=yes|no|sequential]
```

The `nlog` attribute specifies the number of DCO plexes that are created in the DCO volume. It is recommended that you configure as many DCO plexes as there are data plexes in the volume. For example, specify `nlog=3` for a volume with 3 data plexes.

The value of the `regionsize` attribute specifies the size of the tracked regions in the volume. A write to a region is tracked by setting a bit in the change map. The default value is 64k (64KB). A smaller value requires more disk space for the change maps, but the finer granularity provides faster resynchronization.

To enable DRL logging on the volume, specify `drl=yes`. If sequential DRL is required, specify `drl=sequential`.

You can also specify `vxvoladm`-style storage attributes to define the disks that can and/or cannot be used for the plexes of the DCO volume.

Removing Support for DRL and Snapshots from a Volume

To remove support for DRL and instant snapshots from a volume, use the following command to remove the DCO and DCO volume that are associated with the volume:

```
# vxvoladm [-g diskgroup] [-p storage_pool] removeall log volume \
  logtype=dco
```

Note This command fails if the volume is part of a snapshot hierarchy.

Evacuating a Volume

If you need to remove or disable a disk, you must first move any data off the disk by evacuating it. Similarly, if the whole or parts of a volume are configured on disks that are needed for other purposes, or which are not optimal or appropriate for use by the volume, you can evacuate these.

To evacuate certain disks on which a volume is configured, use either of the following commands to specify these:

```
# vxvoladm [-g diskgroup] [-b] evacuate disk volume \
  !dmname ... [use_storage=rule[,...]] [attributes...]
# vxvoladm [-g diskgroup] [-b] evacuate disk volume \
  evac_storage=rule[,...] [use_storage=rule[,...]] \
  [attributes...]
```

The disk media names of the disks that are to be evacuated are specified as `!dmname` where `dmname` is a disk media name. Alternatively, you can also use the storage specification attribute, `evac_storage`, to specify rules for evacuating currently used storage. The `-b` option may be specified to run the evacuation as a background task. ISP allocates suitable storage according the `autogrow` policy of the storage pool, or you can use the storage specification attribute, `use_storage`, to specify rules for allocating new storage.



For example, the following command evacuates disks `mydg01` and `mydg02` on which volume, `vol01`, is configured, and specifies disks `mydg03` and `mydg04` as destination disks:

```
# vxvoladm -g mydg evacuate disk vol01 !mydg01 !mydg02 \  
use_storage='allof("DM"="mydg03", "DM"="mydg04")'
```

Not only disks can be evacuated. You can also specify subdisks, columns, logs, mirrors or entire volumes to be evacuated. In these cases, you can use the `evac_storage` attribute to specify which storage is to be evacuated. In the following example, all columns of the volume are evacuated that have disks on controller `c1`:

```
# vxvoladm -g mydg evacuate column vol01 \  
evac_storage='Controller="c1"'
```

The next example evacuates any disks in columns 0 or 1 that lie on controller `c2`:

```
# vxvoladm -g mydg evacuate column vol01 column=0,1 \  
evac_storage='Controller="c1"'
```

This command specifies that both columns 0 and 1 are to be evacuated to disks on controller `c2`:

```
# vxvoladm -g mydg evacuate column vol01 column=0,1 \  
use_storage='Controller="c2"'
```

In the final example, volume data is evacuated from subdisks that are connected to controller `c1` to disks on any other controller:

```
# vxvoladm -g mydg evacuate subdisk vol01 \  
evac_storage='allof("Controller"="c1")' \  
use_storage='noneof("Controller"="c1")'
```

If the specified volume is currently enabled, the data in enabled plexes and their component enabled plexes is moved without interrupting the availability of the volume and without changing its redundancy. Subdisks that are within detached plexes, disabled plexes, detached logs, or RAID-5 subdisks are moved without any attempt to recover the data.

If the specified volume is not currently enabled, stale or offline plexes are moved without recovery. The evacuation fails if a non-enabled volume contains other subdisks that need to be moved.

Removing a Volume

Once a volume is no longer required, you can use the following command to delete it and make its storage available for re-use:

```
# vxvoladm [-g diskgroup] remove volume volume
```

For example, the following command removes the volume, `vol11`:

```
# vxvoladm -g mydg remove volume vol11
```

Performing Online Relayout on a Volume

ISP does not support online relayout of an application volume in the same way as when the `vxassist relayout` command is used on a traditional volume. ISP can perform relayout internally if this is necessary to preserve the intent of a volume, or to support operations such as changing the number of mirrors, columns or logs that are associated with a volume. However, you should note that such operations may destroy the intent of a volume by changing its desired data redundancy or performance capabilities.

The nearest equivalent in ISP to the online relayout operation is capability transformation. This changes the capabilities of a volume in a controlled fashion, and preserves the size of the volume but not its intent. This operation is discussed in the following section. Subsequent sections describe how to add or remove mirrors, columns or logs to or from a volume, how to stop and reverse transformation and relayout operations, and how to verify that the intent of a volume has been preserved.

Transforming the Capabilities of a Volume Online

To change the capabilities of an existing volume online, use the `vxvoladm transform` command as shown here:

```
# vxvoladm [-g diskgroup] [-b] transform volume [attributes...]
```

If specified, the `-b` option performs the transformation in the background.

For example, the following command changes the capability of the volume, `vol102`, to `DataMirroring` with 4 mirrors:

```
# vxvoladm -g mydg -b transform vol102 \  
  capability='DataMirroring (nmirs=4)'
```



The next example adds the InstantSnapShottable and DCOLogMirroring capabilities to enable the use of instant snapshots with a mirrored volume:

```
# vxvoladm -g mydg -b transform mir3vol \  
  capability='DataMirroring(nmirs=3),InstantSnapShottable,\  
  DCOLogMirroring(nlogs=3)'
```

Adding Mirrors to a Volume

To add mirrors to an existing volume, use the following command:

```
# vxvoladm [-g diskgroup] [-b] add mirror volume \  
  [nmirrors=number] [attributes...]
```

By default, one mirror is added. You can use the `nmirrors` attribute to specify the number of mirrors to add. If specified, the `-b` option performs the synchronization of the new mirrors in the background. You can also use storage attributes to specify the storage to be used for the mirrors. For example, the following command adds a mirror to the volume, `mirvol1`, using disk `mydg01`:

```
# vxvoladm -g mydg -b add mirror mirvol1 \  
  use_storage='DM="mydg01"'
```

Removing Mirrors from a Volume

To remove mirrors from a volume, use the following command:

```
# vxvoladm [-g diskgroup] [-f] remove mirror volume \  
  [nmirrors=number] [attributes...]
```

By default, one mirror is removed. You can use the `nmirrors` attribute to specify the number of mirrors to remove. You can use storage attributes to specify the storage to be removed. For example, the following example removes the mirror on the disk `mydg01`, from the volume `mirvol1`:

```
# vxvoladm -g mydg remove mirror mirvol1 \  
  remove_storage='DM="mydg01"'
```

Note If you use the `vxvoladm` command to remove mirrors, you must specify the `-f` (force) option to the command if the operation would violate any rules. For example, the rules may imply that a volume must have minimum number of mirrors of a particular kind.

Adding Columns to a Volume

To add columns to a striped or RAID-5 volume, use the following command:

```
# vxvoladm [-g diskgroup] [-b] add column volume ncols=number \
  [tmplen=length] [attributes...]
```

The `ncols` attribute specifies the number of columns to add. You can use storage attributes to specify the storage to be used for the columns. If specified, the `-b` option adds the columns in the background.

Note This operation creates a temporary 2-way mirror volume that requires at least two disks, and therefore twice as much disk space as the size of the temporary volume. The size of the temporary volume is based on the size of the volume that is being changed. If required, you can use the `tmplen` attribute to specify the size of the temporary volume.

For example, the following command adds a column to the volume, `strpvoll`, using disk `enc1_5`:

```
# vxvoladm -g mydg -b add column strpvoll ncols=1 \
  use_storage=' "DeviceName"="enc1_5"'
```

Removing Columns from a Volume

To remove columns from a striped or RAID-5 volume, use the following command:

```
# vxvoladm [-g diskgroup] [-b] [-f] remove column volume \
  [ncols=number] [tmplen=length]
```

The `ncols` attribute specifies the number of columns to remove. If specified, the `-b` option removes the columns in the background.

Note This operation creates a temporary 2-way mirror volume that requires at least two disks, and therefore twice as much disk space as the size of the temporary volume. The size of the temporary volume is based on the size of the volume that is being changed. If required, you can use the `tmplen` attribute to specify the size of the temporary volume.

For example, the following command removes a column from the volume, `strpvoll`:

```
# vxvoladm -g mydg -b remove column strpvoll ncols=1
```



Note If you use the `vxvoladm` command to remove columns, you must specify the `-f` (force) option to the command if the operation would violate any rules. For example, the rules may imply that a volume must have minimum number of columns of a particular kind.

Changing the Stripe Unit Size of Volumes

To change the stripe unit size of a striped or RAID-5 volume, use the following command:

```
# vxvoladm [-g diskgroup] [-b] setstwidth volume stripeunit=size \  
[tmplen=length] [attributes...]
```

If specified, the `-b` option changes the stripe width in the background.

Note This operation creates a temporary 2-way mirror volume that requires at least two disks, and therefore twice as much disk space as the size of the temporary volume. The size of the temporary volume is based on the size of the volume that is being changed. If required, you can use the `tmplen` attribute to specify the size of the temporary volume.

For example, the following command changes the stripe unit size of the volume `vol1` to 32KB:

```
# vxvoladm -g mydg -b setstwidth vol1 stripeunit=32k
```

Adding Logs to a Volume

To add logs to a volume, use the following command:

```
# vxvoladm [-g diskgroup] [-b] add log volume logtype=type \  
[nlogs=number] [loglen=length] [attributes...]
```

The supported log types are `dco` and `raid5`. Adding a data change object (DCO) and DCO plex to a volume also allows the use of instant snapshots and dirty region logging (DRL) with the volume.

By default, one log or a DCO with one plex is added. You can use the `nlogs` attribute to specify the number of logs or DCO plexes to add. The `loglen` attribute can be used to specify the size of a RAID-5 log or a DCO volume. If the volume already contains such a log or DCO volume, this attribute is ignored. For a DCO volume, ISP may round up the length to make room for the maps that are required. For a RAID-5 log, a minimum size of three times the full stripe width is imposed, and the length is rounded up to a integral multiple of the full stripe width.

You can use storage attributes to specify the storage to be used for the logs. For example, the following command adds a DCO plex to the volume, `mirvol1`, using disk `enc1_7`:

```
# vxvoladm -g mydg -b add log mirvol1 logtype=dco \
  use_storage=' "DeviceName"="enc1_7"'
```

Removing Logs from a Volume

To remove logs from a volume, use the following command:

```
# vxvoladm [-g diskgroup] [-f] remove log volume [nlogs=number] \
  logtype=type [attributes...]
```

The supported log types are `dco` and `raid5`. By default, one RAID-5 log or one plex of a DCO volume is removed. You can use the `nlogs` attribute to specify the number of logs or DCO plexes to remove. You can use storage attributes to specify the storage to be removed. In the following example, a DCO plex on the disk `mydg11` is removed from the volume `mirvol1`:

```
# vxvoladm -g mydg remove log mirvol1 logtype=dco \
  remove_storage=' "DM"="mydg11"'
```

To remove all logs of a particular type from a volume, use the following command:

```
# vxvoladm [-g diskgroup] removeall log volume logtype=type
```

Note If you use the `vxvoladm` command to remove logs, you must specify the `-f` (force) option to the command if the operation would violate any rules. For example, the rules may imply that a volume must have minimum number of logs of a particular kind. You must also specify the `-f` option when removing a DCO that is in use by DRL configured on a volume.

Monitoring and Controlling ISP Tasks

ISP performs management of objects (such as subdisks, plexes, and volumes). Once these objects have been created, VxVM can start performing I/O with them.

The `vxvoladmtask` command is provided to allow you to manage tasks (*ISP tasks*) that are involved in the creation of objects by ISP. The traditional `vxtask` command allows you to manage tasks that involve VxVM performing I/O with volumes.

For example, if you create a 2-way mirrored volume in the background, ISP creates an allocation task whose progress you can monitor using the `vxvoladmtask monitor` command. When ISP has allocated storage for the volume, it lays out the volume on that



storage and then starts the volume. At this point, VxVM takes over control of I/O, and it begins to initialize the volume by synchronizing its plexes. To view the progress of this synchronization, you would use the `vxtask monitor` command.

The following command lists all current ISP tasks:

```
# vxvoladmtask list
```

This command monitors the progress of an ISP task, specified by its task tag:

```
# vxvoladmtask monitor task_tag
```

If necessary, you can use this command to stop an ISP task:

```
# vxvoladmtask abort task_tag
```

For more information about the `vxvoladmtask` command, see the `vxvoladmtask(1M)` manual page.

For information about the `vxtask` command, see the “Monitoring and Controlling Tasks” section in the “Administering Volumes” chapter of the *VERITAS Volume Manager Administrator’s Guide*, and the `vxtask(1M)` manual page.

Reversing Volume Transformations

If a volume transformation, which was invoked using the `vxvoladm transform` command, is in progress, you can use the `vxvoladm transformreverse` command to stop and reverse the transformation:

```
# vxvoladm [-g diskgroup] transformreverse volume
```

This command can also be used to reverse the following operations on mirrored-stripe volumes:

- ◆ Adding a column to a mirrored-stripe volume (`vxvoladm add column`).
- ◆ Removing a column from a mirrored-stripe volume (`vxvoladm remove column`).
- ◆ Changing the stripe width of a mirrored-stripe volume (`vxvoladm setstwidth`).

For `add/remove column` and `setstwidth` operations on striped, striped-mirror and RAID-5 volumes, use the following procedure to stop and reverse the layout:

1. Enter the following command to discover the task tag of the operation that you want to reverse:

```
# vxtask list
```

2. Use the task tag with this form of the `vxtask` command to stop the operation:

```
# vxtask abort task_tag
```

3. Finally, use the `vxrelayout` command to revert the volume to its former layout:

```
# vxrelayout [-g diskgroup] reverse volume
```

Note When mirrors are added or removed, ISP does not use the `relayout` or `transform` operations internally. After adding a mirror to a volume, VxVM starts synchronizing the new plexes from the existing plexes. In this case, the reverse operation can be performed by removing the newly added plexes. To reverse the removal of a mirror, a new plex must be added, and time allowed for it to be brought into synchronization with the volume.

Verifying the Intent of a Volume

To verify whether the application volumes in a disk group conform to the template rules, user-defined rules, volume group rules and storage pool rules that were used to create them, use the following command:

```
# vxvoladm -g diskgroup verify
```

To verify the intent of all application volumes in all disk groups, use this form of the command:

```
# vxvoladm -a verify
```

Displaying the Rules Associated with Objects

You can use the following command to display the rules that are associated with disk groups, storage pools, plexes and volumes:

```
# vxvoladm [-g diskgroup] printintent [object_name ...]
```

If no objects are named as arguments, the command displays the rules that are associated with the disk group.





VERITAS Volume Manager (VxVM) provides the capability for taking an image of a volume at a given point in time. Such an image is referred to as a *volume snapshot*.

Instant volume snapshots allow you to make backup copies of your volumes online with minimal interruption to users. You can then use the backup copies to restore data that has been lost due to disk failure, software errors or human mistakes, or to create replica volumes for the purposes of report generation, application development, or testing.

Two kinds of instant volume snapshots are supported for use with application volumes created by VERITAS Intelligent Storage Provisioning (ISP):

- ◆ Full-sized instant snapshots require an empty volume to be prepared for use as the snapshot volume as described in [“Creating a Volume for Use as a Full-Sized Instant Snapshot”](#) on page 70. The length of this volume must be the same as that of the volume whose snapshot is being taken. A snapshot volume can be created in either a data pool or in a clone pool. It must be created in a clone pool if you want to move it to a separate disk group. See [“Preparing Storage Pools for Full-Sized Instant Snapshots”](#) on page 69 for details.
- ◆ Space-optimized instant snapshots require less space than a full-sized instant snapshot but they cannot be dissociated from their original volume nor can they be moved into a different disk group. A space-optimized snapshot uses a storage pool or cache, which can be shared by one or more other space-optimized snapshots. You must set up the cache and the space-optimized snapshot volume in advance of creating any space-optimized snapshots, as described in [“Creating a Shared Cache Volume and Preparing Space-Optimized Snapshots”](#) on page 71.

The creation and administration of instant snapshots is described in [“Creating Instant Snapshots”](#) on page 75 and in subsequent sections. For details of how to use volume snapshots to implement off-host online backup, see [“Implementing Off-Host Processing Solutions”](#) on page 88.



Note A volume snapshot represents the data that exists in a volume at a given point in time. As such, VxVM does not have any knowledge of data that is cached by the overlying file system, or by applications such as databases that have files open in the file system. If the `fsngen` volume usage type is set on a volume that contains a VERITAS File System (VxFS), intent logging of the file system metadata ensures the internal consistency of the file system that is backed up. For other file system types, depending on the intent logging capabilities of the file system, there may be inconsistencies between in-memory data and the data in the snapshot image.

For databases, a suitable mechanism must additionally be used to ensure the integrity of tablespace data when the volume snapshot is taken. The facility to temporarily suspend file system I/O is provided by most modern database software. For ordinary files in a file system, which may be open to a wide variety of different applications, there may be no way to ensure the complete integrity of the file data other than by shutting down the applications and temporarily unmounting the file system. In many cases, it may only be important to ensure the integrity of file data that is not in active use at the time that you take the snapshot.

Traditional third-mirror break-off snapshots cannot be taken of application volumes that have been created by ISP.

Most VxVM commands require superuser or equivalent privileges.

For more information about instant volume snapshot features, see the chapter “Understanding VERITAS Volume Manager” in the *VERITAS Volume Manager Administrator’s Guide*.

Full details of how to recover from failures of instant snapshot commands may be found in the “Recovery from Failure of Instant Snapshot Operations” chapter of the *VERITAS Volume Manager Troubleshooting Guide*.

Preparing Storage Pools for Full-Sized Instant Snapshots

Assuming that you have already set up a data storage pool in a disk group using the procedure given in [“Creating a Storage Pool”](#) on page 34, you can create one or more clone storage pools in the same disk group by using the same procedure. You may choose to use different types of disks or templates with a clone storage pool than you set up for the data storage pool.

For example, the following commands set up a data and clone storage pool in the disk group, `tt dg`, from storage pool definitions:

```
# vxpool -g tt dg create tt dt pool \
  pooldefinition=prefab_mirrored_volumes
# vxpool -g tt dg create tt cl pool pooldefinition=mirrored_volumes
```

The data storage pool, `tt dt pool`, is configured with templates that support the creation of volumes on mirrored disks that are prefabricated in hardware. The templates that are installed for the clone storage pool, `tt cl pool`, support mirrored volumes that may be created using software. Having set up the storage pools, they can be populated with initialized disks as described in [“Adding Disks to a Storage Pool”](#) on page 37.

Several storage pool sets are provided (see [“Storage Pool Sets”](#) on page 162) for setting up data and clone storage pools within a disk group. To set up a data and clone storage pool using one of these defined sets, use the following command:

```
# vxpool [-g diskgroup] organize storage_pool_set
```

For example, to set up a data storage pool that supports mirrored volumes and a clone storage pool that supports striped snapshots in the disk group, `my dg`, you could use this command:

```
# vxpool -g my dg organize mirrored_data_striped_clones
```

This command assigns default names for the storage pools. These names are based on the definition names. If required you can rename these storage pools as described in [“Renaming a Storage Pool”](#) on page 40.



Creating a Volume for Use as a Full-Sized Instant Snapshot

If you want to create a full-sized instant snapshot for an original volume, you can use an empty volume with the required capability, and with the same length and region size as the original volume.

To create an empty volume for use by a full-sized instant snapshot:

1. Use the `vxprint` command on the original volume to find the required size for the snapshot volume.

```
# LEN=`vxprint [-g diskgroup] -F%len volume`
```

Note The command shown in this and subsequent steps assumes that you are using a Bourne-type shell such as `sh`, `ksh` or `bash`. You may need to modify the command for other shells such as `csh` or `tcsh`.

2. Use the `vxvoladm` command to create a volume, *snapvol*, of the required size and redundancy:

```
# vxvoladm [-g diskgroup] [-p storage_pool] make snapvol $LEN \  
  [storage_specification ...] [attribute ...] type=snapshot \  
  [regionsize=size] init=active
```

The attribute `regionsize` specifies the minimum size of each chunk (or region) of a volume whose contents are tracked for changes. The region size must be a power of 2, and be greater than or equal to 16KB. A smaller value requires more disk space for the change maps, but the finer granularity provides faster resynchronization. The default region size is 64k (64KB).

Note If the region size of a space-optimized snapshot differs from the region size of the cache, this can degrade the system's performance compared to the case where the region sizes are the same.

The `init=active` attribute is specified to make the volume available immediately.

The following example creates a 10-gigabyte mirrored volume, `ttsnpvol`, in the clone storage pool, `ttclpool`:

```
# vxvoladm -g ttdg -p ttclpool make ttsnpvol 10g \  
  capability='DataMirroring(nmirs=2)' type=snapshot init=active
```


Creating a Shared Cache Volume and Preparing Space-Optimized Snapshots

If you need to create several space-optimized instant snapshots for the volumes in a disk group, you may find it more convenient to create a single shared cache volume in the disk group rather than a separate cache volume for each snapshot.

To create a shared cache volume and prepare any space-optimized snapshots:

1. Decide on the following characteristics that you want to allocate to the cache volume:
 - ◆ The size of the cache volume should be sufficient to record changes to the parent volumes during the interval between snapshot refreshes. A suggested value is 10% of the total size of the parent volumes for a refresh interval of 24 hours.
 - ◆ If redundancy is a desired characteristic of the cache volume, it should be mirrored. This increases the space required by the cache volume in proportion to the number of mirrors that it has.
 - ◆ If the cache volume is mirrored, space is required on at least as many disks as it has mirrors. These disks should not be shared with the disks used for the parent volumes. The disks should also be chosen to avoid impacting I/O performance for critical volumes, or hindering disk group split and join operations.
2. Having decided on its characteristics, use the `vxvoladm` command to create the cache volume:

```
# vxvoladm [-g diskgroup] [-p storage_pool] make cachevol size \
  [storage_specification ...] [attribute ...] [regionsize size] \
  type=cachevolume
```

The attribute `regionsize` specifies the minimum size of each chunk (or region) of a volume whose contents are tracked for changes. The region size must be a power of 2, and be greater than or equal to 16KB. A smaller value requires more disk space for the change maps, but the finer granularity provides faster resynchronization. The default region size is 64k (64KB).

The following example creates a 1GB mirrored cache volume, `cachevol`, in the clone storage pool, `myclpool`, within the disk group, `mydg`:

```
# vxvoladm -g mydg -p myclpool make mycache 1g \
  rules="mirror 2" type=cachevolume
```

3. Once the cache volume has been created, use the following command to prepare each space-optimized snapshot that uses the cache volume:

```
# vxvoladm [-g diskgroup] [-p storage_pool] make sovol srcvol_len \
  [storage_specification ...] [attribute ...] type=snapshot \
  cachevolume=cachevol init=active
```



Note The *srcvol_len* argument specifies the length of the source volume for which the snapshot is being prepared. This value defines the logical size of the snapshot. The actual amount of storage that the snapshot requires is less than this, and is limited by the size of the cache volume.

For example, this command creates a space-optimized snapshot volume that uses the cache volume, *mycache*:

```
# vxvoladm -g mydg -p myclpool make mysovol 10g type=snapshot \
  cachevolume=mycache
```

Note The argument *10g* is the size of the source volume for which the snapshot *mysovol* is being prepared.

Once created, such a volume is ready for use to take a space-optimized instant snapshot.

Alternatively, you can use the following command to create a cache volume and prepare the space-optimized snapshot volumes in a single operation:

```
# vxvoladm -M make <<!!
  volumegroup {
    diskgroup "diskgroup"
    volume "cachevol" cache_size {
      type cachevolume
      [storage_specification]
      [regionsize size]
    }
    volume "sovol1" vol1_size {
      init active
      cachevolume "cachevol"
    }
    volume "sovol2" vol2_size {
      init active
      cachevolume "cachevol"
    }
  }
  .
  .
  .
};
!!
```

Note Because of its complexity, it is recommended that you run this command as a script.

For the examples given earlier in this section, the combined form of the command would be:

```
# vxvoladm -M make <<!!
  volumegroup {
    diskgroup "mydg"
    volume "mycache" 1g {
      type cachevolume
      capability 'DataMirroring(nmirrors=2)'
    }
    volume "mysovol" 10g {
      init active
      cachevolume "cachevol"
    }
  }
};
!!
```

Tuning the autogrow Attributes

The `highwatermark`, `autogrowby` and `maxautogrow` attributes determine how the VxVM cache daemon (`vxcached`) maintains the cache if the `autogrow` feature has been enabled and `vxcached` is running:

- ◆ When cache usage reaches the high watermark value, `highwatermark` (default value is 90 percent), `vxcached` grows the size of the cache volume by the value of `autogrowby` (default value is 20% of the size of the cache volume in blocks). The new required cache size cannot exceed the value of `maxautogrow` (default value is twice the size of the cache volume in blocks).
- ◆ When cache usage reaches the high watermark value, and the new required cache size would exceed the value of `maxautogrow`, `vxcached` deletes the oldest snapshot in the cache. If there are several snapshots with the same age, the largest of these is deleted.

If the `autogrow` feature has been disabled:

- ◆ When cache usage reaches the high watermark value, `vxcached` deletes the oldest snapshot in the cache. If there are several snapshots with the same age, the largest of these is deleted. If there is only a single snapshot, this snapshot is detached and marked as invalid.

Note The `vxcached` daemon does not remove snapshots that are currently open, and it does not remove the last or only snapshot in the cache.

If the cache space becomes exhausted, the snapshot is detached and marked as invalid. If this happens, the snapshot is unrecoverable and must be removed. Enabling the `autogrow` feature on the cache helps to avoid this situation occurring. However, for very



small caches (of the order of a few megabytes), it is possible for the cache to become exhausted before the system has time to respond and grow the cache. In such cases, either increase the size of the cache manually as described in “[Growing and Shrinking a Cache](#)” on page 74, or use the `vxcache set` command to reduce the value of `highwatermark` for the cache object, as shown in this example:

```
# vxcache -g mydg set highwatermark=60 cobjmydg
```

You can use the `maxautogrow` attribute to limit the maximum size to which a cache can grow. To estimate this size, consider how much the contents of each source volume are likely to change between snapshot refreshes, and allow some additional space for contingency.

If necessary, you can use the `vxcache set` command to change other `autogrow` attribute values for a cache. See the `vxcache(1M)` manual page for details.

Caution Ensure that the cache is sufficiently large, and that the `autogrow` attributes are configured correctly for your needs.

Growing and Shrinking a Cache

You can use the `vxcache` command to increase the size of the cache volume that is associated with a cache object:

```
# vxcache [-g diskgroup] growcacheto cache_object size
```

For example, to increase the size of the cache volume associated with the cache, `mycache`, to 2GB, use the following command:

```
# vxcache -g mydg growcacheto mycache 2g
```

To grow a cache by a specified amount, use the following form of the command:

```
# vxcache [-g diskgroup] growcacheby cache_object size
```

For example, to increase the size of the cache, `mycache`, by 1GB, you would use the following command:

```
# vxcache -g mydg growcacheby mycache 1g
```

You can similarly use the `shrinkcacheby` and `shrinkcacheto` operations to reduce the size of a cache. See the `vxcache(1M)` manual page for more information.

Removing a Cache

To remove a cache completely, including the cache object, its cache volume and all space-optimized snapshots that use the cache:

1. Run the following command to find out the names of the top-level snapshot volumes that are configured on the cache object:

```
# vxprint -g diskgroup -vne \  
"v_plex.pl_subdisk.sd_dm_name ~ /cache_object/"
```

where *cache_object* is the name of the cache object.

2. Remove all the top-level snapshots and their dependent snapshots (this can be done with a single command):

```
# vxedit -g diskgroup -r rm snapvol ...
```

where *snapvol* is the name of a top-level snapshot volume.

3. Stop the cache object:

```
# vxcache -g diskgroup stop cache_object
```

4. Finally, remove the cache object and its cache volume:

```
# vxedit -g diskgroup -r rm cache_object
```

Creating Instant Snapshots

Note Instant snapshots of ISP application volumes in a disk group's data pool are best created in clone pools that are also associated with the same disk group. A snapshot of a snapshot does not have to be in the same clone pool as its parent.

Volume sets can be used in place of volumes with the following `vxsnap` operations on instant snapshots: `addmir`, `dis`, `make`, `prepare`, `reattach`, `refresh`, `restore`, `rmmir`, `split`, `syncpause`, `syncresume`, `syncstart`, `syncstop`, `syncwait`, and `unprepare`. A snapshot of a volume set must itself be a volume set. A full-sized instant snapshot of a volume set can be created using a prepared volume set. You cannot use the `nmirrors` or `plex` attributes to specify that existing plexes are to be broken off. See the chapter "Creating and Administering Volume Sets" in the *VERITAS Volume Manager Administrator's Guide* for more information on creating volume sets.

VxVM allows you to make instant snapshots of volumes by using the `vxsnap` command.



A plex in a full-sized instant snapshot requires as much space as the original volume. If you instead make a space-optimized instant snapshot of a volume, this only requires enough storage to record the original contents of the parent volume as they are changed during the life of the snapshot.

The recommended approach to performing volume backup from the command line, or from a script, is to use the `vxsnap` command. The `vxsnap prepare` and `make` tasks allow you to back up volumes online with minimal disruption to users.

The `vxsnap prepare` step creates a DCO and DCO volume and associates this with the volume. It also enables Persistent FastResync on the volume.

The `vxsnap make` step creates an instant snapshot that is immediately available for making a backup. After the snapshot has been taken, read requests for data in the original volume are satisfied by reading either from a non-updated region of the original volume, or from the copy of the original contents of an updated region that have been recorded by the snapshot.

Note Synchronization of a full-sized instant snapshot from the original volume is enabled by default. If you specify the `syncing=no` attribute to `vxsnap make`, this disables synchronization, and the contents of the instant snapshot are unlikely ever to become fully synchronized with the contents of the original volume at the point in time that the snapshot was taken. If you wish to move an instant snapshot volume to another disk group for export to another machine for off-host processing, or to turn it into an independent volume, you must ensure that the snapshot volume has been completely synchronized.

You can immediately retake a full-sized or space-optimized instant snapshot at any time by using the `vxsnap refresh` command. If a fully synchronized instant snapshot is required, you must wait for the new resynchronization to complete.

To back up a volume with the `vxsnap` command, use the following procedure:

1. If you intend to take a space-optimized instant snapshot of the volume, you must first set up a shared cache volume in the same disk group as the volume. This cache object for this cache volume can be maintained by using the `vxcache` command.

For both full-sized and space-optimized instant snapshots, you must also create a volume for use as the snapshot volume. This volume must have the same region size as that of the volume for which the snapshot is being created. In addition, a volume that is created for use as a full-sized instant snapshot must be the same size as the volume for which the snapshot is being created.

See [“Creating a Shared Cache Volume and Preparing Space-Optimized Snapshots”](#) on page 71 for details of how to set up a shared cache volume, and how to prepare space-optimized snapshots that share this cache.

See “[Creating a Volume for Use as a Full-Sized Instant Snapshot](#)” on page 70 for details of how to prepare a volume for use as a full-sized instant snapshot.

Note If you intend to split the clone pool that contains snapshots into separate disk groups (for example, to perform off-host processing), the clone pool must only contain fully synchronized full-sized instant snapshots (which do not require a cache volume). You cannot split off a clone pool that contains either a cache volume or space-optimized instant snapshots.

2. Use the following commands on the primary host to see if the volume is associated with a version 20 data change object (DCO) and DCO volume that allow instant snapshots and Persistent FastResync to be used with the volume, and to check that FastResync is enabled on the volume:

```
# vxprint -g diskgroup -F%instant volume
# vxprint -g diskgroup -F%fastresync volume
```

If both these commands return a value of on, the volume can be used for instant snapshot operations.

To prepare a volume for instant snapshots, use the following command:

```
# vxsnap [-g diskgroup] prepare volume [regionsize=size] \
  [ndcomirs=number] [alloc=storage_attributes]
```

Note It is only necessary to run this command on a volume if it does not already have a version 20 DCO volume.

For example, to prepare the volume, `myvol`, in the disk group, `mydg`, use the following command:

```
# vxsnap -g mydg prepare myvol regionsize=128k ndcomirs=2
```

This example creates a DCO object and redundant DCO volume with two plexes, and associates them with `myvol`. The region size is also increased to 128KB from the default size of 64KB. The region size must be a power of 2, and be greater than or equal to 16KB. A smaller value requires more disk space for the change maps, but the finer granularity provides faster resynchronization.

Note If you intend to create space-optimized instant snapshots that share a cache volume, the region size that you specify for the volume must be greater than or equal to any region size that you specify for the cache volume. Creation of space-optimized snapshots that use a shared cache fails if the region size of the volume is smaller than the region size of the cache.



If the region size of a space-optimized snapshot differs from the region size of the cache, this can degrade the system's performance compared to the case where the region sizes are the same.

3. Use the `vxsnap make` step to create an instant snapshot that is immediately available for making a backup. If you specify a name or size for a storage cache, a space-optimized snapshot is created that requires less space than does a full-sized instant snapshot volume.
- ❖ To create a full-sized instant snapshot, *snapvol*, use one of the following forms of the `vxsnap make` command:

```
# vxsnap [-g diskgroup] make source=volume/snapvol=snapvol\  
[/syncing=off]
```

Note The attributes for a snapshot are specified as a tuple. The `vxsnap make` command accepts multiple tuples; one for each snapshot that is being created. A tuple for a full-sized instant snapshot must contain a `source` attribute and a `snapvol` attribute. Each element of a tuple is separated from the next by a slash character (/). Tuples are separated by white space.

This command specifies an existing volume, *snapvol*, that is to be used as the snapshot volume. See “[Creating a Volume for Use as a Full-Sized Instant Snapshot](#)” on page 70 for details.

Background synchronization of the snapshot volume from its parent volume is enabled by default (equivalent to specifying the `syncing=on` attribute). If you do not want to move the snapshot into a separate disk group, or turn it into an independent volume, specify the `syncing=off` attribute to disable synchronization. This avoids unnecessary system overhead.

For example, to use the prepared volume, *snap1myvol*, as the snapshot for the volume, *myvol*, in the disk group, *mydg*, use the following command:

```
# vxsnap -g mydg make source=myvol/snapvol=snap1myvol
```

If you want to move a snapshot into a separate disk group, or to turn it into an independent volume, you must wait for its contents to be synchronized with those of its parent volume.

For example, to use the prepared volume, *snap2myvol*, as the snapshot for the volume, *myvol*, in the disk group, *mydg*, on the volume, use the following command:

```
# vxsnap -g mydg make source=myvol/snapvol=snap2myvol
```


You can use the `vxsnap syncwait` command to wait for the synchronization of the snapshot volume to be completed, as shown here:

```
# vxsnap [-g diskgroup] syncwait snapvol
```

For example, you would use the following command to wait for synchronization to finish on the snapshot volume, `snap2myvol`:

```
# vxsnap -g mydg syncwait snap2myvol
```

This command exits (with a return code of zero) when synchronization of the snapshot volume is complete. The snapshot volume may then be moved to another disk group or turned into an independent volume.

If required, you can use the following command to verify whether the `V_PFLAG_INCOMPLETE` flag is set on a volume:

```
# vxprint [-g diskgroup] -F%incomplete snapvol
```

This command returns the value `off` if synchronization of the volume, `snapvol`, is complete; otherwise, it returns the value `on`.

See “[Controlling Instant Snapshot Synchronization](#)” on page 87 for more information.

- ❖ To create a space-optimized instant snapshot, `snapvol`, that uses a prepared space-optimized snapshot:

```
# vxsnap [-g diskgroup] make source=vol/snapvol=snapvol
```

For example, to create the space-optimized instant snapshot of the volume, `myvol`, in the disk group, `mydg`, and the prepared snapshot, `snap3myvol`, enter the following command:

```
# vxsnap -g mydg make source=myvol/snapvol=snap3myvol
```

For details of how to create a shared cache object and prepare a snapshot that uses this cache, see “[Creating a Shared Cache Volume and Preparing Space-Optimized Snapshots](#)” on page 71.

4. Use `fsck` (or some utility appropriate for the application running on the volume) to clean the temporary volume’s contents. For example, you can use this command:


```
# fsck -F vxfs /dev/vx/rdisk/diskgroup/snapshot
```
5. If you require a backup of the data in the snapshot, use an appropriate utility or operating system command to copy the contents of the snapshot to tape, or to some other backup medium.



You have the following choices for what to do with an instant snapshot:

- ◆ Refresh the contents of the snapshot. This creates a new point-in-time image of the original volume ready for another backup. If synchronization was already in progress on the snapshot, this operation may result in large portions of the snapshot having to be resynchronized. See [“Refreshing an Instant Snapshot \(vxsnap refresh\)”](#) on page 82 for details.
- ◆ Restore the contents of the original volume from the snapshot volume. For full instant snapshot volumes, you can choose whether none, a subset, or all of the plexes of the snapshot volume are returned to the original volume as a result of the operation. A space-optimized instant snapshot always remains intact at the end of the operation. See [“Restoring a Volume from an Instant Snapshot \(vxsnap restore\)”](#) on page 84 for details.
- ◆ Dissociate the snapshot volume entirely from the original volume. This may be useful if you want to use the copy for other purposes such as testing or report generation. If desired, you can delete the dissociated volume. See [“Dissociating an Instant Snapshot \(vxsnap dis\)”](#) on page 84 for details.

Note For space-optimized instant snapshots, this operation is only useful if you then want to delete the snapshot altogether.

- ◆ If the snapshot is part of a snapshot hierarchy, you can also choose to split this hierarchy from its parent volumes. See [“Splitting an Instant Snapshot Hierarchy \(vxsnap split\)”](#) on page 85 for details.

Note This operation is not supported for space-optimized instant snapshots.



Creating Multiple Instant Snapshots

Note In these examples, all snapshot volumes and any cache volumes must be prepared in advance as described in “[Creating a Volume for Use as a Full-Sized Instant Snapshot](#)” on page 70 and “[Creating a Shared Cache Volume and Preparing Space-Optimized Snapshots](#)” on page 71.

To make it easier to create snapshots of several volumes at the same time, the `vxsnap` make command accepts multiple tuples that define the source and snapshot volumes names as their arguments. For example, to create three instant snapshots, each with the same redundancy, the following form of the command can be used:

```
# vxsnap [-g diskgroup] make \  
source=vol1/snapvol=snapvol1 \  
source=vol2/snapvol=snapvol2 \  
source=vol3/snapvol=snapvol3
```

The specified source volumes (`vol1`, `vol2` and so on) may be the same volume or different volumes.

If all the snapshots are to be space-optimized, the following form of the command can be used:

```
# vxsnap [-g diskgroup] make \  
source=vol1/snapvol=snapvol1 \  
source=vol2/snapvol=snapvol2 \  
source=vol3/snapvol=snapvol3
```

The `vxsnap` make command also allows the snapshots to be of different types as shown here:

```
# vxsnap [-g diskgroup] make \  
source=vol1/snapvol=snapvol1 \  
source=vol2/snapvol=snapvol2
```

In this example, `snapvol1` is a full-sized snapshot, and `snapvol2` is a space-optimized snapshot.



Adding a Snapshot to a Cascaded Snapshot Hierarchy

To create a snapshot and push it onto a snapshot hierarchy between the original volume and an existing snapshot volume, specify the name of the existing snapshot volume as the value of the `infrontof` attribute to the `vxsnap make` command. The following example, shows how to place the space-optimized snapshot, `thurs_bu`, of the volume, `dbvol`, in front of the earlier snapshot, `wed_bu`:

```
# vxsnap -g dbdg make source=dbvol/snapvol=thurs_bu/\
infrontof=wed_bu/cache=dbdgcache
```

Similarly, the next snapshot that is taken, `fri_bu`, is placed in front of `thurs_bu`:

```
# vxsnap -g dbdg make source=dbvol/snapvol=fri_bu/\
infrontof=thurs_bu/cache=dbdgcache
```

For more information on the application of cascaded snapshots, see the *VERITAS Volume Manager Administrator's Guide*.

Refreshing an Instant Snapshot (vxsnap refresh)

Refreshing an instant snapshot replaces it with another point-in-time copy of a parent volume. To refresh one or more snapshots and make them immediately available for use, use the following command:

```
# vxsnap [-g diskgroup] refresh snapvol [source=vol] \
[[snapvol2 source=vol2]...] [sync=yes|no]
```

If the source volume is not specified, the immediate parent of the snapshot is used. For full-sized instant snapshots, resynchronization is started by default. To disable resynchronization, specify the `syncing=no` attribute. This attribute is not supported for space-optimized snapshots.

Note The snapshot being refreshed must not be open to any application. For example, any file system configured on the volume must first be unmounted.

It is possible to refresh a volume from an unrelated volume provided that their sizes are compatible.

You can use the `vxsnap syncwait` command to wait for the synchronization of the snapshot volume to be completed, as shown here:

```
# vxsnap [-g diskgroup] syncwait snapvol
```

See “[Controlling Instant Snapshot Synchronization](#)” on page 87 for more information.

Attaching Plexes of an Instant Snapshot (`vxsnap reattach`)

Note Although this operation is named `reattach`, the plexes of an ISP snapshot volume could never have belonged to the parent volume. For this reason, the description below refers to the *attachment*, rather than the *reattachment*, of snapshot plexes.

This operation is not supported for space-optimized instant snapshots.

Using the following command, some or all plexes of an instant snapshot may be attached to the specified source volume, or to a source volume in the snapshot hierarchy above the snapshot volume:

```
# vxsnap -f [-g diskgroup] reattach snapvol source=vol \
  [nmirror=number]
```

Caution This operation requires the specification of the `-f` (force) option as it violates the intent of the source volume. After the `reattach` operation completes, it may not be possible to perform other operations such as resizing the volume or transforming the layout of the volume. To restore the intent of the volume and allow such operations to be performed, use the `vxplex displex` command to dissociate the attached snapshot plexes.

By default, all the plexes are attached, which results in the removal of the snapshot. If required, the number of plexes to be attached may be specified as the value assigned to the `nmirror` attribute.

Note The snapshot being reattached must not be open to any application. For example, any file system configured on the snapshot volume must first be unmounted.

Only the plexes of a snapshot volume that was set up using ISP may be attached.

If the snapshot volume and the source volume lie in different storage pools, the underlying disks of the snapshot volume are moved to the source volume's storage pool. However, if other objects in the snapshot volume's storage pool are also configured on these disks, the `reattach` command fails.

For example the following command attaches one plex from the snapshot volume, `snapmyvol`, to the volume, `myvol`:

```
# vxsnap -g mydg -f reattach snapmyvol source=myvol nmirror=1
```



Restoring a Volume from an Instant Snapshot (vxsnap restore)

On occasion, it may be desirable to reinstate the contents of a volume from a backup or modified replica within a snapshot volume. The following command may be used to restore a volume:

```
# vxsnap [-g diskgroup] restore [nmirrors=number] vol \  
[source=snapvol] [destroy=yes|no]
```

For a full instant snapshot, some or all of its plexes may be reattached to the parent volume or to a specified source volume in the snapshot hierarchy above the snapshot volume. If `destroy=yes` is specified, all the plexes of the snapshot are reattached and the snapshot volume is removed.

For a space-optimized instant snapshot, the cached data is used to restore the contents of the specified volume. The snapshot itself remains unchanged by the operation.

Note For this operation to succeed, the volume that is being restored and the snapshot volume must not be open to any application. For example, any file systems that are configured on either volume must first be unmounted.

It is not possible to restore a volume from an unrelated volume.

The `destroy` and `nmirror` attributes are not supported for space-optimized instant snapshots.

The following example demonstrates how to restore the volume, `myvol`, from the space-optimized snapshot, `snap3myvol`.

```
# vxsnap -g mydg restore myvol source=snap3myvol
```

Dissociating an Instant Snapshot (vxsnap dis)

The following command breaks the association between a snapshot volume, `snapvol`, and its parent volume, so that the snapshot may be used as an independent volume:

```
# vxsnap [-f] [-g diskgroup] dis snapvol
```

This operation fails if the snapshot, `snapvol`, has a snapshot hierarchy below it that contains unsynchronized snapshots. If this happens, the dependent snapshots must be fully synchronized from `snapvol`. When no dependent snapshots remain, `snapvol` may be dissociated. The snapshot hierarchy is then adopted by `snapvol`'s parent volume.

Note To be usable after dissociation, the snapshot volume and any snapshots in the hierarchy must have been fully synchronized. See "[Controlling Instant Snapshot Synchronization](#)" on page 87 for more information. In addition, you cannot

dissociate a snapshot if synchronization of any of the dependent snapshots in the hierarchy is incomplete. If an incomplete snapshot is dissociated, it is unusable and should be deleted as described in [“Removing an Instant Snapshot”](#) on page 85.

The following command dissociates the snapshot, `snap2myvol`, from its parent volume:

```
# vxsnap -g mydg dis snap2myvol
```

Note When applied to a volume set or to a component volume of a volume set, this operation can result in inconsistencies in the snapshot hierarchy in the case of a system crash or hardware failure. If the operation is applied to a volume set, the `-f` (force) option must be specified.

Removing an Instant Snapshot

When you have dissociated a full-sized instant snapshot, you can use the `vxvoladm` command to delete it altogether, as shown in this example:

```
# vxvoladm -g mydg remove volume snap2myvol
```

You can also use this command to remove a space-optimized instant snapshot from its cache. For details of how to remove a cache, see [“Removing a Cache”](#) on page 75.

Splitting an Instant Snapshot Hierarchy (`vxsnap split`)

Note This operation is not supported for space-optimized instant snapshots.

The following command breaks the association between a snapshot hierarchy that has the snapshot volume, `snapvol`, at its head, and its parent volume, so that the snapshot hierarchy may be used independently of the parent volume:

```
# vxsnap [-f] [-g diskgroup] split snapvol
```

Note The topmost snapshot volume in the hierarchy must have been fully synchronized for this command to succeed. Snapshots that are lower down in the hierarchy need not have been fully resynchronized. See [“Controlling Instant Snapshot Synchronization”](#) on page 87 for more information.

The following command splits the snapshot hierarchy under `snap2myvol` from its parent volume:

```
# vxsnap -g mydg split snap2myvol
```



Note When applied to a volume set or to a component volume of a volume set, this operation can result in inconsistencies in the snapshot hierarchy in the case of a system crash or hardware failure. If the operation is applied to a volume set, the `-f` (force) option must be specified.

Displaying Instant Snapshot Information (`vxsnap print`)

The `vxsnap print` command may be used to display information about the snapshots that are associated with a volume.

```
# vxsnap [-g diskgroup] print [vol]
```

This command shows the percentage progress of the synchronization of a snapshot or volume. If no volume is specified, information about the snapshots for all the volumes in a disk group is displayed.

The following example shows a volume, `vol1`, which has a full-sized snapshot, `snapvol1` whose contents have not been synchronized with `vol1`:

```
# vxsnap -g mydg print
```

NAME	SNAPOBJECT	TYPE	PARENT	SNAPSHOT	%DIRTY	%VALID
vol1	--	volume	--	--	--	100
	snapvol1_snp1	volume	--	snapvol1	1.30	--
snapvol1	vol1_snp1	volume	vol1	--	1.30	1.30

The `%DIRTY` value for `snapvol1` shows that its contents have changed by 1.30% when compared with the contents of `vol1`. As `snapvol1` has not been synchronized with `vol1`, the `%VALID` value is the same as the `%DIRTY` value. If the snapshot were partly synchronized, the `%VALID` value would lie between the `%DIRTY` value and 100%. If the snapshot were fully synchronized, the `%VALID` value would be 100%. The snapshot could then be made independent or moved into another disk group.

Controlling Instant Snapshot Synchronization

Note Synchronization of the contents of a snapshot with its original volume is not possible for space-optimized instant snapshots.

By default, synchronization is enabled for the `vxsnap refresh` and `restore` operation on instant snapshots. Otherwise, synchronization is disabled unless you specify the `sync=yes` attribute to the `vxsnap` command.

The following table shows the commands that are provided for controlling the synchronization manually.

Command	Description
<code>vxsnap [-g <i>diskgroup</i>] syncpause <i>vol</i></code>	Pause synchronization of a volume.
<code>vxsnap [-g <i>diskgroup</i>] syncresume <i>vol</i></code>	Resume synchronization of a volume.
<code>vxsnap [-b] [-g <i>diskgroup</i>] syncstart <i>vol</i></code>	Start synchronization of a volume. The <code>-b</code> option puts the operation in the background.
<code>vxsnap [-g <i>diskgroup</i>] syncstop <i>vol</i></code>	Stop synchronization of a volume.
<code>vxsnap [-g <i>diskgroup</i>] syncwait <i>vol</i></code>	Exit when synchronization of a volume is complete. An error is returned if <i>vol</i> is invalid (for example, it is a space-optimized snapshot), or if <i>vol</i> is not being synchronized.

Improving the Performance of Snapshot Synchronization

Two optional arguments to the `-o` option are provided to help optimize the performance of synchronization when using the `make`, `refresh`, `restore` and `syncstart` operations:

`iosize=size` Specifies the size of each I/O request that is used when synchronizing the regions of a volume. Specifying a larger size causes synchronization to complete sooner, but with greater impact on the performance of other processes that are accessing the volume. The default *size* of 1m (1MB) is suggested as the minimum value for high-performance array and controller hardware. The specified value is rounded to a multiple of the volume's region size.



`slow=iodelay` Specifies the delay in milliseconds between synchronizing successive sets of regions as specified by the value of `iosize`. This can be used to change the impact of synchronization on system performance. The default value of `iodelay` is 0 milliseconds (no delay). Increasing this value slows down synchronization, and reduces the competition for I/O bandwidth with other processes that may be accessing the volume.

Options may be combined as shown in the following examples:

```
# vxsnap -g mydg -o iosize=2m,slow=100 make \  
source=myvol/snapvol=snap2myvol/syncing=on  
  
# vxsnap -g mydg -o iosize=10m,slow=250 syncstart snap2myvol
```

Note These optional parameters only affect the synchronization of full-sized instant snapshots. They are not supported for space-optimized snapshots.

Implementing Off-Host Processing Solutions

By importing snapshot volumes on a lightly loaded host, CPU- and I/O-intensive operations for online backup and decision support do not degrade the performance of the primary host that is performing the main production activity (such as running a database). If the snapshot volumes are configured on disks that are attached to different host controllers than the disks in the primary volumes, it is possible to avoid contending with the primary host for I/O resources.

The following sections describe how you can apply off-host processing to implement regular online backup of a volume in a private disk group, and to set up a replica of a production database for decision support. Two applications are outlined in the following sections:

- ◆ [Implementing Off-Host Online Backup](#)
- ◆ [Implementing Decision Support](#)

These applications use the Persistent FastResync and disk group move, split and join features of VxVM in conjunction with full-sized instant volume snapshots. It is assumed that you have configured a data storage pool containing the application volumes, and a clone storage pool containing prepared empty volumes for any snapshots. You must also have associated a data change object (DCO) and DCO volume with all these volumes.

Implementing Off-Host Online Backup

This section describes a procedure for implementing off-host online backup for a volume in a private disk group. The intention is to present an outline of how to set up a regular backup cycle by combining the Persistent FastResync and disk group split and join features of VxVM. It is beyond the scope of this guide to describe how to configure a database to use this procedure, or how to perform the backup itself.

To back up a volume in a private disk group, use the following procedure.

1. Create a full-sized instant snapshot volume, *snapvol*, using the following command on the primary host:

```
# vxsnap -g volumedg make source=volume/snapvol=snapvol
```

This command uses the specified prepared snapshot volume, *snapvol*, to form the snapshot volume. (See “[Creating a Volume for Use as a Full-Sized Instant Snapshot](#)” on page 70 for details.)

If a database spans more than one volume, you can specify all the volumes and their snapshot volumes using one command, as shown in this example:

```
# vxsnap -g dbasedg make source=vol1/snapvol=snapvol1 \
  source=vol2/snapvol=snapvol2 \
  source=vol3/snapvol=snapvol3
```

Note This step sets up the snapshot volumes ready for the backup cycle, and starts tracking changes to the original volumes. When you are ready to make a backup, proceed to [step 2](#).

2. On the primary host, suspend updates to the volume that contains the database tables. The database may have a hot backup mode that allows you to do this by temporarily suspending writes to its tables.
3. On the primary host, refresh the plexes of the snapshot volume using the following command:

```
# vxsnap [-g diskgroup] refresh snapvol source=volume sync=yes
```

For a database, multiple snapshots can be refreshed in parallel, as shown in this example:

```
# vxsnap -g dbasedg refresh snapvol1 source=vol1 snapvol2 \
  source=vol2 snapvol3 source=vol3 sync=yes
```

4. On the primary host, if you temporarily suspended updates to the volume by a database in [step 2](#), release all the tables from hot backup mode.



5. The snapshot volume must be completely synchronized before you can move it into another disk group. You can use the `vxsnap syncwait snapvol` command to wait for the synchronization to complete as shown here:

```
# vxsnap -g volumedg syncwait snapvol
```

The `vxsnap syncwait` command exits with an exit code of zero when the snapshot volume has been synchronized with the parent volume.

If required, you can use the following command to verify whether the `V_PFLAG_INCOMPLETE` flag is set on a volume:

```
# vxprint [-g diskgroup] -F%incomplete snapvol
```

This command returns the value `off` if synchronization of the volume, `snapvol`, is complete; otherwise, it returns the value `on`.

6. On the primary host, use the following command to split the clone storage pool containing the snapshot volume into a separate disk group, `snapvoldg`, from the original disk group, `volumedg`:

```
# vxdg split volumedg snapvoldg clonepool
```

7. On the primary host, deport the snapshot volume's disk group using the following command:

```
# vxdg deport snapvoldg
```

8. On the OHP host where the backup is to be performed, use the following command to import the snapshot volume's disk group:

```
# vxdg import snapvoldg
```

9. The snapshot volume is initially disabled following the split. Use the following commands on the OHP host to recover and restart the snapshot volume:

```
# vxrecover -g snapvoldg -m snapvol
```

```
# vxvol -g snapvoldg start snapvol
```

10. On the OHP host, back up the snapshot volume. If you need to remount the file system in the volume to back it up, first run `fsck` on the volume. The following are sample commands for checking and mounting a file system:

```
# fsck -F vxfs /dev/vx/rdisk/snapvoldg/snapvol
```

```
# mount -F vxfs /dev/vx/dsk/snapvoldg/snapvol mount_point
```

Back up the file system at this point, and then use the following command to unmount it.

```
# umount mount_point
```

11. On the OHP host, use the following command to deport the snapshot volume's disk group:


```
# vxdbg deport snapvoldg
```
12. On the primary host, re-import the snapshot volume's disk group using the following command:


```
# vxdbg import snapvoldg
```
13. On the primary host, use the following command to rejoin the snapshot volume's disk group with the original volume's disk group:


```
# vxdbg join snapvoldg volumedg
```
14. The snapshot volume is initially disabled following the join. Use the following commands on the primary host to recover and restart the snapshot volume:


```
# vxrecover -g volumedg -m snapvol
# vxvol -g volumedg start snapvol
```

The contents of the snapshot volume are now ready to be refreshed.

Repeat steps 2 through 14 each time that you need to back up the volume.

Implementing Decision Support

This section describes a procedure for implementing off-host decision support for a volume in a private disk group. The intention is to present an outline of how to set up a replica database by combining the Persistent FastResync and disk group split and join features of VxVM. It is beyond the scope of this guide to describe how to configure a database to use this procedure.

To set up a replica database using the table files that are configured within a volume in a private disk group, use the following procedure.

1. Prepare the OHP host to receive the snapshot volume that contains the copy of the database tables. This may involve setting up private volumes to contain any redo logs, and configuring any files that are used to initialize the database.
2. Create a full-sized instant snapshot volume, *snapvol*, using the following command on the primary host:

```
# vxsnap -g volumedg make source=volume/snapvol=snapvol
```

This command uses the specified prepared snapshot volume, *snapvol*, to form the snapshot volume. (See [“Creating a Volume for Use as a Full-Sized Instant Snapshot”](#) on page 70 for details.)



If a database spans more than one volume, you can specify all the volumes and their snapshot volumes using one command, as shown in this example:

```
# vxsnap -g dbasedg make source=vol1/snapvol=snapvol1 \  
  source=vol2/snapvol=snapvol2 \  
  source=vol3/snapvol=snapvol3
```

Note This step sets up the snapshot volumes, and starts tracking changes to the original volumes. When you are ready to create a replica database, proceed to [step 3](#).

3. On the primary host, suspend updates to the volume that contains the database tables. The database may have a hot backup mode that allows you to do this by temporarily suspending writes to its tables.
4. On the primary host, refresh the plexes of the snapshot volume using the following command:

```
# vxsnap [-g diskgroup] refresh snapvol source=volume sync=yes
```

The `sync=yes` attribute starts a synchronization of the snapshot in the background.

For a database, multiple snapshots can be refreshed in parallel, as shown in this example:

```
# vxsnap -g dbasedg refresh snapvol1 source=vol1 snapvol2 \  
  source=vol2 snapvol3 source=vol3 sync=yes
```

5. On the primary host, if you temporarily suspended updates to the volume by a database in [step 3](#), release all the tables from hot backup mode.
6. The snapshot volume must be completely synchronized before you can move it into another disk group. You can use the `vxsnap syncwait` command to wait for the synchronization to complete as shown here:

```
# vxsnap -g volmedg syncwait snapvol
```

The `vxsnap syncwait` command exits with an exit code of zero when the snapshot volume has been synchronized with the parent volume.

If required, you can use the following command to verify whether the `V_PFLAG_INCOMPLETE` flag is set on a volume:

```
# vxprint [-g diskgroup] -F%incomplete snapvol
```

This command returns the value `off` if synchronization of the volume, *snapvol*, is complete; otherwise, it returns the value `on`.

7. On the primary host, use the following command to split the clone storage pool containing the snapshot volume into a separate disk group, *snapvoldg*, from the original disk group, *volumedg*:


```
# vxdg split volumedg snapvoldg clonepool
```
8. On the primary host, deport the snapshot volume's disk group using the following command:


```
# vxdg deport snapvoldg
```
9. On the OHP host where the replica database is to be set up, use the following command to import the snapshot volume's disk group:


```
# vxdg import snapvoldg
```
10. The snapshot volume is initially disabled following the split. Use the following commands on the OHP host to recover and restart the snapshot volume:


```
# vxrecover -g snapvoldg -m snapvol
# vxvol -g snapvoldg start snapvol
```
11. On the OHP host, check and mount the snapshot volume. The following are sample commands for checking and mounting a file system:


```
# fsck -F vxfs /dev/vx/rdisk/snapvoldg/snapvol
# mount -F vxfs /dev/vx/dsk/snapvoldg/snapvol mount_point
```
12. On the OHP host, use the appropriate database commands to recover and start the replica database for its decision support role.

When you want to resynchronize the snapshot volume's data with the primary database, you can refresh the snapshot plexes from the original volume as described below:

1. On the OHP host, shut down the replica database, and use the following command to unmount the snapshot volume:


```
# umount mount_point
```
2. On the OHP host, use the following command to deport the snapshot volume's disk group:


```
# vxdg deport snapvoldg
```
3. On the primary host, re-import the snapshot volume's disk group using the following command:


```
# vxdg import snapvoldg
```



4. On the primary host, use the following command to rejoin the snapshot volume's disk group with the original volume's disk group:

```
# vxvg join snapvoldg volumedg
```

5. The snapshot volume is initially disabled following the join. Use the following commands on the primary host to recover and restart the snapshot volume:

```
# vxrecover -g volumedg -m snapvol
```

```
# vxvol -g volumedg start snapvol
```

The contents of the snapshot volume are now ready to be refreshed.

You can then resume the procedure from [step 3](#) on page 92. The snapshot volume can be split from the disk group when synchronization is again complete.



Administering Volume Templates and Other Configuration Elements

6

The VERITAS Intelligent Storage Provisioning (ISP) feature creates volumes with a set of rules or capabilities. A volume template (or template for short) is a collection of rules that provide capabilities. ISP refers to templates when creating a volume, and selects an appropriate set of templates to use based on the requested capabilities.

ISP follows certain rules when selecting templates to match a requested set of capabilities. See “[Volume Templates](#)” on page 110 for more details. For a list of the standard templates that are provided by ISP, see “[Volume Templates](#)” on page 148.

The procedures in this chapter use the `vxtemplate` command. For full information about using this command, see the `vxtemplate(1M)` manual page.

Installing Volume Templates and Other Elements into the ISP Configuration Database

Storage pool, storage pool set, template set, template and capability definitions are referred to as *configuration elements*. A standard set of configuration elements are included in the Configuration Database that is installed with the ISP package (see “[ISP Configuration Elements](#)” on page 143). These configuration elements cover a broad range of uses, and should be sufficient for most applications. To make additional configuration elements available for use, they must be installed in the Configuration Database.

To install additional elements that are defined in a file, use the following command:

```
# vxtemplate -C -d element_defs_file install
```

You can select only to install selected elements from a file by naming them explicitly as shown here:

```
# vxtemplate -r -C -d my_templates install template=Reliability
```

The `-r` (recursive) option ensures that all capabilities and templates that are referred to by the `Reliability` template are also installed.



Installing Volume Templates and Other Elements into Storage Pools and Disk Groups

If you specify a template set, storage pool definition or a storage pool set definition when creating a storage pool, the required templates and capabilities are automatically associated with the storage pool and with its disk group. (See “[Creating a Storage Pool](#)” on page 34 for details.)

A storage pool's `selfsufficient` policy governs whether configuration elements can be installed automatically from the Configuration Database as required. If the policy is set to `host`, elements are available to the pool from the Configuration Database, from the disk group and from the pool itself. If the policy is set to `diskgroup`, the pool can install additional elements from the disk group, but not from the Configuration Database. A policy value of `pool` means that only elements that are installed in the pool can be used. If required, you can use the `vxtemplate` command to install templates, capabilities and template sets from the Configuration Database into disk groups and pools.

Template sets are convenient for installing many capabilities and templates in a single operation. The following example shows how to install all the capabilities and templates from the template set, `DataMirroring`, into a storage pool, `mypool`, and its disk group, `mydg`:

```
# vxtemplate -g mydg -p mypool install template_set=DataMirroring
```

This is equivalent to using this (very long) command:

```
# vxtemplate -r -g mydg -p mypool install \  
template=DataMirroring,ArrayProductId,\  
ConfineLogsToSimilarStorage,ConfineMirrorsToSimilarStorage,\  
DCOLogMirroring,InstantSnapshottable,LogsOnSeparateComponents,\  
MirrorsOnSeparateComponents
```



Listing and Printing Configuration Elements

Use the following command to list the templates and capabilities that are associated with a specified disk group and/or storage pool.

```
# vxtemplate [-g diskgroup] [-p pool] list
```

This command displays results similar to the following.

TY	NAME	STATE	AUTOINSTALL
vt	Mirroring	Active	0
vt	MirroringStriping	Active	0
vt	Raid5Template	Active	0
vt	Striping	Active	0
cp	ParityReliable	-	-
cp	PerformanceByStriping	-	-
cp	Reliability	-	-

Here the types vt and cp indicate volume template and capability definitions.

To print the details of these templates and capabilities, use this command:

```
# vxtemplate [-g diskgroup] [-p pool] print
```

You can print the details of only certain elements by specifying these as arguments to the command:

```
# vxtemplate [-g diskgroup] [-p pool] print [template=t1[,t2...]] \
[capability=c1[,c2...]] [template_set=ts1[,ts2...]] \
[storage_pool_set=ps1[,ps2...]] [pool_definition=pd1[,pd2...]]
```

For example, to print the definitions of the `Mirroring` and `Striping` volume templates that are associated with the storage pool, `mypool`, in the disk group, `mydg`, you would use this command:

```
# vxtemplate -g mydg -p mypool print template=Mirroring,Striping
```

The following command lists all the templates and capabilities that are available in the ISP Configuration Database on the system:

```
# vxtemplate -C list
```

The output from this command is similar to the following.

TY	NAME	STATE	AUTOINSTALL
vt	DataMirroring	-	-
vt	Raid5Volume	-	-
vt	Reliability	-	-
vt	Striping	-	-
cp	DataMirroring	-	-
cp	DataRedundancy	-	-
cp	Raid5LogMirroring	-	-
cp	Raid5Capability	-	-



```
cp Reliability - -
cp Striping - -
ts Raid5Templates - -
pd raid5_volumes - -
ps mirrored_data_striped_clones - -
.
.
.
```

Here the types `ts`, `pd` and `ps` indicate template set, storage pool and storage pool set definitions respectively.

To print the details of elements in the Configuration Database, use this command:

```
# vxtemplate -C print [template=t1[,t2...]] \
[capability=c1[,c2...]] [template_set=ts1[,ts2...]] \
[storage_pool_set=ps1[,ps2...]] [pool_definition=pd1[,pd2...]]
```

As for storage pools and disk groups, you can print the details of certain elements by specifying these as arguments to the command, for example:

```
# vxtemplate -C print template_set=DataMirroring,Raid5Templates
```

You can also use the `listcapabilities`, `listtemplates` and `listtemplatesets`, `listpooldefinitions`, and `listpoolsets` keywords of `vxtemplate` to list only the capabilities or templates that are associated with the specified disk group and/or storage pool. Similarly, the `printcapabilities`, `printtemplates` and `printtemplatesets`, `printpooldefinitions`, and `printpoolsets` keywords are used to print the element definitions in detail. For more information, see the `vxtemplate(1M)` manual page.

Deactivating and Reactivating Templates

By default, templates are activated when they are associated with a storage pool. You can run the `vxtemplate deactivate` command to prevent one or more templates from being used in the storage pool with which they have been associated:

```
# vxtemplate [-g diskgroup] [-p pool] deactivate \
template=template[,template...]
```

If the template is currently in use, ISP displays an error message.

You can reactivate templates by using the `vxtemplate activate` command:

```
# vxtemplate [-g diskgroup] [-p pool] activate \
template=template[,template...]
```



Renaming a Capability

To change the name of a capability that is associated with a disk group and/or storage pool, use the following command:

```
# vxtemplate [-g diskgroup] [-p pool] renamecapability \
  oldname newname
```

For example, you may want to change the name if you have modified the attributes of the capability for a particular disk group.

Renaming a Template

To change the name of a template that is associated with a disk group and/or storage pool, use the following command:

```
# vxtemplate [-g diskgroup] [-p pool] renametemplate \
  oldname newname
```

For example, you may want to change the name if you have modified a template for a particular disk group.

Removing Templates, Capabilities and Template Sets

To remove a template, capability or template set from a disk group and/or storage pool, or from the ISP Configuration Database, use the `vxtemplate uninstall` command. For example, the following command removes the definitions of the DataMirroring template and capability from the storage pool, `mypool`, in the disk group, `mydg`:

```
# vxtemplate -g mydg -p mypool uninstall template=DataMirroring \
  capability=DataMirroring
```

The following command similarly removes this template and capability from the ISP Configuration Database:

```
# vxtemplate -C uninstall template=DataMirroring \
  capability=DataMirroring
```





Creating and Modifying User Templates

7

When using VERITAS Intelligent Storage Provisioning (ISP) to create an application volume with a specified set of capabilities, you can usually enter values for the parameters that modify these capabilities. For example, you can select the degree of redundancy, fault tolerance, or performance that you require from the volume. For convenience in creating volumes, you can set up user templates to store commonly used sets of capabilities and parameter values. You can then specify the name of a user template instead of the name of a capability when using the `vxvoladm` command to create an application volume.

Format of User Templates

A user template consists of a list of capabilities and rules. Associated with each capability is a list of parameter-value pairs that define default parameter values for the capability. The format of a typical user template specification is shown here:

```
user_template usertmplt_tname {
  description "string"
  descriptionid id
  volume_templates template1, template2 ...
  capability capability1 {
    attribute_name:type = default_value
    ...
  }
  capability capability2 {
    attribute_name = default_value
    ...
  }
  ...
  rules {
    rule1
    rule2
    ...
  }
};
```

This definition has the following important components:



<code>usertmplt_name</code>	Defines the name of the user template, for example, <code>MyReliableReplication</code> , and <code>MySWSnapshot</code> .
<code>description</code>	Describes a user template in English.
<code>descriptionid</code>	References the message catalog where localized versions of the description may be found, and provides an index number for the description in the catalog.
<code>volume_templates</code>	Indicates the templates that can be used by the user template.
<code>capability</code>	Indicates the capabilities that are provided by volumes created from the user template.
<code>attribute_name</code>	Defines the name and value of a parameter.
<code>rules</code>	Specifies the start of the section that contains the rules for selecting and laying out storage, and which implement the capabilities that the user template provides. See “ Rules ” on page 115.

For a formal definition of `user_template` in the ISP language, see “[User Template](#)” on page 140.

For example, consider a capability named `HardwareReplication` that has two variable parameters that specify the source and the destination:

```
capability HardwareReplication {
    var source:string
    var destination:string
};
```

In addition, the capability named `Reliable`, provides reliability by creating a mirrored volume:

```
capability Reliable {
    var NMIRS:int
};
```

Rules can also be specified to user templates, as shown in these examples that could be used for creating application volumes for database tables and indexes:

```
user_template DB_Table {
    description "Makes mirrored volume for a database table"
    capability DataMirroring {
        NMIRS = 2
    }
    rules {
        confineto "VendorName"="EMC"
    }
};
```




```

user_template DB_Index {
  description "Makes high performance volume for a database index"
  capability Striping {
    NCOLS = 8
  }
  rules {
    confineto "VendorName"="EMC"
  }
};

```

The user template, `DB_Table`, can be used to create a mirrored volume with two plexes, but is restricted to using only EMC disks. Similarly, the user template, `DB_Index`, can be used to create a striped volume with eight columns, and is also restricted to using only EMC disks.

Creating User Templates

You can either create a user template by defining it directly from the command line, or by defining it in a configuration file. The first method is only suitable for very simple user templates. It is usually preferable to define your templates in a configuration file.

To create a user template directly from the command line, use the `vxusertemplate create` command as shown here:

```

# vxusertemplate create usertemplate_name \
  [description="string"] \
  [rules=rule1 [rule2 ]...] \
  [capability=capability1[(var1=value1[,var2=value2]...)]\
    [,capability2[(var1=value1[,var2=value2]...)]]...]

```

For example, the following command creates a user template named `RP_DB_Table` that has both Reliable and HighPerformance capabilities:

```

# vxusertemplate create RP_DB_Table \
  description="Makes reliable high performance volume \
  for database table"rules=confineto "VendorName"="EMC" \
  capability='DataMirroring(NMIRS=2),Striping(NCOLS=8)'

```

This command adds the user template to the global `usertemplates` file that is maintained by ISP.

Alternatively, you can create a configuration file that contains an equivalent user template, as shown in this sample listing:

```

user_template DB_Table {
  description "Makes mirrored volume for database table"
  capability DataMirroring {
    NMIRS = 2
  }
}

```



```
    }
    rules {
        confineto "VendorName"="EMC"
    }
};

user_template DB_Index {
    description "Makes high performance volume for database index"
    capability Striping {
        NCOLS = 8
    }
    rules {
        confineto "VendorName"="EMC"
    }
};
```

You can then use the `-d` option with `vxusertemplate create` command to add the user template in the configuration file to the global `usertemplates` file, as shown here:

```
# vxusertemplate -d config_file create
```

Using a User Template to Create an Application Volume

You can create an application volume using a user template by specifying the name of the user template in place of the name of a capability to the `vxvoladm make` command. For example, to create a 10GB application volume in the storage pool, `mypool`, using the user template, `RP_DB_Table`, you would use the following command:

```
# vxvoladm -g mydg -p mypool make myDBvol 10g \
  user_template='RP_DB_Table'
```

Note Unlike volume templates, you cannot specify parameter values for user templates on the command line.

Listing Currently Defined User Templates

Use the following command to list all the user templates that are currently defined in the global `usertemplates` file:

```
# vxusertemplate list
```

Printing User Template Definitions

Use the following command to print detailed information about one or more user templates that are currently defined in the global `usertemplates` file:

```
# vxusertemplate print usertemplate1 [usertemplate2 ...]
```

Deleting User Templates

To remove a user template definition from the global `usertemplates` file, use the following command:

```
# vxusertemplate delete usertemplate
```





VERITAS Intelligent Storage Provisioning (ISP) provides a structured and flexible rule-based declarative language for expressing how an application volume with a given set of characteristics is to be configured from the available storage. The language can be used to specify rules for allocating storage to the individual parts of a volume, such as mirrors, columns, logs and snapshots, as well to as an entire volume.

See the following sections in this chapter for more information:

- ◆ [Capabilities](#)
- ◆ [Volume Templates](#)
- ◆ [Rules](#)

See “[ISP Language Definition](#)” on page 129 for full details of the syntax of capabilities, rules and templates. Also see “[ISP Configuration Elements](#)” on page 143 for details of the basic capabilities and templates that are provided for use.

Capabilities

A capability, as expressed in the ISP language, is a description of what a volume is capable of doing. Each template is associated with one or more capabilities so that ISP can choose those templates that are suitable for use in allocating storage to volumes. A capability is interpreted by ISP as a tag.

The format of a typical capability definition is shown here:

```
capability cap_name {
  extends capname1, capname2, ...
  description text
  descriptionid id
  display_name name
  display_name_id catalogid, index
  var varname1:type {
    defaultvalue value
    description description
    descriptionid catalogid, index
  }
}
```



```
    var varname2:type {
        defaultvalue value
        description text
        descriptionid catalogid, index
    }
    ...
};
```

This definition has the following important components:

<i>cap_name</i>	Indicates the nature of the capability, for example, Reliable, Performant, Snapshot and EMCSnapshot.
<i>extends</i>	Indicates that the capability is derived from other named capabilities. See “Inheritance of Capabilities” on page 109 for more information.
<i>description</i>	Describes a capability or one of its variable parameters in English.
<i>descriptionid</i>	References the message catalog where localized versions of the description may be found, and provides an index number for the description in the catalog.
<i>display_name</i>	Defines the English name of the capability that is displayed in the VEA.
<i>display_name_id</i>	References the message catalog where localized versions of the display name may be found, and provides an index number for the display name in the catalog.
<i>var</i>	Defines a variable that may be specified as a parameter and its value to a capability. A template can use the variables in its rules section to provide the requested capability. Permitted variable types are int or string.
<i>defaultvalue</i>	Defines the default value of a capability’s parameter if no value is specified.

For a formal definition of capability in the ISP language, see [“Capability”](#) on page 132.

The following is a sample capability definition:

```
capability DataMirroring {
    display_name "Data Mirroring"
    display_name_id "{b84f1c64-1dd1-11b2-8b42-080020feef8b}", 3

    description "Volume has multiple copies of data."
    descriptionid "{b84f1c64-1dd1-11b2-8b42-080020feef8b}", 4

    extends DataRedundancy
    var nmirs:int {
        display_name "Number of data copies"
```

```

display_name_id "{b84f1c64-1dd1-11b2-8b42-080020feef8b}", 5

description "Specify the number of copies of data."
descriptionid "{b84f1c64-1dd1-11b2-8b42-080020feef8b}", 6

defaultvalue 2
}
};

```

Inheritance of Capabilities

The `extends` keyword in a capability definition allows a capability to inherit some of the properties of one or more *base* capabilities. This implies that such a *derived* capability has an “is a” relationship with these base capabilities. The following rules are applied by the inheritance mechanism:

- ◆ A derived capability inherits variables from all its base capabilities.
- ◆ A derived capability cannot define variables with the same name as any of the variables in any of its base capabilities.
- ◆ If a capability is derived from more than one base capability, none of the variable names in any of its base capabilities should be the same as a variable name in any other base capability.

The following sample capability definitions show how the `DataMirrorStripe` capability is derived from the more general `DataMirroring` and `Striping` capabilities:

```

capability DataMirrorStripe {
    extends DataMirroring, Striping
};

```

`DataMirrorStripe` also inherits the variables `nmirs` and `ncols` from the two capabilities that it extends.



Volume Templates

A volume template (or template for short) is a meaningful collection of rules that provides capabilities for volumes as defined by those rules, or by reference to other capabilities. ISP refers to templates when creating an application volume. It chooses an appropriate template to use based on the capabilities that you request for the volume, and allocates storage by following the rules that the template contains.

The format of a typical template specification is shown here:

```
volume_template template_name {
    extends templatel, template2, ...
    inherits capability5, capability6, ...
    provides capability1, capability2, ...
    requires capability3, capability4, ...
    description text
    descriptionid id
    group name
    rules {
        rule1
        rule2
        ...
    }
};
```

This definition has the following important components:

<i>template_name</i>	Indicates the nature of the volume that can be created by the template, for example, <i>DataMirroring</i> , <i>Raid5Volume</i> and <i>InstantSnapshottable</i> .
<i>extends</i>	Indicates that the template includes all the capabilities, rules and variables from the named templates. See “ extends ” on page 111 for more information.
<i>inherits</i>	Indicates that the template can inherit capabilities when required from those listed. See “ inherits ” on page 112 for more information.
<i>provides</i>	Indicates the capabilities that are provided by volumes created from the template. See “ provides ” on page 113 for more information.
<i>requires</i>	Indicates that the template can acquire rules when required from other templates that provide the specified capabilities. See “ requires ” on page 113 for more information.
<i>description</i>	Describes a template in English.
<i>descriptionid</i>	References the message catalog where localized versions of the description may be found, and provides an index number for the description in the catalog.

group	Indicates the name of the group to which application volumes created from this template belong.
rules	Specifies the start of the section that contains the rules for selecting and laying out storage, and which implement the capabilities that the template provides. The rules usually operate on the values that were specified for the arguments of the requested capabilities. See “Rules” on page 115 and “Compound Rules” on page 124 for more information.

The following sections describe the keywords in detail:

- ◆ [extends](#)
- ◆ [group](#)
- ◆ [inherits](#)
- ◆ [provides](#)
- ◆ [requires](#)
- ◆ [Rules](#)
- ◆ [Compound Rules](#)

For a formal definition of `volume_template` in the ISP language, see [“Volume Template”](#) on page 133.

extends

A template can derive some of its properties by extending one or more base templates as shown in this example:

```

volume_template DerivedTemplate {
    extends BaseTemplate
    rules {
        ...
    }
};

```

By extending template `BaseTemplate`, the template `DerivedTemplate`:

- ◆ Provides all capabilities that `BaseTemplate` provides (see [“provides”](#) on page 113).
- ◆ Requires all capabilities that `BaseTemplate` requires (see [“requires”](#) on page 113).
- ◆ Inherits all capabilities that `BaseTemplate` inherits (see [“inherits”](#) on page 112).
- ◆ Obtains and applies all the rules of `BaseTemplate`.
- ◆ Can use variables of all the capabilities that `BaseTemplate` provides.



Note `BaseTemplate` and `DerivedTemplate` cannot use different capabilities that have variables with the same name.

The derived template has an “is a” relationship with its base templates. The derived template can be used instead of any of its base templates.

The following example demonstrates the application of the `extends` keyword:

- ◆ Extend `ReliablePerformant` into the template `MyReliablePerformant`:

```
volume_template MyReliablePerformant {
    extends ReliablePerformant
    rules {
        ...
    }
};
```

group

This keyword specifies that all volumes allocated using this template are in the specified group. Rules in the storage pool apply to all groups, and specify relationships between groups. For example, a storage pool rule might specify that all groups are to be separated by enclosures. This would mean that all templates with different group tags must be placed in separate non-overlapping sets of enclosures. This keyword can also appear within a log clause. In this case, the specified group overrides any group specified in the template.

inherits

If a template specifies that it can inherit a capability, it provides that capability when required. Inheriting a capability is equivalent to the combination of requiring and providing a capability (see “[requires](#)” and “[provides](#)” on page 113).

The following example demonstrates the application of the `inherits` keyword:

- ◆ The following template definition:

```
volume_template ReliableSnapshot {
    requires Reliable
    provides Reliable, Snapshot
    rules {
        ...
    }
};
```

can be rewritten as:

```
volume_template ReliableSnapshot {
    inherits Reliable
    provides Snapshot
    rules {
        ...
    }
};
```

provides

A template provides one or more capabilities as defined by its rules, or by requiring capabilities (see “[requires](#)”). Any variables that are defined for the capability can be used by the template’s rules.

The following example demonstrates the application of the `provides` keyword:

- ◆ Define a template, `ReliableT`, that provides the `Reliable` capability, and which uses the `NMIRS` variable of the capability to set the number of mirrors:

```
volume_template ReliableT {
    provides Reliable
    rules {
        mirror NMIRS {
            ...
        }
    }
};
```

requires

If a template requires one or more capabilities, it can take the appropriate rules from any templates that provide those capabilities.

The `requires` keyword does not imply `provides` (see “[provides](#)”). Whenever, a template provides a capability by specifying that it requires it, it should be explicitly listed in a `provides` or `inherits` clause (see “[inherits](#)” on page 112).

The following example demonstrates the application of the `requires` keyword:

- ◆ Define a template, `MySnapshot`, that provides the `Snapshot` capability, and requires, but does not provide, the `Reliable` capability:

```
volume_template MySnapshot {
    requires Reliable
    provides Snapshot
    rules {
```



```
    ...  
  }  
};
```

This template picks up any templates that provide the `Reliable` capability, and merges their rules with its own rules. If the template were also required to provide the `Reliable` capability, the `inherits` keyword should be used as shown here:

```
volume_template MyReliableSnapshot {  
  inherits Reliable  
  provides Snapshot  
  rules {  
    ...  
  }  
};
```

This template provides the `Snapshot` capability through its own rules, and also provides the `Reliable` capability by using rules from other templates.

Note By allowing ISP to choose any template that provides the required capability, the `requires` keyword gives ISP more flexibility when allocating storage. This behavior is known as *dynamic inheritance*.

When choosing a template with a required capability, ISP gives preference to templates that provide only that capability. This behavior avoids giving unrelated capabilities to a volume.

When searching for a template with a required capability, ISP chooses only those templates that inherit or provide that capability.

When searching for a template with a required capability, ISP recursively chooses templates that provide all the required capabilities.

Rules

Rules specify the criteria for allocating storage, the criteria for laying out VxVM objects on storage, and the relationship between these objects. Rules can be classified as storage selection rules that define how to choose storage, or as storage layout rules that define how storage is to be used.

Note You can optionally precede any rule with the keyword `desired`. This modifier means that ISP tries to honor this rule, but it can discard it if the rule would cause the allocation to fail.

Storage Selection Rules

The following sections describe storage selection rules:

- ◆ `affinity`
- ◆ `confineto`
- ◆ `exclude`
- ◆ `multipath`
- ◆ `select`
- ◆ `separateby`
- ◆ `strong separateby`

See “[Compound Rules](#)” on page 124 for details of how to limit the scope of interpretation of rules to the components of an application volume, such as its plexes, columns and logs.

Multiple arguments to the `confineto`, `exclude` and `select` storage selection rules can be combined using the operators listed in “[Storage Selection Rule Operators](#)” on page 121. If an operator is not specified, ISP uses the default operator for the rule.

Note The `=`, `!=`, `<`, `<=`, `>` and `>=` comparative operators can be used with the `confineto`, `exclude` and `select` storage selection rules. However, the operand arguments to the `<`, `<=`, `>` and `>=` operators must be signed or unsigned integers that are capable of being represented by 64 or fewer bits. If the operands are character strings, real numbers, or are integers longer than 64 bits, the result of the comparison may be incorrect.



affinity

An `affinity` rule expresses attraction between VxVM objects. Objects that conform to this rule share as many attribute values as possible.

Note The `affinity` rule does not take any rule operators.

The following example demonstrates the application of `affinity` rules:

- ◆ Allocate storage from as few enclosures as possible:

```
desired affinity "Enclosure"
```

confineto

A `confineto` rule restricts a VxVM object, such as volume or mirror, to being configured from a specific set of LUNs. The scope of the rule determines the VxVM object for which the restrictions apply. When a `confineto` rule is used at the top level, it usually applies to the volume. Refer to [“Compound Rules”](#) on page 124 for details on confining a mirror, column or log to a set of LUNs.

Note Expressions involving `confineto` can use the `allof`, `anyof`, `eachof`, `noneof` and `oneof` operators to combine multiple arguments. By default, ISP applies the `eachof` operator. See [“Storage Selection Rule Operators”](#) on page 121 for more information.

The expression argument of a `confineto` rule usually consists of one or more LUN attributes that can be specified either with or without an accompanying value. The LUN attributes can be auto-discovered or user-defined. A value that is not quoted is interpreted as the name of a variable whose value is to be determined when a VxVM object is created.

The following examples demonstrate the application of `confineto` rules:

- ◆ Use storage having the same value for the user-defined attribute, `Room`:

```
confineto "Room"
```

- ◆ By default, the `eachof` operator is assumed for a `confineto` rule. The following rules, which specify that storage is only to be assigned from EMC LUNs or from LUNs that share the same value for the `Room` attribute, are equivalent:

```
confineto "Room", "VendorName"="EMC"  
confineto eachof("Room", "VendorName"="EMC")
```

- ◆ Use only EMC LUNs that have their `Room` attribute set to the value `Room1`:

```
confineto eachof("VendorName"="EMC", "Room"="Room1")
```

- ◆ Use only storage with `VendorName` set to the value of the variable `VENDOR_NAME`, and with `Room` set to the value of the variable `ROOM_NAME`:

```
confineto eachof ("VendorName"=VENDOR_NAME, "Room"=ROOM_NAME)
```

Note `VENDOR_NAME` and `ROOM_NAME` are variables that are defined in a capability. Their values are resolved when you enter values for the capability during the creation of a VxVM object.

- ◆ Create a volume using one or more LUNs from either or both of the enclosures `EMC1` and `EMC2`, and not from anywhere else:

```
confineto anyof ("Enclosure"="EMC1", "Enclosure"="EMC2")
```

Note When the `anyof` operator is used, ISP takes storage from the operands in the order that they are specified. In this example, ISP first attempts to select LUNs from the enclosure `EMC1`, and if this is not possible, it selects LUNs from the enclosure `EMC2`. If this also is not possible, ISP selects LUNs from both `EMC1` and `EMC2`.

- ◆ Use LUNs that originate either only from `EMC` or only from `Hitachi`:

```
confineto oneof ("VendorName"="EMC", "VendorName"="Hitachi")
```

Note When the `oneof` operator is used, ISP takes storage from the operands in the order that they are specified. In this example, ISP first attempts to select `EMC` LUNs, and if this is not possible, it selects `Hitachi` LUNs.

- ◆ Confine storage to be allocated from either `Room1` or from `Room2`. If storage is selected from `Room1`, `Hitachi` LUNs cannot be used. Similarly, if storage is selected from `Room2`, `EMC` LUNs cannot be used.

```
confineto
oneof (eachof ("Room"="Room1", noneof ("VendorName"="Hitachi")), \
      eachof ("Room"="Room2", noneof ("VendorName"="EMC")))
```

Note In this example, ISP first attempts to select LUNs from `Room1`, and if this is not possible, it selects LUNs from `Room2`.

- ◆ Do not use LUNs from `Room1` or LUNs from vendor `EMC`:

```
confineto noneof ("VendorName"="EMC", "Room"="Room1")
```

Note The `noneof` operator implies the logical union of its operands.



- ◆ Allocate storage from LUNs in Room1 and Room2:

```
confineto allof("Room"="Room1", "Room"="Room2")
```

Note In the absence of a specified operator, the `eachof` operator is assumed.

- ◆ Do not mix EMC LUNs with LUNs from other vendors when allocating storage:

```
confineto oneof("VendorName"="EMC", noneof("VendorName"="EMC"))
```

- ◆ Allocate storage only from LUNs that have a `Columns` attribute value greater than 1, and a `Parity` attribute value of 0:

```
confineto eachof("Columns">"1", "Parity"="0")
```

exclude

An `exclude` rule omits a set of LUNs from being allocated to a VxVM object.

Note Expressions involving `exclude` can only use the `allof` and `eachof` operators to combine multiple arguments. By default, ISP applies the `allof` operator. See [“Storage Selection Rule Operators”](#) on page 121 for more information.

The following examples demonstrate the application of `exclude` rules:

- ◆ The following rules, which prevent storage being assigned from EMC or Hitachi disks, are equivalent:

```
exclude "VendorName"="EMC", "VendorName"="Hitachi"  
exclude allof("VendorName"="EMC", "VendorName"="Hitachi")
```

- ◆ Do not use EMC LUNs from Room1:

```
exclude eachof("VendorName"="EMC", "Room"="Room1")
```

- ◆ Do not use disks with `VendorName` set to the value of the variable `VENDOR_NAME`:

```
exclude "VendorName"=VENDOR_NAME
```

Note `VENDOR_NAME` is a variable that is defined in a capability. Its value is resolved when the VxVM object is created.

- ◆ Exclude certain LUNs from the enclosure `Enclr1`:

```
exclude allof("DeviceName"="Enclr1_1", "DeviceName"="Enclr1_2")
```


multipath

A `multipath` rule specifies how tolerant a VxVM object is to the failure of a number of specified components. The rule defines how many paths a VxVM object should have available through each component.

Note The `multipath` rule does not take any rule operators.

The following examples demonstrate the application of `multipath` rules:

- ◆ Tolerate the failure of one controller:

```
multipath 2 "Controller"
```

- ◆ Tolerate the failure of one controller *and* one switch:

```
multipath 2 "Controller", 2 "Switch"
```

select

A `select` rule specifies which storage to use for creating VxVM objects. When used outside of a sub clause, this rule is applied to an entire volume.

Note Expressions involving `select` can use the `allof`, `anyof`, `eachof`, `noneof` and `oneof` operators to combine multiple arguments. By default, ISP applies the `anyof` operator. See [“Storage Selection Rule Operators”](#) on page 121 for more information.

The following examples demonstrate the application of `select` rules:

- ◆ The following rules, which try to allocate LUNs first from `Room1`, then from `Room2` if unsuccessful, and then from both locations, are equivalent:

```
select "Room"="Room1", "Room"="Room2"
select anyof("Room"="Room1", "Room"="Room2")
```

Note When the `anyof` operator is used, ISP takes storage from the operands in the order that they are specified.

- ◆ Use only EMC LUNs from `Room1`:

```
select eachof("VendorName"="EMC", "Room"="Room1")
```

Note Here the `eachof` operator is used rather than the `allof` operator. The `eachof` operator implies the logical intersection of its operands. The `allof` operator implies the logical union of its operands.

- ◆ Use the specified LUNs from an enclosure:

```
select "DeviceName"="Enclr1_1", "DeviceName"="Enclr1_2"
```



separateby

A `separateby` rule is used to describe separation between VxVM objects. This is typically used to define failure domains to provide greater reliability by avoiding a single point of failure. For example, a `separateby` rule can be used to define that the mirrors of a volume should not share a controller. This makes the volume resilient to the failure of a controller.

Note The `separateby` rule does not take any rule operators.

The following examples demonstrate the application of `separateby` rules:

- ◆ Allocate VxVM objects on separate enclosures:

```
separateby "Enclosure"
```

- ◆ Allocate VxVM objects so that each object tolerates the failure of one controller and also uses LUNs from different manufacturers:

```
separateby "VendorName", "Controller"
```

strong separateby

The `strong separateby` rule is a more restrictive form of `separateby` rule, which does not permit any sharing of attributes for the storage that is assigned to VxVM objects.

Note The `strong separateby` rule does not take any rule operators.

The following example demonstrates the application of the `strong separateby` rule:

- ◆ Allocate VxVM objects so that each object is configured on a totally independent set of spindles.

```
strong separateby "Spindles"
```

Storage Selection Rule Operators

The following table lists the operators that are provided for combining the `confine to`, `exclude` and `select` storage selection rules:

Operator	Description
<code>allof</code>	Select available storage that matches the union of all the operands.
<code>anyof</code>	Select available storage that matches any of the operands in the order that they are listed. The first match is chosen.
<code>eachof</code>	Select available storage that matches each of the operands.
<code>noneof</code>	Do not select storage that matches any of the operands.
<code>oneof</code>	Select available storage that matches one and only one of the operands. The first match is chosen.

See the description of the individual selection rules for details of the applicability of these operators.

Storage Layout Rules

The following sections describe storage layout rules:

- ◆ `apply`
- ◆ `parity`
- ◆ `striped`

See “[Compound Rules](#)” on page 124 for details of how to limit the scope of interpretation of rules to the components of an application volume, such as its plexes, columns and logs.

apply

The `apply` rule is used to apply rules from one or more specified templates in addition to the rules that appear in the current template. This rule acts recursively if the specified templates also use `apply` in their rules sections. The capabilities of any referenced templates are not used.

Expressions involving `apply` can specify the `eachof` or `oneof` operator. The default operator for this keyword is `eachof`.



The following examples demonstrate the application of the apply rule:

- ◆ Apply the rules but not the capabilities from the template `ArrayProductId` to a compound rule within the template `PrefabricatedDataMirroring`:

```
volume_template PrefabricatedDataMirroring {
    provides PrefabricatedDataMirroring
    rules {
        apply ArrayProductId
        confineto eachof ( "Redundancy" =nmirs , "Parity" ="0" )
    }
};
```

```
volume_template ArrayProductId {
    provides ArrayProductId
    rules {
        confineto "ProductId"
    }
};
```

- ◆ Typically, you would use the `apply` keyword when you want to get the rules of a template without its associated capabilities. In the example, the template `MyReliableSnapshot` is defined so that the application of `Snapshot` to one mirror results in the whole volume getting the associated `Snapshot` capability, whereas the application of `EMCStorage` to one mirror does not result in the whole volume getting the `EMCStorage` capability:

```
volume_template MyReliableSnapshot {
    provides Snapshot, Reliable
    rules {
        separateby "Enclosure"
        mirror 1 {
            apply Snapshot, EMCStorage
            confineto "Enclosure"
        }
        mirror 1 {
            confineto "Enclosure"
        }
    }
};
```

parity

The `parity` rule defines whether redundancy should be parity based (that is, RAID-5) as implemented in either hardware or software. The value can be `true` or `false`.

The following example demonstrates the application of the `parity` rule:

- ◆ Define a template for providing reliability using software RAID-5:

```
volume_template Raid5Volume {
    provides Raid5Capability, Raid5LogMirroring
    rules {
        parity true
        stripe ncols - nmaxcols
        log nlogs {
            type raid5
        }
    }
};
```

striped

The `striped` rule indicates whether a volume or mirror is to be striped.

If `striped` is set to `true`, the number of columns is not necessarily greater than one as striping can be implemented in hardware as well as software.

The following example demonstrates the application of the `striped` rule:

- ◆ Define a template for providing reliability using mirrors, but where striping is not allowed:

```
volume_template ReliableConcat {
    provides Reliable, Concat
    rules {
        redundancy 2-3
        striped false
    }
};
```



Compound Rules

Whether a rule applies to a volume, mirror, column or log depends on the scope in which the rule is applied. Compound rules are composed of several other rules, and are used to specify the scope of rules at a level below that of an entire volume. A compound rule can apply to one or more mirrors, columns or logs of a volume. It can also define how redundancy and separation are to be implemented for a volume.

Note No more than two levels of nesting of compound rules may be specified.

The following sections describe the various types of compound rule:

- ◆ `mirror`
- ◆ `mirror_group`
- ◆ `stripe`
- ◆ `log`

mirror

The mirror rule is used to describe one or more mirrors of a volume. All the basic rules except striped and parity, and a restricted form of the stripe rule, can be used within a mirror rule. Rules that are specified within a mirror rule apply only to those mirrors that are constructed from this rule.

The following examples demonstrate the application of the mirror rule:

- ◆ Confine each mirror within an enclosure so that no mirror spans more than one enclosure:

```
mirror all {
    confineto "Enclosure"
}
```

- ◆ Configure preferably two mirrors, and at least one mirror, of the volume with the EMCSnapshot feature:

```
mirror 2-1 {
    apply EMCSnapshot
}
```

- ◆ Use `confineto` rules to force one mirror to be created on each of four separate enclosures:

```
mirror 1 {
    confineto "Enclosure"="enclr1"
}
mirror 1 {
    confineto "Enclosure"="enclr2"
}
mirror 1 {
    confineto "Enclosure"="enclr3"
}
mirror 1 {
    confineto "Enclosure"="enclr4"
}
```

mirror_group

The `mirror_group` rule groups together different mirrors of a volume. It should be used when there are groups of mirrors with several things that are common to each group, or when such groups need to have a `separateby` rule between them. Merging of mirrors can only take place within mirror groups.

The following example demonstrates the application of the `mirror_group` rule:

- ◆ Configure two mirror groups, A with two striped mirrors, and B with two concatenated mirrors, where the mirrors in each group lie within different enclosures:

```
mirror_group A {
    mirror 2 {
        confineto "Enclosure"
    }
    stripe 4
}

mirror_group B {
    mirror 2 {
        confineto "Enclosure"
    }
    striped false
}

mirror_group A,B {
    separateby "Enclosure"
}
```



stripe

The `stripe` rule describes one or more columns of a volume. All basic rules and some restricted form-related or mirror-related rules can be specified within a `stripe` rule. ISP merges multiple `stripe` rules to form a single `stripe` rule whose rules are the union of the separate `stripe` rules.

The following examples demonstrate the application of the `stripe` rule:

- ◆ Stripe a VxVM object over 5 columns:

```
stripe 5
```

- ◆ Use `confineto` rules to force a column to be created on separate enclosures, but which are attached to the same controller, `ctlr1`:

```
stripe 2-5 {
  confineto "Controller"="ctlr1"
}
stripe 3-6 {
  separateby "Enclosure"
}
```

These rules are merged to form the following rule:

```
stripe 2-6 {
  confineto "Controller"="ctlr1"
  separateby "Enclosure"
}
```

Six columns are created by preference. If this is not possible, ISP attempts to create fewer columns down to a minimum of two.

log

The `log` rule describes a volume's logs. The argument of the rule specifies how many mirrors the log should have. Compound rules can include storage selection rules, `stripe` rules, and define the log type. The following log types may be defined:

`dco` Version 20 data change object (DCO) that can be used for both DRL and FastResync.

`raid5` RAID-5 log.

The following examples demonstrate the application of the `log` rule:

- ◆ Create a striped RAID-5 log with 4 columns, and a DCO log, each of which are confined to LUNs from a single (but possibly separate) enclosure:

```
parity true
log 1{
  type raid5
  confineto "Enclosure"
  stripe 4
}
log 1{
  type dco
  confineto "Enclosure"
}
```

- ◆ Create a mirrored new-style DCO log, with each plex configured on a separate controller.

```
mirror 2
log 2{
  type dco
  separateby "Controller"
}
```





ISP Language Definition

You can define the following objects using the VERITAS Intelligent Storage Provisioning (ISP) specification language:

- ◆ [Capability](#)
- ◆ [Volume Template](#)
- ◆ [User Template](#)
- ◆ [Storage Pool](#)
- ◆ [Template Set](#)
- ◆ [Storage Pool Set](#)

Note the following points with regard to the syntax of the language:

- ◆ Each object category, such as capability, template, user template and storage pool and capability has its own name space. This means that a capability and a template can have the same name, but two capabilities cannot have the same name.
- ◆ All keywords are case insensitive.
- ◆ The primitive types are:

<i>boolean</i>	Possible values are true or false .
<i>guid_string</i>	String identifier for a GUI element.
<i>int</i>	Short signed integer.
<i>long</i>	Long signed integer.
<i>quoted_string</i>	String enclosed in double quotes.
<i>string</i>	String.
<i>uint32</i>	Unsigned 32-bit integer.



Syntax Conventions

The following typographic conventions are used in the syntax description:

Typeface	Usage	Examples
monospace (bold)	Indicates a keyword.	capability
<i>monospace (italic)</i>	Indicates an irreducible term such as an identifier, and its type. A value is expected if only a type is specified.	<i>c_name:string</i> <i>uint32</i>
monospace	Indicates a reducible term.	capability_list

Symbol	Usage	Examples
[]	Indicates an optional syntax component.	[extends capability_list]
	Separates mutually exclusive syntax components.	dco dr1 raid5 sr1



Reserved Keywords

The following keywords are reserved. They may not be used as identifiers for names of capabilities, templates and so on.

all	descriptionid	mirror	storage_pool_set
allof	desired	mirror_group	string
affinity	display_name	multipath	stripe
aggregatable	display_name_id	none	strong
aggregate	dg	noneof	template
anyof	domain	oneof	templates
application_template	dontcare	parity	template_set
application_templates	eachof	pool	true
apply	exclude	pools	type
autogrow	extends	provides	user_template
capabilities	false	raid5	user_templates
capability	feature	range	var
clone	features	required	volume_template
column	group	requires	volume_templates
confineto	host	rules	widget_plugin_id
const	hosts	select	
data	implements	selfsufficient	
dco	inherits	separateby	
defaultvalue	int	server_plugin_id	
description	log	storage_pool	



Capability

```
capability c_name:string [ {  
  [ extends string_list ]  
  [ description quoted_string ]  
  [ descriptionid msgcat_id:quoted_string, msg_id:int ]  
  [ display_name quoted_string ]  
  [ display_name_id msgcat_id:quoted_string, msg_id:int ]  
  [ variable_list ]  
} ] ;
```

See “[Capabilities](#)” on page 107 for more information about the elements of a capability specification.

string_list

```
string | string_list, string
```

variable_list

```
variable | variable_list variable
```

variable

```
var var_name:string : int | string [ {  
  [ defaultvalue value:int | quoted_string ]  
  [ description quoted_string ]  
  [ descriptionid msgcat_id:quoted_string, msg_id:int ]  
} ]
```

Volume Template

```

volume_template vt_name:string {
  [ provides string_list ]
  [ requires string_list ]
  [ inherits string_list ]
  [ extends string_list ]
  [ description quoted_string ]
  [ descriptionid msgcat_id:quoted_string, msg_id:int ]
  [ group quoted_string ]
  [ rules [ {
    template_rules
  } ] ]
} ;

```

See “[Volume Templates](#)” on page 110 for more information about the elements of a volume template specification.

template_rules

```

[ [ desired ] confineto confineto_expr ] |
[ [ desired ] exclude exclude_expr ] |
[ [ desired ] select select_expr ] |
[ [ desired ] separateby string_list ] |
[ [ desired ] strong separateby string_list ] |
[ [ desired ] affinity string_list ] |
[ [ desired ] multipath multipath_expr ] |
[ [ desired ] striped boolean ] |
[ [ desired ] parity boolean ] |
[ [ desired ] apply string_list ] |

```



```
[ [ desired ] mirror int [ {  
  [ [ desired ] confineto confineto_expr ]  
  [ [ desired ] exclude exclude_expr ]  
  [ [ desired ] select select_expr ]  
  [ [ desired ] separateby string_list ]  
  [ [ desired ] strong separateby string_list ]  
  [ [ desired ] affinity string_list ]  
  [ [ desired ] multipath multipath_expr ]  
  [ [ desired ] striped boolean ]  
  [ [ desired ] stripe from:int - to:int [ {  
    [ [ desired ] confineto confineto_expr ]  
    [ [ desired ] exclude exclude_expr ]  
    [ [ desired ] select select_expr ]  
    [ [ desired ] separateby string_list ]  
    [ [ desired ] strong separateby string_list ]  
    [ [ desired ] affinity string_list ]  
  } ] ]  
} ] ] |
```

```
[ [ desired ] mirror [ {  
  [ [ desired ] confineto confineto_expr ]  
  [ [ desired ] exclude exclude_expr ]  
  [ [ desired ] select select_expr ]  
  [ [ desired ] separateby string_list ]  
  [ [ desired ] strong separateby string_list ]  
  [ [ desired ] affinity string_list ]  
  [ [ desired ] multipath multipath_expr ]  
  [ [ desired ] striped boolean ]  
  [ [ desired ] stripe from:int - to:int [ {  
    [ [ desired ] confineto confineto_expr ]  
    [ [ desired ] exclude exclude_expr ]  
    [ [ desired ] select select_expr ]  
    [ [ desired ] separateby string_list ]  
    [ [ desired ] strong separateby string_list ]  
    [ [ desired ] affinity string_list ]  
  } ] ]  
} ] ] |
```



```

[ [ desired ] mirror all [ {
  [ [ desired ] confineto confineto_expr ]
  [ [ desired ] exclude exclude_expr ]
  [ [ desired ] select select_expr ]
  [ [ desired ] separateby string_list ]
  [ [ desired ] strong separateby string_list ]
  [ [ desired ] affinity string_list ]
  [ [ desired ] multipath multipath_expr ]
  [ [ desired ] striped boolean ]
  [ [ desired ] stripe from:int - to:int [ {
    [ [ desired ] confineto confineto_expr ]
    [ [ desired ] exclude exclude_expr ]
    [ [ desired ] select select_expr ]
    [ [ desired ] separateby string_list ]
    [ [ desired ] strong separateby string_list ]
    [ [ desired ] affinity string_list ]
  } ] ]
} ] ] |

[ [ desired ] stripe from:int - to:int [ {
  [ [ desired ] confineto confineto_expr ]
  [ [ desired ] exclude exclude_expr ]
  [ [ desired ] select select_expr ]
  [ [ desired ] separateby string_list ]
  [ [ desired ] strong separateby string_list ]
  [ [ desired ] affinity string_list ]
  [ [ desired ] multipath multipath_expr ]
  [ [ desired ] mirror int [ {
    [ [ desired ] confineto confineto_expr ]
    [ [ desired ] exclude exclude_expr ]
    [ [ desired ] select select_expr ]
    [ [ desired ] separateby string_list ]
    [ [ desired ] strong separateby string_list ]
    [ [ desired ] affinity string_list ]
    [ [ desired ] multipath multipath_expr ]
  } ] ]
  [ [ desired ] mirror [ {
    [ [ desired ] confineto confineto_expr ]
    [ [ desired ] exclude exclude_expr ]
    [ [ desired ] select select_expr ]
    [ [ desired ] separateby string_list ]
    [ [ desired ] strong separateby string_list ]
    [ [ desired ] affinity string_list ]
    [ [ desired ] multipath multipath_expr ]
  } ] ]
} ] ] |

```



```

[ [ desired ] mirror_group mg_name:string [ {
  [ [ desired ] confineto confineto_expr ]
  [ [ desired ] exclude exclude_expr ]
  [ [ desired ] select select_expr ]
  [ [ desired ] separateby string_list ]
  [ [ desired ] strong separateby string_list ]
  [ [ desired ] affinity string_list ]
  [ [ desired ] multipath multipath_expr ]
  [ [ desired ] mirror int [ {
    [ [ desired ] confineto confineto_expr ]
    [ [ desired ] exclude exclude_expr ]
    [ [ desired ] select select_expr ]
    [ [ desired ] separateby string_list ]
    [ [ desired ] strong separateby string_list ]
    [ [ desired ] affinity string_list ]
  } ] ]
} ] ]
[ [ desired ] mirror [ {
  provides string_list ]
  [ [ desired ] confineto confineto_expr ]
  [ [ desired ] exclude exclude_expr ]
  [ [ desired ] select select_expr ]
  [ [ desired ] separateby string_list ]
  [ [ desired ] strong separateby string_list ]
  [ [ desired ] affinity string_list ]
  [ [ desired ] multipath multipath_expr ]
  [ [ desired ] striped boolean ]
  [ [ desired ] stripe from:int - to:int [ {
    [ [ desired ] confineto confineto_expr ]
    [ [ desired ] exclude exclude_expr ]
    [ [ desired ] select select_expr ]
    [ [ desired ] separateby string_list ]
    [ [ desired ] strong separateby string_list ]
    [ [ desired ] affinity string_list ]
  } ] ]
} ] ]
} ] ] |

```

```

[ [ desired ] stripe all [ {
  [ [ desired ] confineto confineto_expr ]
  [ [ desired ] exclude exclude_expr ]
  [ [ desired ] select select_expr ]
  [ [ desired ] separateby string_list ]
  [ [ desired ] strong separateby string_list ]
  [ [ desired ] affinity string_list ]
  [ [ desired ] multipath multipath_expr ]
} ] ] |

[ [ desired ] log int [ {
  [ type dco | raid5 ]
  [ group quoted_string ]
  [ [ desired ] confineto confineto_expr ]
  [ [ desired ] exclude exclude_expr ]
  [ [ desired ] select select_expr ]
  [ [ desired ] separateby string_list ]
  [ [ desired ] strong separateby string_list ]
  [ [ desired ] affinity string_list ]
  [ [ desired ] multipath multipath_expr ]
  [ [ desired ] striped boolean ]
  [ [ desired ] stripe from:int - to:int [ {
    [ [ desired ] confineto confineto_expr ]
    [ [ desired ] exclude exclude_expr ]
    [ [ desired ] select select_expr ]
    [ [ desired ] separateby string_list ]
    [ [ desired ] strong separateby string_list ]
    [ [ desired ] affinity string_list ]
    [ [ desired ] multipath multipath_expr ]
  } ] ]
} ] ] |

```



```
[ [ desired ] log all {
  type dco | raid5
  [ [ desired ] confineto confineto_expr ]
  [ [ desired ] exclude exclude_expr ]
  [ [ desired ] select select_expr ]
  [ [ desired ] separateby string_list ]
  [ [ desired ] strong separateby string_list ]
  [ [ desired ] affinity string_list ]
  [ [ desired ] multipath multipath_expr ]
  [ [ desired ] striped boolean ]
  [ [ desired ] stripe from:int - to:int [ {
    [ [ desired ] confineto confineto_expr ]
    [ [ desired ] exclude exclude_expr ]
    [ [ desired ] select select_expr ]
    [ [ desired ] separateby string_list ]
    [ [ desired ] strong separateby string_list ]
    [ [ desired ] affinity string_list ]
    [ [ desired ] multipath multipath_expr ]
  } ] ]
} ] ]
[ [ desired ] stripe all [ {
  [ [ desired ] confineto confineto_expr ]
  [ [ desired ] exclude exclude_expr ]
  [ [ desired ] select select_expr ]
  [ [ desired ] separateby string_list ]
  [ [ desired ] strong separateby string_list ]
  [ [ desired ] affinity string_list ]
  [ [ desired ] multipath multipath_expr ]
} ] ]
} ] ]
```

confineto_expr

```
name:string |
name:string operator value:string |
name:quoted_string |
name:quoted_string operator value:quoted_string |
eachof(confineto_expr) |
anyof(confineto_expr) |
allof(confineto_expr) |
oneof(confineto_expr) |
noneof(confineto_expr) |
confineto_expr, confineto_expr
```

exclude_expr

```
name:string operator value:string |  
name:quoted_string operator value:quoted_string |  
allof(exclude_expr) |  
exclude_expr, exclude_expr
```

multipath_expr

```
from:int [ - to:int ] name:string |  
from:int [ - to:int ] name:quoted_string |  
multipath_expr, multipath_expr
```

select_expr

```
confineto_expr
```

operator

```
<= | < | = | > | >= | !=
```



User Template

```
user_template ut_name:string [ {  
  [ description quoted_string ]  
  [ descriptionid descriptionid ]  
  [ volume_templates vt_name_list ]  
  [ capability capabilities_expr ]  
  [ rules [ {  
    [ rules ]  
  } ] ]  
} ] ;
```

See [“Creating and Modifying User Templates”](#) on page 101 for more information about the elements of a user template specification.

vt_name_list

```
vt_name:string | vt_name_list, vt_name_list
```

capabilities_expr

```
c_name:string [ {  
  parameter_list  
} ]  
| capabilities_expr, capabilities_expr
```

parameter_list

```
[ const ] attribute:string = value_expr  
| parameter_list, parameter_list
```

value_expr

```
string | int
```

Storage Pool

```

storage_pool sp_name:string [ {
  [ volume_templates vt_name_list ]
  [ description quoted_string ]
  [ descriptionid descriptionid ]
  [ autogrow boolean ]
  [ selfsufficient boolean ]
  [ rules [ {
    [ sp_rules ]
  } ] ]
} ] ;

```

sp_rules

```
[ sp_rule ] | sp_rules sp_rule
```

sp_rule

```

[ [ desired ] exclude exclude_expr ]
[ [ desired ] separateby separateby_expr ]
[ [ desired ] strong separateby separateby_expr ]
[ [ desired ] affinity separateby_expr ]
[ [ desired ] confineto sp_confineto_expr ]
[ [ desired ] select sp_confineto_expr ]

```

sp_confineto_expr

```

name:quoted_string |
name:quoted_string operator value:quoted_string |
eachof(sp_confineto_expr) |
anyof(sp_confineto_expr) |
allof(sp_confineto_expr) |
oneof(sp_confineto_expr) |
noneof(sp_confineto_expr)

```



Template Set

```
template_set sp_name:string [ {  
  [ volume_templates vt_name_list ]  
  [ description quoted_string ]  
  [ descriptionid descriptionid ]  
} ] ;
```

Storage Pool Set

```
storage_pool sp_name:string [ {  
  [ storage_pools st_pool_list ]  
  [ description quoted_string ]  
  [ descriptionid descriptionid ]  
} ] ;
```

st_pool_list

```
sp_name:string | st_pool_list, st_pool_list
```


ISP Configuration Elements

This appendix lists and describes the following types of pre-defined elements that are available for use with VERITAS Intelligent Storage Provisioning (ISP):

- ◆ [Template Sets](#)
- ◆ [Volume Templates](#)
- ◆ [Capabilities](#)
- ◆ [Storage Pools](#)
- ◆ [Storage Pool Sets](#)

These elements are defined in `/etc/vx/alloc/configuration_database.txt`. Before modifying this file, make a backup copy so that you can reverse any changes that you make.



Template Sets

ConfineVolume

Ensures that a volume is confined to specified storage.

Provides capabilities: [ConfineToSimilarStorage](#), [ConfineToSpecificStorage](#).

Uses templates: [ConfineToSimilarStorage](#), [ConfineToSpecificStorage](#).

DataMirroring

Ensures that a volume has multiple copies of its data.

Provides capabilities: [ArrayProductId](#), [ConfineLogsToSimilarStorage](#), [ConfineMirrorsToSimilarStorage](#), [DataMirroring](#), [DCOLogMirroring](#), [InstantSnapshottable](#), [LogsOnSeparateComponents](#), [MirrorsOnSeparateComponents](#).

Uses templates: [ArrayProductId](#), [ConfineLogsToSimilarStorage](#), [ConfineMirrorsToSimilarStorage](#), [DataMirroring](#), [DCOLogMirroring](#), [InstantSnapshottable](#), [LogsOnSeparateComponents](#), [MirrorsOnSeparateComponents](#).

DataMirroringPrefabricatedRaid5

Ensures that a volume has multiple copies of data on prefabricated RAID-5 disks that are exported by an array.

Provides capabilities: [ArrayProductId](#), [ConfineLogsToSimilarStorage](#), [ConfineMirrorsToSimilarStorage](#), [DataMirroring](#), [DCOLogMirroring](#), [InstantSnapshottable](#), [LogsOnSeparateComponents](#), [MirrorsOnSeparateComponents](#), [PrefabricatedRaid5](#).

Uses templates: [ArrayProductId](#), [ConfineLogsToSimilarStorage](#), [ConfineMirrorsToSimilarStorage](#), [DataMirroring](#), [DCOLogMirroring](#), [InstantSnapshottable](#), [LogsOnSeparateComponents](#), [MirrorsOnSeparateComponents](#), [PrefabricatedRaid5](#).

DataMirroringPrefabricatedStriping

Ensures that a volume has multiple copies of data on prefabricated striped disks that are exported by an array.

Provides capabilities: [ArrayProductId](#), [ConfineLogsToSimilarStorage](#), [ConfineMirrorsToSimilarStorage](#), [DataMirroring](#), [DCOLogMirroring](#), [InstantSnapshottable](#), [LogsOnSeparateComponents](#), [MirrorsOnSeparateComponents](#), [PrefabricatedStriping](#).

Uses templates: [ArrayProductId](#), [ConfineLogsToSimilarStorage](#), [ConfineMirrorsToSimilarStorage](#), [DataMirroring](#), [DCOLogMirroring](#), [InstantSnapshottable](#), [LogsOnSeparateComponents](#), [MirrorsOnSeparateComponents](#), [PrefabricatedStriping](#).

DataMirrorStripe

Ensures that I/O from and to a volume is spread across multiple columns within mirrors.

Provides capabilities: [ArrayProductId](#), [ColumnsOnSeparateComponents](#), [ConfineColumnsToSimilarStorage](#), [ConfineLogsToSimilarStorage](#), [ConfineMirrorsToSimilarStorage](#), [DataMirrorStripe](#), [DCOLogMirroring](#), [InstantSnapshottable](#), [LogsOnSeparateComponents](#), [MirrorsOnSeparateComponents](#).

Uses templates: [ArrayProductId](#), [ColumnsOnSeparateComponents](#), [ConfineColumnsToSimilarStorage](#), [ConfineLogsToSimilarStorage](#), [ConfineMirrorsToSimilarStorage](#), [DataMirrorStripe](#), [DCOLogMirroring](#), [InstantSnapshottable](#), [LogsOnSeparateComponents](#), [MirrorsOnSeparateComponents](#).

DataStripeMirror

Ensures that I/O from and to a volume is spread across multiple columns, where each column has multiple copies of the data.

Provides capabilities: [ArrayProductId](#), [ColumnsOnSeparateComponents](#), [ConfineColumnsToSimilarStorage](#), [ConfineLogsToSimilarStorage](#), [ConfineMirrorsToSimilarStorage](#), [DataStripeMirror](#), [DCOLogMirroring](#), [InstantSnapshottable](#), [LogsOnSeparateComponents](#), [MirrorsOnSeparateComponents](#).

Uses templates: [ArrayProductId](#), [ColumnsOnSeparateComponents](#), [ConfineColumnsToSimilarStorage](#), [ConfineLogsToSimilarStorage](#), [ConfineMirrorsToSimilarStorage](#), [DataStripeMirror](#), [DCOLogMirroring](#), [InstantSnapshottable](#), [LogsOnSeparateComponents](#), [MirrorsOnSeparateComponents](#).



InstantSnapshottable

Ensures that a volume supports dirty region logging (DRL) and instant snapshots.

Provides capabilities: [ConfineLogsToSimilarStorage](#), [DCOLogMirroring](#), [InstantSnapshottable](#), [LogsOnSeparateComponents](#).

Uses templates: [ConfineLogsToSimilarStorage](#), [DCOLogMirroring](#), [InstantSnapshottable](#), [LogsOnSeparateComponents](#).

MultipathingThroughMirroring

Ensures that a volume can withstand the failure of a number of paths. The I/O from and to a volume can potentially be spread across all the paths.

Provides capability: [DataMirroring](#), [Multipathing](#).

Uses template: [MultipathingThroughMirroring](#).

MultipathingThroughMultiplePaths

Ensures that a volume can withstand the failure of a specified number of paths. The I/O from and to the volume can potentially be spread across all these paths.

Provides capability: [MultipathingThroughMultiplePaths](#).

Uses template: [MultipathingThroughMultiplePaths](#).

PrefabricatedDataMirroring

Ensures that a volume uses prefabricated data mirroring configured within the disks exported by an array.

Provides capabilities: [ArrayProductId](#), [PrefabricatedDataMirroring](#).

Uses templates: [ArrayProductId](#), [PrefabricatedDataMirroring](#).

PrefabricatedRaid5

Ensures that a volume uses prefabricated RAID-5 disks that are exported by an array.

Provides capabilities: [ArrayProductId](#), [PrefabricatedRaid5](#).

Uses templates: [ArrayProductId](#), [PrefabricatedRaid5](#).

PrefabricatedStriping

Ensures that a volume uses prefabricated striped disks that are exported by an array.

Provides capabilities: [ArrayProductId](#), [PrefabricatedStriping](#).

Uses templates: [ArrayProductId](#), [PrefabricatedStriping](#).

Raid5Templates

Ensures that a volume uses parity to maintain redundant data.

Provides capabilities: [ArrayProductId](#), [ColumnsOnSeparateComponents](#), [ConfineColumnsToSimilarStorage](#), [ConfineLogsToSimilarStorage](#), [LogsOnSeparateComponents](#), [Raid5Capability](#), [Raid5LogMirroring](#), [Raid5LogStriping](#).

Uses templates: [ArrayProductId](#), [ColumnsOnSeparateComponents](#), [ConfineColumnsToSimilarStorage](#), [ConfineLogsToSimilarStorage](#), [LogsOnSeparateComponents](#), [Raid5LogStriping](#), [Raid5Volume](#).

Striping

Ensures that I/O from and to a volume is spread across multiple columns.

Provides capabilities: [ArrayProductId](#), [ColumnsOnSeparateComponents](#), [ConfineColumnsToSimilarStorage](#), [Striping](#).

Uses templates: [ArrayProductId](#), [ColumnsOnSeparateComponents](#), [ConfineColumnsToSimilarStorage](#), [Striping](#).

StripingPrefabricatedDataMirroring

Ensures that I/O from and to a volume are spread across multiple columns, which are configured on prefabricated data mirror disks that are exported by an array.

Provides capabilities: [ArrayProductId](#), [ColumnsOnSeparateComponents](#), [ConfineColumnsToSimilarStorage](#), [PrefabricatedDataMirroring](#), [Striping](#).

Uses templates: [ArrayProductId](#), [ColumnsOnSeparateComponents](#), [ConfineColumnsToSimilarStorage](#), [PrefabricatedDataMirroring](#), [Striping](#).



Volume Templates

ArrayProductId

Provides capability: [ArrayProductId](#).

ColumnsOnSeparateComponents

Provides capability: [ColumnsOnSeparateComponents](#).

ConcatVolumes

Provides capability: [ConcatVolumes](#).

ConfineColumnsToSimilarStorage

Provides capability: [ConfineColumnsToSimilarStorage](#).

ConfineLogsToSimilarStorage

Provides capability: [ConfineLogsToSimilarStorage](#).

ConfineMirrorsToSimilarStorage

Provides capability: [ConfineMirrorsToSimilarStorage](#).

ConfineToSimilarStorage

Provides capability: [ConfineToSimilarStorage](#).

ConfineToSpecificStorage

Provides capability: [ConfineToSpecificStorage](#).

DataMirroring

Provides capability: [DataMirroring](#).

Variable: `nmirs` Number of mirrors.

DataMirrorStripe

Provides capability: [DataMirrorStripe](#).

Variables: `ncols` Minimum number of columns.

`nmaxcols` Maximum number of columns.

`nmirs` Number of mirrors.

DataStripeMirror

Provides capability: [DataStripeMirror](#).

Variables: `ncols` Minimum number of columns.

`nmaxcols` Maximum number of columns.

`nmirs` Number of mirrors.

DCOLogMirroring

Provides capability: [DCOLogMirroring](#).

DCOLogStriping

Provides capability: [DCOLogStriping](#).

ExcludeSpecificStorage

Provides capability: [ExcludeSpecificStorage](#).

InstantSnapshottable

Provides capability: [InstantSnapshottable](#).



LogsOnSeparateComponents

Provides capability: [LogsOnSeparateComponents](#).

MirrorsOnSeparateComponents

Provides capability: [MirrorsOnSeparateComponents](#).

MultipathingThroughMirroring

Provides capabilities: [DataMirroring](#), [Multipathing](#).

Variable: `nmirs` Number of mirrors.

MultipathingThroughMultiplePaths

Provides capability: [MultipathingThroughMultiplePaths](#).

PrefabricatedDataMirroring

Provides capability: [PrefabricatedDataMirroring](#).

PrefabricatedRaid5

Provides capability: [PrefabricatedRaid5](#).

PrefabricatedStriping

Provides capability: [PrefabricatedStriping](#).

Raid5LogStriping

Provides capability: [Raid5LogStriping](#).

Raid5Volume

Provides capabilities: [Raid5Capability](#), [Raid5LogMirroring](#).

Variables: `ncols` Minimum number of columns.

`nlogs` Number of logs.
`nmaxcols` Maximum number of columns.

Striping

Provides capability: [Striping](#).

Variables: `ncols` Minimum number of columns.
`nmaxcols` Maximum number of columns.



Capabilities

ArrayProductId

A volume uses storage of the same type (`productId`).

Provided by volume template: [ArrayProductId](#).

ColumnsOnSeparateComponents

The columns of a volume are separated at the specified component level, such as "Controller" or "Enclosure".

Provided by volume template: [ColumnsOnSeparateComponents](#).

Variable: `component` Name of component (default value is "Controller").

ConcatVolumes

The volume is concatenated.

Provided by volume template: [ConcatVolumes](#).

ConfineColumnsToSimilarStorage

Each column uses only storage that has the same value for a specified attribute.

Provided by volume template: [ConfineColumnsToSimilarStorage](#).

Variable: `name` Name of storage attribute (default value is "Enclosure").

ConfineLogsToSimilarStorage

Each log uses only storage that has the same value for a specified attribute.

Provided by volume template: [ConfineLogsToSimilarStorage](#).

Variable: `name` Name of storage attribute (default value is "Enclosure").

ConfineMirrorsToSimilarStorage

Each mirror uses only storage that has the same value for a specified attribute.

Provided by volume template: [ConfineMirrorsToSimilarStorage](#).

Variable: `name` Name of storage attribute (default value is "Enclosure").

ConfineToSimilarStorage

A volume uses only storage that has the same value for a specified attribute.

Provided by volume template: [ConfineToSimilarStorage](#).

Variable: `name` Name of storage attribute (default value is VendorName).

ConfineToSpecificStorage

A volume uses only storage that has the specified value for a specified attribute name.

Provided by volume template: [ConfineToSpecificStorage](#).

Variables: `name` Name of storage attribute (no default).

`value` Value of storage attribute (no default).

DataMirroring

A mirrored volume maintains multiple copies of its data. This capability extends the [DataRedundancy](#) capability.

Provided by volume template: [DataMirroring](#).

Variable: `nmirs` Number of mirrors (default value is 2).

DataMirrorStripe

A mirrored-stripe volume distributes I/O across multiple columns within mirrors. This capability extends the [DataMirroring](#) and [Striping](#) capabilities.

Provided by volume template: [DataMirrorStripe](#).

Variables: `ncols` Minimum number of columns (default value is 8).

`nmaxcols` Maximum number of columns (default value is 20).

`nmirs` Number of mirrors (default value is 2).



DataRedundancy

A volume that maintains redundant data.

Provided by capability: [Raid5Capability](#).

Extended by capability: [DataMirroring](#).

DataStripeMirror

A striped-mirror volume distributes I/O across multiple columns, where each column has multiple copies of data. This capability extends the [DataMirroring](#) and [Striping](#) capabilities.

Provided by volume template: [DataStripeMirror](#).

Variables: `ncols` Minimum number of columns (default value is 8).
`nmaxcols` Maximum number of columns (default value is 20).
`nmirs` Number of mirrors (default value is 2).

DCOLogMirroring

The number of DCO plexes (copies) to configure for a DCO volume.

Provided by volume template: [DCOLogMirroring](#).

Variable: `nlogs` Number of DCO plexes (default value is 1).

DCOLogStriping

The number of columns to configure for a striped DCO volume.

Provided by volume template: [DCOLogStriping](#).

Variables: `ndcocols` Minimum number of columns (default value is 4).
`nmaxdcocols` Maximum number of columns (default value is 10).

ExcludeSpecificStorage

A volume does not use storage that has the specified value for a specified attribute name.

Provided by volume template: [ExcludeSpecificStorage](#).

Variables: `name` Name of storage attribute (no default).

value Value of storage attribute (no default).

InstantSnapshottable

A volume supports instant snapshots (full-sized or space-optimized). This capability extends the [Snapshottable](#) capability.

Provided by volume template: [InstantSnapshottable](#).

LogsOnSeparateComponents

The logs of a volume are separated at the specified component level, such as "Controller" or "Enclosure".

Provided by volume template: [LogsOnSeparateComponents](#).

Variable: component Name of component (default value is "Enclosure").

MirrorsOnSeparateComponents

The mirrors of a volume are separated at the specified component level, such as "Controller" or "Enclosure".

Provided by volume template: [MirrorsOnSeparateComponents](#).

Variable: component Name of component (default value is "Enclosure").

Multipathing

Multipathing allows a volume to withstand failure of a number of paths to the disks. The I/O from and to the volume can potentially be spread across all the paths.

Extended by capability: [MultipathingThroughMultiplePaths](#).

MultipathingThroughMultiplePaths

Multipathing allows a volume to withstand failure of the specified number of paths to the disks. The I/O from and to the volume can potentially be spread across all the paths. This capability extends the [Multipathing](#) capability.

Provided by volume template: [MultipathingThroughMultiplePaths](#).

Variable: npaths Number of paths that are allowed to fail (default value is 2).



PrefabricatedDataMirroring

A volume uses prefabricated data mirroring that is configured on disks that are exported by an array. This capability extends the [PrefabricatedDataRedundancy](#) capability.

Provided by volume template: [PrefabricatedDataMirroring](#).

Variable: `nmirs` Number of prefabricated mirrors to use (default value is 2).

PrefabricatedDataRedundancy

A volume uses prefabricated redundant disks that are exported by an array.

Extended by capabilities: [PrefabricatedDataMirroring](#), [PrefabricatedRaid5](#).

PrefabricatedRaid5

A volume uses prefabricated RAID-5 disks that are exported by an array. This capability extends the [PrefabricatedDataRedundancy](#) capability.

Provided by volume template: [PrefabricatedRaid5](#).

PrefabricatedStriping

A volume uses prefabricated striped disks that are exported by an array.

Provided by volume template: [PrefabricatedStriping](#).

Raid5Capability

A RAID-5 volume uses parity to implement data redundancy. This capability provides the [DataRedundancy](#) capability.

Provided by volume template: [Raid5Volume](#).

Variable: `ncols` Minimum number of columns (default value is 8).
`nmaxcols` Maximum number of columns (default value is 20).

Raid5LogMirroring

The number of RAID-5 log copies to configure for a RAID-5 volume.

Provided by volume template: [Raid5Volume](#).

Variable: `nlogs` Number of RAID-5 log copies (default value is 1).

Raid5LogStriping

The number of columns to configure for striped RAID-5 logs.

Provided by volume template: [Raid5LogStriping](#).

Variables: `nraid5cols` Minimum number of columns (default value is 4).
`nmaxraid5cols` Maximum number of columns (default value is 10).

Snapshottable

Volume snapshots of a volume may be taken.

Extended by capability: [InstantSnapshottable](#).

Striping

A striped volume distributes I/O across multiple columns.

Provided by volume template: [Striping](#).

Variables: `ncols` Minimum number of columns (default value is 8).
`nmaxcols` Maximum number of columns (default value is 20).



Storage Pools

any_volume_type

Supports volumes using any template from the configuration database.

Default policies: autogrow=diskgroup
 selfsufficient=host

Associates volume templates: none.

mirror_stripe_volumes

Supports distribution of I/O from and to volumes across multiple columns within mirrors.

Default policies: autogrow=diskgroup
 selfsufficient=1

Associates volume templates: [ArrayProductId](#), [ColumnsOnSeparateComponents](#), [ConfineColumnsToSimilarStorage](#), [ConfineLogsToSimilarStorage](#), [ConfineMirrorsToSimilarStorage](#), [ConfineToSimilarStorage](#), [ConfineToSpecificStorage](#), [DataMirrorStripe](#), [DCOLogMirroring](#), [InstantSnapshottable](#), [LogsOnSeparateComponents](#), [MirrorsOnSeparateComponents](#), [MultipathingThroughMultiplePaths](#).

mirrored_prefab_raid5_volumes

Supports use by volumes of multiple copies of data configured on prefabricated Raid-5 disks that are exported by an array.

Default policies: autogrow=diskgroup
 selfsufficient=1

Associates volume templates: [ArrayProductId](#), [ConfineLogsToSimilarStorage](#), [ConfineMirrorsToSimilarStorage](#), [ConfineToSimilarStorage](#), [ConfineToSpecificStorage](#), [DataMirroring](#), [DCOLogMirroring](#), [InstantSnapshottable](#), [LogsOnSeparateComponents](#), [MirrorsOnSeparateComponents](#), [MultipathingThroughMultiplePaths](#), [PrefabricatedRaid5](#).

mirrored_prefab_striped_volumes

Supports use by volumes of multiple copies of data configured on prefabricated striped disks that are exported by an array.

Default policies: `autogrow=diskgroup`
 `selfsufficient=1`

Associates volume templates: [ArrayProductId](#), [ConfineLogsToSimilarStorage](#), [ConfineMirrorsToSimilarStorage](#), [ConfineToSimilarStorage](#), [ConfineToSpecificStorage](#), [DataMirroring](#), [DCOLogMirroring](#), [InstantSnapshottable](#), [LogsOnSeparateComponents](#), [MirrorsOnSeparateComponents](#), [MultipathingThroughMultiplePaths](#), [PrefabricatedStriping](#).

mirrored_volumes

Supports volume with multiple copies of data.

Default policies: `autogrow=diskgroup`
 `selfsufficient=host`

Associates volume templates: [ArrayProductId](#), [ConfineLogsToSimilarStorage](#), [ConfineMirrorsToSimilarStorage](#), [ConfineToSimilarStorage](#), [ConfineToSpecificStorage](#), [DataMirroring](#), [DCOLogMirroring](#), [InstantSnapshottable](#), [LogsOnSeparateComponents](#), [MirrorsOnSeparateComponents](#), [MultipathingThroughMultiplePaths](#).

prefab_mirrored_volumes

Supports use by volumes of prefabricated data mirrors that are exported by an array.

Default policies: `autogrow=diskgroup`
 `selfsufficient=host`

Associates volume templates: [ArrayProductId](#), [ConfineToSimilarStorage](#), [ConfineToSpecificStorage](#), [InstantSnapshottable](#), [MultipathingThroughMultiplePaths](#), [PrefabricatedDataMirroring](#).



prefab_raid5_volumes

Supports use by volumes of prefabricated RAID-5 disks that are exported by an array.

Default policies: autogrow=diskgroup
 selfsufficient=host

Associates volume templates: [ArrayProductId](#), [ConfineToSimilarStorage](#), [ConfineToSpecificStorage](#), [InstantSnapshottable](#), [MultipathingThroughMultiplePaths](#), [PrefabricatedRaid5](#).

prefab_stripped_volumes

Supports use by volumes of prefabricated striped disks that are exported by an array.

Default policies: autogrow=diskgroup
 selfsufficient=host

Associates volume templates: [ArrayProductId](#), [ConfineToSimilarStorage](#), [ConfineToSpecificStorage](#), [InstantSnapshottable](#), [MultipathingThroughMultiplePaths](#), [PrefabricatedStriping](#).

raid5_volumes

Supports volumes which use parity to maintain redundant data.

Default policies: autogrow=diskgroup
 selfsufficient=host

Associates volume templates: [ArrayProductId](#), [ColumnsOnSeparateComponents](#), [ConfineColumnsToSimilarStorage](#), [ConfineLogsToSimilarStorage](#), [ConfineToSimilarStorage](#), [ConfineToSpecificStorage](#), [InstantSnapshottable](#), [LogsOnSeparateComponents](#), [Raid5Volume](#), [MultipathingThroughMultiplePaths](#).

stripe_mirror_volumes

Supports distribution of I/O from and to volumes across multiple columns, where each column has multiple copies of data.

Default policies: `autogrow=diskgroup`
 `selfsufficient=host`

Associates volume templates: [ArrayProductId](#), [ColumnsOnSeparateComponents](#), [ConfineColumnsToSimilarStorage](#), [ConfineLogsToSimilarStorage](#), [ConfineMirrorsToSimilarStorage](#), [ConfineToSimilarStorage](#), [ConfineToSpecificStorage](#), [DataStripeMirror](#), [DCOLogMirroring](#), [InstantSnapshottable](#), [LogsOnSeparateComponents](#), [MirrorsOnSeparateComponents](#), [MultipathingThroughMultiplePaths](#).

striped_prefab_mirrored_volumes

Supports distribution of I/O from and to volumes across multiple columns that are configured on prefabricated data mirrors exported by an array.

Default policies: `autogrow=diskgroup`
 `selfsufficient=host`

Associates volume templates: [ArrayProductId](#), [ColumnsOnSeparateComponents](#), [ConfineColumnsToSimilarStorage](#), [ConfineToSimilarStorage](#), [ConfineToSpecificStorage](#), [InstantSnapshottable](#), [MultipathingThroughMultiplePaths](#), [PrefabricatedDataMirroring](#), [Striping](#).

striped_volumes

Supports distribution of I/O from and to volumes across multiple columns.

Default policies: `autogrow=diskgroup`
 `selfsufficient=host`

Associates volume templates: [ArrayProductId](#), [ColumnsOnSeparateComponents](#), [ConfineColumnsToSimilarStorage](#), [ConfineToSimilarStorage](#), [ConfineToSpecificStorage](#), [InstantSnapshottable](#), [MultipathingThroughMultiplePaths](#), [Striping](#).



Storage Pool Sets

mirrored_data_striped_clones

Supports data volumes with multiple copies of data, and snapshot volumes with I/O distributed across multiple columns.

Data storage pool type: [mirrored_volumes](#).

Clone storage pool type: [striped_volumes](#).

mirrored_prefab_raid5_data_mirrored_clones

Supports data volumes with multiple copies of data created from RAID-5 storage, and snapshot volumes with multiple copies of data.

Data storage pool type: [mirrored_prefab_raid5_volumes](#).

Clone storage pool type: [mirrored_volumes](#).

mirrored_prefab_stripe_data_striped_clones

Supports data volumes with multiple copies of data configured on prefabricated striped storage, and snapshot volumes with I/O distributed across multiple columns.

Data storage pool type: [mirrored_prefab_striped_volumes](#).

Clone storage pool type: [striped_volumes](#).

prefab_mirrored_data_prefab_striped_clones

Supports data volumes with multiple copies of data configured on prefabricated striped storage, and snapshot volumes with I/O distributed across multiple columns also configured on prefabricated striped storage.

Data storage pool type: [prefab_mirrored_volumes](#).

Clone storage pool type: [prefab_striped_volumes](#).

stripe_mirrored_data_striped_clones

Supports I/O from and to data volumes that are distributed across multiple columns, where each column has multiple copies of data, and snapshot volumes with I/O distributed across multiple columns.

Data storage pool type: [stripe_mirror_volumes](#).

Clone storage pool type: [striped_volumes](#).

striped_prefab_mirrored_data_striped_clones

Supports I/O from and to data volumes distributed across multiple columns constructed from mirrored storage, and snapshot volumes with I/O distributed across multiple columns.

Data storage pool type: [striped_prefab_mirrored_volumes](#).

Clone storage pool type: [striped_volumes](#).





Volume Group Definition Syntax

This appendix describes the syntax of a `volume` definition that may be used as input to the `vxvoladm` command. Volume groups are generally used to create several volumes at the same time within a storage pool and are given equal weighting by VERITAS Intelligent Storage Provisioning (ISP) when allocating storage resources.

The syntax of a `volume` definition is shown here:

```

volume {
  [diskgroup "dgname"]
  [rules { volume-group-rules } ]
  volume "name" length {
    [cachevolume "cachevol"]
    [capability 'capability[(name=value,...)][,capability...]' ]
    [comment "comment"]
    [dcologlen length]
    [dm dm1,[dm2,...]]
    [drl on|true|yes|sequential|off|false|no]
    [excl on|off|true|false|yes|no]
    [fmr on|off|true|false|yes|no]
    [fstype type]
    [group "group"]
    [init active|none|zero]
    [iodelay delay]
    [iosize size]
    [layout "layout-type"]
    [max_ncolumn number]
    [max_nraid5column number]
    [min_ncolumn number]
    [min_nraid5column number]
    [mode mode]
    [pool "poolname"]
    [raid5_stripeunit width]
    [raid5loglen length]
    [regionsize size]
    [rules { volume-rules } ]
    [spare yes|no|only]
    [stripe_stripeunit width]
  }
}

```



```

    [tasktag "tag"]
    [type data|snapshot|cachevolume]
    [user "user"]
    [user_template "ut1" [, "ut2"...]]
    [usetype "volume-usage-type"]
    [volume_template "vt1" [, "vt2"...]]
    [vxvmtaskid taskid]
  }
  [volume "name" length { ...
  }]
};

```

The `volumegroup` fields in this definition are:

<code>diskgroup <i>dgname</i></code>	The name of the disk group in which the volumes are to be created.
<code>rules { <i>volume-group-rules</i> }</code>	The rules that are to be applied to all volumes in this volume group.
<code>volume "name" length</code>	The name of a volume to be created and its size.

The `volume` fields in the definition are:

<code>cachevolume "cachevol"</code>	The name of the cache volume on which a space-optimized snapshot volume is to be created.
<code>capability `capability[(name=value,...)][, capability..]`</code>	The capabilities that are desired for the volume.
<code>comment "comment"</code>	A description of the volume.
<code>dcologlen length</code>	The size of a DCO volume whose creation is implied by the specified capabilities or templates.
<code>dm <i>dm1</i> [, <i>dm2</i>, ...]</code>	A list of disk media which can be allocated to a volume.
<code>drl on true yes sequential off false no</code>	Whether DRL, sequential DRL, or no DRL is enabled on a volume.
<code>excl on off true false yes no</code>	Whether a volume in a cluster-shareable disk group can be opened by only one node at a time.
<code>fmr on off true false yes no</code>	Whether FastResync is enabled on a volume.
<code>fstype type</code>	Specifies the file system type for a volume.



<code>group "group"</code>	The group ownership of a volume.
<code>init active none zero</code>	The type of initialization to perform on a volume.
<code>iodelay delay</code>	The delay in milliseconds between copy operations performed during recovery of a plex.
<code>iosize size</code>	The size of each region that is resynchronized during recovery of a plex.
<code>layout "layout-type"</code>	The plex layout that is to be created.
<code>max_ncolumn number</code>	The maximum number of columns in a striped volume.
<code>max_nraid5column number</code>	The maximum number of columns in a RAID-5 volume.
<code>min_ncolumn number</code>	The minimum number of columns in a striped volume.
<code>min_nraid5column number</code>	The minimum number of columns in a RAID-5 volume.
<code>mode mode</code>	The permissions to be applied to a volume, for example 644.
<code>pool "poolname"</code>	The name of the storage pool.
<code>raid5_stripeunit width</code>	The stripe unit width for a RAID-5 column.
<code>raid5loglen length</code>	The size of a RAID-5 log whose creation is implied by the specified capabilities or templates.
<code>regionsize size</code>	The size of each region that is tracked by a bit in the maps within a version 20 DCO volume. The value of <i>size</i> must be a power of 2 and be greater than or equal to 16k (16KB). The default value is 64k (64KB).
<code>rules { volume-rules }</code>	The rules that are to be applied during volume creation.
<code>spare yes no only</code>	Whether spare disks can be used for hot-relocation, or only spare disks are to be used.
<code>stripe_stripeunit width</code>	The stripe unit width.
<code>tasktag "tag"</code>	A tag that can be used to track the volume creation task.



`type data|snapshot|cachevolume`

Whether a volume is to be used for user data (such as a database or file system), as a full-sized instant snapshot volume, or as a cache volume for space-optimized instant snapshots.

`user "user"`

The user ownership of a volume.

`user_template ut1[,ut2...]`

The user templates that are to be used to create a volume.

`usetype "volume-usage-type"`

The usage type of a volume, such as `fsgen` or `raid5`.

`volume_template vt1[,vt2...]`

The templates that are to be used to create a volume.

`vxvmtaskid taskid`

VxVM task ID.

Multiple volumes may be defined within a volume group, and multiple volume groups may be defined in a definitions file.



Command Summary

This appendix summarizes the usage and purpose of important commands for the VERITAS Intelligent Storage Provisioning (ISP) feature of VERITAS Volume Manager (VxVM).

- ◆ [Creating and Administering Storage Pools](#)
- ◆ [Creating and Administering Application Volumes](#)

References are included to longer descriptions in the remainder of this book. For detailed information about an individual command, refer to the appropriate manual page in the 1M section. Further examples can be found in [“Command Examples”](#) on page 173.

Creating and Administering Storage Pools

Command	Description
<code>vxpool [-g <i>diskgroup</i>] create \ <i>storage_pool</i> [dm=<i>dm1</i>[,<i>dm2</i>...] \ [description="<i>description</i>"] \ \ \[autogrow=1 2] \ \ [selfsufficient=1 2 3] \ \ [rules=<i>rule</i>[,<i>rule</i> ...]</code>	Creates a storage pool. See “Creating a Storage Pool” on page 34.
<code>vxpool [-g <i>diskgroup</i>] adddisk \ <i>storage_pool</i> dm=<i>dm1</i>[,<i>dm2</i>,...]</code>	Adds one or more disks to a storage pool. See “Adding Disks to a Storage Pool” on page 37.
<code>vxpool [-g <i>diskgroup</i>] rmdisk \ <i>storage_pool</i> dm=<i>dm1</i>[,<i>dm2</i>,...]</code>	Removes one or more disks from a storage pool. See “Removing Disks from a Storage Pool” on page 37.
<code>vxpool [-g <i>diskgroup</i>] assoctemplate\ <i>storage_pool</i> template=<i>t1</i>[,<i>t2</i>,...]</code>	Associates one or more templates with a storage pool. See “Associating Templates with a Storage Pool” on page 37.
<code>vxpool [-g <i>diskgroup</i>] \ assoctemplateset\ <i>storage_pool</i> \ template_set=<i>ts1</i>[,<i>ts2</i>,...]</code>	Associates one or more template sets with a storage pool. See “Associating Template Sets with a Storage Pool” on page 38.



Creating and Administering Storage Pools

Command	Description
<code>vxpool [-g <i>diskgroup</i>] distemplate \ storage_pool template=t1[,t2,...]</code>	Dissociates one or more templates from a storage pool. See “Dissociating Templates from a Storage Pool” on page 38.
<code>vxpool [-g <i>diskgroup</i>] print \ storage_pool [storage_pool ...]</code>	Displays information about storage pools. See “Displaying Information About Storage Pools” on page 39.
<code>vxpool [-g <i>diskgroup</i>] getpolicy \ storage_pool</code>	Displays policies for a storage pool. See “Displaying Storage Pool Policies” on page 39.
<code>vxpool [-g <i>diskgroup</i>] setpolicy storage_pool \ [autogrow={1 pool} {2 diskgroup}] [selfsufficient={1 pool} \ {2 diskgroup} {3 host}]</code>	Sets policies on a storage pool. See “Changing the Policies on a Storage Pool” on page 39.
<code>vxpool [-g <i>diskgroup</i>] list</code>	Lists storage pools in a disk group. See “Listing Storage Pools Within a Disk Group” on page 40.
<code>vxpool [-g <i>diskgroup</i>] rename \ storage_pool new_name</code>	Renames a storage pool. See “Renaming a Storage Pool” on page 40.
<code>vxpool [-g <i>diskgroup</i>] [-r] delete \ storage_pool</code>	Deletes a storage pool. See “Deleting a Storage Pool” on page 40.



Creating and Administering Application Volumes

Command	Description
<code>vxvoladm [-g diskgroup] [-b] \ maxsize [<i>storage_specification</i>] \ [<i>attribute=value</i> ...]</code>	Determines the maximum volume size. See “Determining the Maximum Volume Size” on page 42.
<code>vxvoladm [-g diskgroup] [-b] make \ volume length [<i>storage_specification</i>] \ [<i>attribute=value</i> ...]</code>	Creates a volume. See “Creating Volumes” on page 43.
<code>vxvoladm [-g diskgroup] [-b] make \ volume length \ capability='DataMirroring' \ init=active</code>	Creates a volume with 2 mirrors and makes it immediately available for use. See “Creating a Mirrored Volume” on page 44.
<code>vxvoladm [-g diskgroup] make \ volume length \ capability='Striping(ncols=N)'</code>	Creates a striped volume with <i>N</i> columns. See “Creating a Striped Volume” on page 45.
<code>vxvoladm [-g diskgroup] make \ volume length \ capability='PrefabricatedRaid5' \ rules='confineto \ "VendorName"="Name"'</code>	Creates a RAID-5 volume on a device that is exported by an array made by a specified vendor. See “Creating a RAID-5 Volume on Prefabricated Storage” on page 46.
<code>vxvoladm -M make < filename</code>	Creates multiple volumes from a specification file. See “Creating Multiple Volumes as a Volume Group” on page 49.
<code>vxvoladm [-g diskgroup] maxgrow \ volume [<i>storage_specification</i>] \ [<i>attribute=value</i> ...]</code>	Determines the maximum growable size of a volume. See “Determining the Maximum Size of a Volume” on page 54.
<code>vxvoladm [-g diskgroup] \ {growby growto}\ volume length [<i>storage_specification</i>] \ [<i>attribute=value</i> ...]</code>	Grows a volume. See “Increasing the Size of a Volume to a Specified Length” on page 54 and “Increasing the Size of a Volume by a Specified Amount” on page 55.
<code>vxvoladm [-g diskgroup] \ {shrinkby shrinkto}\ volume length [<i>storage_specification</i>] \ [<i>attribute=value</i> ...]</code>	Shrinks a volume. See “Reducing the Size of a Volume to a Specified Length” on page 55 and “Reducing the Size of a Volume by a Specified Amount” on page 55.
<code>vxvoladm [-g diskgroup] evacuate \ disk volume length !dm:dmname ...</code>	Evacuates a volume from one or more specified disks. See “Evacuating a Volume” on page 57.



Creating and Administering Application Volumes

Command	Description
<code>vxvoladm [-g diskgroup] remove \ volume <i>volume</i></code>	Deletes a volume. See “Removing a Volume” on page 59.
<code>vxvoladm [-g diskgroup] verify \ volume</code>	Verifies the intent of a volume. See “Verifying the Intent of a Volume” on page 65.



Command Examples

This appendix lists examples of using the `vxvoladm` command that is provided by the VERITAS Intelligent Storage Provisioning (ISP) feature of VERITAS Volume Manager (VxVM).

- ◆ [Creating Volumes](#)
- ◆ [Resizing a Volume](#)
- ◆ [Adding or Removing Mirrors](#)
- ◆ [Adding or Removing Columns](#)
- ◆ [Adding or Removing Logs](#)
- ◆ [Evacuating Data from a Volume](#)

Further examples are given in [“Examples of Using ISP from the Command Line”](#) on page 27, and on the `vxvoladm(1M)` manual page.

Creating Volumes

Create a 10-gigabyte concatenated volume:

```
# vxvoladm -g exdg make vol1 10g
```

Create a 2-way mirrored volume using rules:

```
# vxvoladm -g exdg make vol1 10g rules='mirror 2'
```

Create a 7-column striped volume using rules:

```
# vxvoladm -g exdg make vol1 10g rules='stripe 7'
```

Create a 2-way mirrored volume using the `DataMirroring` capability:

```
# vxvoladm -g exdg make vol1 10g \  
  capability='DataMirroring(nmirs=2)'
```



Create a 2-way mirrored volume with each mirror on a separate enclosure:

```
# vxvoladm -g exdg make vol1 10g \  
  capability='DataMirroring(nmirs=2),\  
  MirrorsOnSeparateComponents(component="Enclosure")'
```

Create a 2-way mirror volume that is enabled for the creation of instant snapshots:

```
# vxvoladm -g exdg make vol1 10g \  
  capability='DataMirroring(nmirs=2), InstantSnapshottable'
```

Create a volume using only disks from enclosure e1:

```
# vxvoladm -g exdg make vol1 10g rules='confineto "Enclosure"="e1"'
```

or alternatively:

```
# vxvoladm -g exdg make vol1 10g \  
  capability='ConfineToSpecificStorage(name="Enclosure",\  
  value="e1")'
```

Create a volume using disks on the same controller:

```
# vxvoladm -g exdg make vol1 10g rules='confineto "Controller"'
```

or alternatively:

```
# vxvoladm -g exdg make vol1 10g \  
  capability='ConfineToSimilarStorage (name="Controller")'
```

Create a RAID-5 volume with a 2-way mirrored RAID-5 log and a 2-way mirrored DCO volume:

```
# vxvoladm -g exdg make vol1 10g capability='Raid5Capability,\  
  Raid5LogMirroring(nlogs=2), DCOLogMirroring(nlogs=2)'
```

Create a volume using a RAID-5 device that has been implemented in hardware (such as a RAID-5 LUN in an EMC Symmetrix array):

```
# vxvoladm -g exdg make vol1 10g capability='PrefabricatedRaid5'
```

Create a striped volume with a minimum of 10 columns using mirrored LUNs from enclosure e1, and for which instant snapshots can be taken:

```
# vxvoladm -g exdg make vol1 10g \  
  capability='PrefabricatedDataMirroring, Striping(ncols=10),\  
  InstantSnapshottable' rules='confineto "Enclosure"="e1"'
```

or alternatively:

```
# vxvoladm -g exdg make vol1 10g \  
  capability='PrefabricatedDataMirroring, Striping(ncols=10),\  
  InstantSnapshottable,\  
  ConfineToSpecificStorage (name="Enclosure",value="e1")'
```


Create a 4-way mirrored volume in which each mirror uses disks from the same enclosure, and for which instant snapshots can be taken:

```
# vxvoladm -g exdg make vol1 10g \  
  capability='DataMirroring(nmirrors=2),InstantSnapshottable,\  
  ConfineMirrorsToSimilarStorage(name="Enclosure")'
```

Resizing a Volume

Note The following examples show how to resize volumes that do not contain file systems (volume type `gen`). If an application is using the volume to store data, use the appropriate utility to reduce the size of the data object before reducing the size of the volume, or to increase the size of the data object after increasing the size of the volume.

For volumes that contain volumes (volume type `fsgen`), use the `vxresize` command to change both the size of the file system and the volume.

Grow a volume by 5 gigabytes:

```
# vxvoladm -g exdg growby vol1 5g
```

Grow an existing 10-gigabyte volume to 15 gigabytes without using disks from the enclosure `e1`:

```
# vxvoladm -g exdg growto vol1 15g \  
  use_storage='noneof("Enclosure"="e1")'
```

Shrink a volume by 10%:

```
# vxvoladm -g exdg growby vol1 10%
```

Shrink an existing 15-gigabyte volume to 10 gigabytes:

```
# vxvoladm -g exdg shrinkto vol1 10g
```

Adding or Removing Mirrors

Add a mirror to an existing volume:

```
# vxvoladm -g exdg add mirror vol1
```

Add two mirrors to a volume:

```
# vxvoladm -g exdg add mirror vol1 nmirror=2
```



Add a mirror to the volume `vol1`, where the new mirror is like the existing plex `p1`:

```
# vxvoladm -g exdg add mirror vol1 plexname=p1
```

Remove a mirror from a volume:

```
# vxvoladm -g exdg remove mirror vol1
```

Remove the plex `p1` from the volume `v1`:

```
# vxvoladm -g exdg remove mirror vol1 plexnames=p1
```

Adding or Removing Columns

Add a column to a volume, and grow the volume while doing this:

```
# vxvoladm -g exdg add column vol1 layout=grow
```

Add 4 columns to a volume, and grow the volume while doing this:

```
# vxvoladm -g exdg add column vol1 ncols=4 layout=grow
```

Add a column, but do not grow the volume:

```
# vxvoladm -g exdg add column vol1 layout=nogrow
```

Remove a column, and shrink the volume while doing this:

```
# vxvoladm -g exdg remove column vol1 layout=shrink
```

Remove a column, but do not shrink the volume:

```
# vxvoladm -g exdg remove column vol1 layout=noshrink
```

Adding or Removing Logs

Add a DCO log to a volume:

```
# vxvoladm -g exdg add log vol1 logtype=dco
```

Add a DCO log to volume `vol1`, and make the new log like the existing log `p1`:

```
# vxvoladm -g exdg add log vol1 lognames=p1 logtype=dco
```

Remove a RAID-5 log from a volume:

```
# vxvoladm -g exdg remove log vol1 logtype=raid5
```

Remove the RAID-5 log named `p1` from a volume:

```
# vxvoladm -g exdg remove log vol1 lognames=p1 logtype=raid5
```

Evacuating Data from a Volume

Evacuate subdisk `sd01` from the volume `vol1`:

```
# vxvoladm -g exdg evacuate subdisk vol1 sd=sd01
```

Evacuate subdisks `sd11` and `sd12` from volume `vol1`:

```
# vxvoladm -g exdg evacuate subdisk vol1 sd=sd11,sd12
```

Evacuate disks `disk01` and `disk01` from volume `vol1`:

```
# vxvoladm -g exdg evacuate disk vol1 \!disk01 \!disk02
```

Evacuate columns 4 and 7 of volume `vol1`:

```
# vxvoladm -g exdg evacuate column vol1 columnnames=4,7
```

Evacuate mirror `p1` of volume `vol1`:

```
# vxvoladm -g exdg evacuate mirror vol1 plexnames=p1
```

Evacuate columns 3 and 4 of mirror `p1` from volume `vol1`:

```
# vxvoladm -g exdg evacuate column vol1 columnnames=3,4 \  
plexnames=p1
```





Configuring ISP to Work with SAL

F

The SAN Access Layer (SAL) is a component of the VERITAS CommandCentral™ Storage product that provides information about storage, hosts, and connectivity between hosts, and storage, HBAs, volumes and file systems. You can configure ISP to understand and consume information that is provided by SAL. The storage attributes provided by SAL can then be used with ISP rules. This appendix describes how to configure ISP and the SAN Access Layer (SAL) so that they can work together.

Enabling ISP to work with SAL

To enable ISP to receive information from SAL:

1. To allow ISP to contact SAL, add the following line to the `/etc/default/vxassist` file:

```
salcontact=yes
```

If this attribute is set to no or is not present, ISP cannot contact SAL.

2. Define the SAL Primary Host and SAL Primary Port by adding `sal_primary` and `sal_primary_port` definitions to the `/etc/default/vxassist_sal_info` file, as shown in the following sample entries:

```
sal_primary=private.universe.com  
sal_primary_port=2802
```

This example enables ISP to communicate with the SAL primary `private.universe.com` on port number 2802.

If this information is not specified, the host running ISP is assumed to be the SAL primary, and the default port to be 2802.

3. To establish a communication channel successfully, ISP must authenticate itself with SAL using a user name and password. The user name is that of the account under which the VEA service is running, usually `root`. Use the `vxsalcmd` command to add this user account with SAL administrator privileges, and set an appropriate password for it. To allow ISP to have transparent access to SAL, also use the `vxsalcmd`



command to store the password on the local machine in encrypted form. See “[Configuring root as a SAL User](#)” on page 180 for details, and refer to the “Command and Configuration File Reference” appendix in the *SANPoint Control Administrator’s Guide* for more information on using the `vxsalcmd` command.

Note The `vxsalcmd` command is provided by SAL to manage SAL user accounts. It is not a VERITAS Volume Manager command.

4. Edit the `etc/default/vxassist` file, and add an entry to define the user name that ISP uses for authentication. In the following example, the root account is used:

```
sal_username=root
```

Configuring root as a SAL User

To add the `root` user on the remote host, `island.universe.com`, as a SAL user with SAL administrator privileges on the SAL primary, `private.universe.com`, perform these steps on the remote host as `root`:

1. Create a file, such as `/tmp/add_user`, that contains the following single line definition of the new SAL user:

```
user add root@island.veritas.com clydenw Admin
```

This defines `root` on the system `island.universe.com` as a SAL user with SAL administrator privileges, and with a password set to `clydenw`.

2. Use the following command to add the new SAL user on the SAL primary:

```
# vxsalcmd private.universe.com:2802 -u admin -f /tmp/add_user
```

You are prompted to enter the password for the SAL administrator, in this example named `admin`.

To view the new SAL user account, enter the following command:

```
# vxsalcmd private.universe.com:2802 -u admin user list
```

Again, you are prompted for the SAL administrator’s password.

3. To allow ISP to communicate transparently with SAL, a local copy of the encrypted account information for the SAL user must be set up. Create a file, such as `/tmp/maintain_user`, that contains the following single line definition of the SAL user’s password:

```
user rem clydenw
```

4. Use the following command to create the local SAL account file:

```
# vxsalcmd private.universe.com:2802 -f /tmp/maintain_user
```

To confirm that the password has been set up correctly, enter the following command:

```
# vxsalcmd private.universe.com:2802 user list
```

This command should now list all the configured users without prompting for the SAL administrator's password.

5. Remove the /tmp/add_user and /tmp/maintain_user files as these contain passwords in clear text.

Note If the SAL user's password is not stored locally, ISP attempts to authenticate with SAL as the user `admin` with the password `passwd`.

If ISP fails to authenticate with SAL, it can neither see nor use any CommandCentral Storage attributes.





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